# Topics in Equivariant Cohomology 

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## Abstract

The equivariant cohomology of a manifold $M$ acted upon by a compact Lie group $G$ is defined to be the singular cohomology groups of the topological space

$$
(M \times E G) / G
$$

It is well known that the equivariant cohomology of $M$ is parametrised by the Cartan model of equivariant differential forms. However, this model has no obvious geometric interpretation - partly because the expression above is not a manifold in general. Work in the 70s by Segal, Bott and Dupont indicated that this space can be constructed as the geometric realisation of a simplicial manifold that is naturally built out of $M$ and $G$. This simplicial manifold carries a complex of so-called simplicial differential forms which gives a much more natural geometric interpretation of differential forms on the topological space $(M \times E G) / G$.

This thesis provides a model for the equivariant cohomology of a manifold in terms of this complex of simplicial differential forms. Explicit chain maps are constructed, inducing isomorphisms on cohomology, between this complex of simplicial differential forms and the more standard models of equivariant cohomology, namely the Cartan and Weil models.

## Signed Statement

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## Chapter 1

## Introduction

For this chapter, let $G$ be a compact Lie group and $\mathfrak{g}$ its Lie algebra. The work of Chern and Weil in the 1940s to generalise the Gauss-Bonnet Theorem led to what is now know as the Chern-Weil homomorphism. Given a principal $G$-bundle $P \rightarrow B$, this is a canonical homomorphism

$$
\kappa_{G}: S\left(\mathfrak{g}^{*}\right)^{G} \rightarrow H^{*}(B)
$$

that is constructed from a connection on $P \rightarrow B$ but does not depend on that choice of connection. This classical result can also be interpreted in the language of classifying spaces. That is, there is a principal $G$-bundle, called the universal bundle and denoted

$$
\begin{equation*}
E G \rightarrow B G, \tag{1.1}
\end{equation*}
$$

for which the base space $B G$ classifies topological principal $G$-bundles. More specifically, the isomorphism class of principal $G$-bundles over a manifold $M$, is uniquely determined by a map into the classifying space $B G$

$$
f: M \rightarrow B G
$$

up to homotopy. Indeed, from this perspective the Chern-Weil homomorphism tells us that the cohomology of the classifying space is

$$
\begin{equation*}
H^{*}(B G) \cong S\left(\mathfrak{g}^{*}\right)^{G} \tag{1.2}
\end{equation*}
$$

Closely related to this is the subject of equivariant cohomology. The equivariant cohomology groups of a manifold $M$ with right $G$-action were first explicitly defined by Borel in [Bor60] to be the singular cohomology groups

$$
\begin{equation*}
H^{*}((M \times E G) / G) . \tag{1.3}
\end{equation*}
$$

It is well understood, through the work of Cartan in [Car50a] and [Car50b], that the cohomology of this space is parametrised by the complex of 'equivariant differential forms'

$$
\left(S\left(\mathfrak{g}^{*}\right) \otimes \Omega^{*}(M)\right)^{G}
$$

thought of as symmetric polynomials on the vector space $\mathfrak{g}$ taking values in the differential forms of $M$

$$
p: \mathfrak{g} \rightarrow \Omega^{*}(M)
$$

that are invariant under the action of $G$. Bott provides an excellent and more contemporary proof of this fact in his paper [Bot73]. These equivariant differential forms have no obvious geometric interpretation on the space

$$
(M \times E G) / G
$$

however, partly because it is not a manifold.
We see in the work of Segal in [Seg68], Bott in [Bot73], Bott-Shulman-Stasheff in [BSS76] and Dupont in [Dup75] that the classifying space and the associated bundle $(M \times E G) / G$ can be built out of a simplicial manifold and studied via simplicial methods. This simplicial manifold, which is naturally built out of the manifolds $M$ and $G$, carries a complex of simplicial differential forms, denoted $A^{*}(N G)$ and $A^{*}\left(N \bar{G} \bullet \times_{G} M\right)$ for the classifying space and associated bundle respectively.

More recently, Guillemin and Sternberg have concisely condensed a lot of the work on equivariant de Rham theory in their text [GS99]. In particular, they isolate conditions for a complex $W$ such that

$$
\begin{equation*}
\left(\Omega^{*}(M) \otimes W\right)_{b a s} \tag{1.4}
\end{equation*}
$$

is a model for the equivariant cohomology of $M$. In this construction, $W$ plays the role of the differential forms on $E G$ and the expression in (1.4) is effectively the correct algebraic approximation for 'differential forms' on the space $(M \times E G) / G$.

In the monograph [Dup78], Dupont uses the complex of simplicial differential forms $A^{*}(N G)$ to calculate the cohomology of the classifying space $B G$. The purpose of this thesis is to extend the work of Dupont to the case of studying the equivariant cohomology of a manifold using the simplicial principal bundle

$$
\begin{equation*}
N \bar{G}_{\bullet} \times M \rightarrow N \bar{G}_{\bullet} \times{ }_{G} M \tag{1.5}
\end{equation*}
$$

Namely, we will construct explicit chain maps from the Cartan model for equivariant cohomology and the Weil model for equivariant cohomology to the complex of simplicial differential forms that induce isomorphisms on cohomology. These results are best summarised by the main two theorems that are proven in Chapter 4.

Theorem 4.78: Let $G$ be a compact Lie group and $M$ be a manifold with right $G$-action and let $\alpha \otimes \omega \in\left(S\left(\mathfrak{g}^{*}\right) \otimes \Omega^{*}(M)\right)^{G}$. There is a chain map

$$
\Phi:\left(S\left(\mathfrak{g}^{*}\right) \otimes \Omega^{*}(M)\right)^{G} \rightarrow A^{*}\left(N \bar{G}_{\bullet} \times M\right)_{b a s}
$$

given explicitly by

$$
\Phi(\alpha \otimes \omega)=w\left(\theta_{\bullet}\right)(\alpha) \wedge \operatorname{Hor}\left(\omega_{\bullet}\right)
$$

that induces an isomorphism on cohomology.
Theorem 4.82: Let $G$ be a compact Lie group and $M$ be a manifold with right $G$-action and let $\alpha \otimes \omega \in\left(W(\mathfrak{g}) \otimes \Omega^{*}(M)\right)_{b a s}$. There is a chain map

$$
\Psi:\left(W(\mathfrak{g}) \otimes \Omega^{*}(M)\right)_{b a s} \rightarrow A^{*}\left(N \bar{G}_{\bullet} \times M\right)_{b a s}
$$

given explicitly by

$$
\Psi(\alpha \otimes \omega)=w\left(\theta_{\bullet}\right)(\alpha) \wedge \omega_{\bullet}
$$

that induces an isomorphism on cohomology.
In these two theorems, $w\left(\theta_{\bullet}\right)$ is the Weil homomorphism associated to a connection $\theta_{\bullet}$ on the simplicial principal bundle in Equation 1.5 and $\omega_{\bullet}$ is the natural 'simplicial version' of the differential form $\omega \in \Omega^{*}(M)$. When $M$ is a point, these maps are precisely the chain maps Dupont describes that induce the isomorphism on cohomology groups

$$
\begin{equation*}
\Phi=\Psi: S\left(\mathfrak{g}^{*}\right)^{G} \xrightarrow{\sim} H^{*}(B G) \tag{1.6}
\end{equation*}
$$

which is the classical isomorphism in Equation 1.2.
Chapter 2 is a piece of exposition on the classical theory of equivariant cohomology. Firstly, the reader is reminded about the topological definition of equivariant cohomology as first formulated by Borel in [Bor60]. Namely, if $X$ is a topological space on which a group $G$ acts, the equivariant cohomology of $X$ is defined to be

$$
\begin{equation*}
H^{*}((X \times E) / G) \tag{1.7}
\end{equation*}
$$

where $E$ is a contractible space on which $G$ acts freely. The legitimacy of this definition is then further explored so that it is clear that the definition of equivariant cohomology doesn't depend on the choice of $E$. In fact, this leads to the construction of the universal bundle

$$
E G \rightarrow B G
$$

which is a principal $G$-bundle. The differential geometry of smooth principal bundles will also play a role in later chapters. One of our goals will be to build the bundle $E G \rightarrow B G$ out of a simplicial manifold and another will be to describe the Chern-Weil homomorphism using this construction. As such, a discussion on the geometry of principal bundles naturally follows the discussion on the universal bundle. The last part of this chapter is used to describe the Weil algebra and develop some of the classical results from equivariant cohomology including a description of the Weil model, Cartan model and the Mathai-Quillen isomorphism from [MQ86]. These two models are both fundamental in this thesis and must be reasonably well understood
so that we can construct the explicit chain maps described in the main theorems above, Theorem 4.78 and Theorem 4.82.

The main purpose of Chapter 3 is to construct the universal bundle $E G \rightarrow B G$ using manifolds so that we may approximate a de Rham complex for the topological space

$$
(M \times E G) / G .
$$

The obstruction is that $E G$ is not a manifold in general so we instead define the complex of simplicial differential forms on the simplicial manifold

$$
N \overline{G_{\bullet}} \times_{G} M
$$

and show that by taking geometric realisation of this simplicial manifold one has

$$
\begin{equation*}
\left|N \bar{G}_{\bullet} \times_{G} M\right|=(E G \times M) / G . \tag{1.8}
\end{equation*}
$$

The first half of this chapter is dedicated to building the correct language for this construction and introducing some other important simplicial and cosimplicial objects along the way. Most importantly, the simplicial principal bundle

$$
N \bar{G}_{\bullet} \rightarrow N G_{\bullet}
$$

is defined and the last half of the chapter is reserved for checking that the respective map under geometric realisation

$$
\left|N \bar{G}_{\bullet}\right| \rightarrow\left|N G_{\bullet}\right|
$$

corresponds to the projection map of the universal bundle. As Segal remarks upon in [Seg68], the construction of the simplicial principal $G$-bundle in this way is closely related to the classical Milnor construction of the universal bundle (see [Mi156a] and [Mil56b]). The results naturally extend to showing that Equation 1.8 holds using results of May (see [May72]).

The final chapter of this thesis deals with constructing an approximation of differential forms on the topological space

$$
(E G \times M) / G
$$

by using the complex of basic simplicial differential forms $A^{*}(N \bar{G} \times M)_{\text {bas }}$. The complex of simplicial differential forms $A^{*}\left(M_{\bullet}\right)$ was first introduced by Whitney (see [Whi57, Chapter IX]) and used extensively by Dupont to study the Chern-Weil homomorphism in [Dup75] and [Dup78]. Using the fact that $N \bar{G}_{\bullet} \rightarrow N G_{\bullet}$ is a simplicial principal bundle, Dupont defines simplicial connection and curvature forms such that there is a natural Chern-Weil homomorphism. Moreover, we construct a chain map

$$
\Phi:\left(S\left(\mathfrak{g}^{*}\right) \otimes \Omega^{*}(M)\right)_{b a s} \rightarrow A^{*}\left(N \bar{G} \bullet_{\bullet} \times_{G} M\right)
$$

which arises naturally from the associated principal bundle

$$
N \bar{G}_{\bullet} \times M \rightarrow N \bar{G}_{\bullet} \times{ }_{G} M
$$

The complex of simplicial differential forms on a simplicial manifold $A^{*}\left(M_{\bullet}\right)$ is a computational powerhouse for the calculations performed in this chapter and we state some well known results to establish the sequence of isomorphisms on cohomology

$$
H^{*}\left(\left|M_{\bullet}\right|\right) \cong H^{*}\left(\left\|M_{\bullet}\right\|\right) \cong H_{\mathrm{Tot}}^{*}\left(C^{*, *}\left(M_{\bullet}\right)\right) \cong H_{\mathrm{Tot}}^{*}\left(\Omega^{*, *}\left(M_{\bullet}\right)\right) \cong H^{*}\left(A^{*}\left(M_{\bullet}\right)\right)
$$

using the technology of Segal, Dupont and Palais. It is then shown that the complex $A^{*}(N \bar{G} \bullet \times$ $M)_{b a s}$ is a natural model for the equivariant cohomology of a manifold $M$ with right $G$-action. Similar work has also been done by Bott, Shulman and Stasheff in [BSS76] but focused on the de Rham double complex associated to a simplicial manifold $\Omega^{*, *}\left(M_{\bullet}\right)$. The work of Guillemin and Sternberg in [GS99] establishes the classical results of Cartan (from [Car50a] and [Car50b]) for a more general $G^{*}$ algebra. It is shown that the complex $A^{*}\left(N \bar{G}_{\bullet} \times M\right)$ is a $G^{*}$ algebra and the complex

$$
\left(S\left(\mathfrak{g}^{*}\right) \otimes A^{*}\left(N \bar{G}_{\bullet} \times M\right)\right)^{G}
$$

computes the equivariant cohomology of a manifold $M$ acted upon by a compact Lie group $G$. This all culminates in the construction of a chain map

$$
\Phi:\left(S\left(\mathfrak{g}^{*}\right) \otimes \Omega^{*}(M)\right)^{G} \rightarrow A^{*}\left(N \overline{G_{\bullet}} \times_{G} M\right)
$$

from Theorem 4.78 which is proven to be an isomorphism on cohomology. Moreover, we see that there is an even more natural chain map

$$
\Psi:\left(W(\mathfrak{g}) \otimes \Omega^{*}(M)\right)_{\text {bas }} \rightarrow A^{*}\left(N \overline{G_{\bullet}} \times_{G} M\right)
$$

that induces an isomorphism on cohomology given by the much more obvious identification

$$
\alpha \otimes \omega \mapsto w\left(\theta_{\bullet}\right)(\alpha) \wedge \omega_{\bullet}
$$

as described above in Theorem 4.82. These chain maps establish alternate proofs of Cartan's theorems as well as describing a simple way to calculate these simplicial differential forms from the classical equivariant differential forms.

## Chapter 2

## Classical Equivariant Cohomology

### 2.1 Topological Equivariant Cohomology

### 2.1.1 Group Actions

Let $G$ be a topological group and $X$ be a topological space. We say that $G$ acts on the right of $X$, or $X$ has a right $G$-action, if there is a map

$$
\phi: X \times G \rightarrow X
$$

such that $\phi(x, 1)=x$ and $\phi(\phi(x, g), h)=\phi(x, g h)$ for every $x \in X, g, h \in G$. These conditions can be described by requiring that the following two diagrams commute

where $m$ is the group multiplication and $i_{1}: X \rightarrow X \times G$ is the map $x \mapsto(x, 1)$. The notation $\phi_{g}:=\phi(-, g)$ and $x \cdot g=\phi(x, g)$ is more natural in some circumstances and will be used interchangeably. For example, the conditions for $G$ to act on $X$ may be restated as $\phi_{1}=\mathrm{id}_{x}$ and $\phi_{h} \circ \phi_{g}=\phi_{g h}$ or $x \cdot 1=x$ and $(x \cdot g) \cdot h=x \cdot(g h)$.

Similarly, one may define a left $G$-action by instead imposing that $\phi_{h} \circ \phi_{g}=\phi_{h g}$ for every $g, h \in G$. For a left $G$-action we will adopt the notation $g \cdot x=\phi(x, g)$ for which we may restate this condition as $h \cdot(g \cdot x)=(h g) \cdot x$.

Once stated diagrammatically, the definition of a group action can be easily understood for other mathematical objects, $X$. For example, if $X$ is a smooth manifold, then the diagrams above make sense if $G$ is a Lie group and the action $\phi: X \times G \rightarrow X$ is a smooth map.

By letting $A u t(S)$ denote the group of automorphisms of a set $S$ - in this case, the bijections from $S$ to itself - we note that a group action is equivalent to a homomorphism from $G$ to Aut (S).

Proposition 2.1: Let $G$ be a group and $S$ be a set. Then a $G$-action on $S$ is equivalent to $a$ group homomorphism

$$
\psi: G \rightarrow \operatorname{Aut}(S)
$$

Proof. Let $S$ have a left $G$-action with corresponding automorphisms $\phi_{g}$ for each $g \in G$. Then define $\psi: G \rightarrow A u t(S)$ by

$$
\psi(g)=\phi_{g} .
$$

Note that $\psi\left(g^{-1}\right)=\phi_{g^{-1}}=\phi_{g}^{-1}$ since $\phi_{g} \circ \phi_{g^{-1}}$ is the identity map and $\psi(g h)=\phi_{g h}=\phi_{g} \circ \phi_{h}=$ $\psi(g) \psi(h)$ as required.

If $G$ acts on the right, the induced homomorphism is slightly different. Let $S$ have a right $G$-action with corresponding automorphisms $\varphi_{g}$ for each $g \in G$. Then define $\psi: G \rightarrow A u t(S)$ by

$$
\psi(g)=\varphi_{g^{-1}}
$$

In this case, $\psi\left(g^{-1}\right)=\varphi_{g}=\left(\varphi_{g^{-1}}\right)^{-1}$ and $\psi(g h)=\varphi_{(g h)^{-1}}=\varphi_{h^{-1} g^{-1}}=\varphi_{g^{-1}} \circ \varphi_{h^{-1}}=\psi(g) \psi(h)$. So if $S$ has a left or right $G$-action, it determines a homomorphism $\psi: G \rightarrow A u t(S)$.

Let $\psi: G \rightarrow \operatorname{Aut}(S)$ be a group homomorphism. It is clear that $\psi(1)=\mathrm{id}_{S}$ and that for any group elements $g, h, \psi(g h)=\psi(g) \psi(h)$. So the homomorphism $\psi$ naturally defines a left $G$ action on $S$.

For a right $G$-action, the orbit of a point $x \in X$ is the subspace of points

$$
x \cdot G:=\left\{\phi_{g}(x): g \in G\right\}
$$

and similarly, the orbit of a point under a left $G$-action is denoted $G \cdot x$. Similarly, the stabiliser group $G_{x}$ for a point $x \in X$ is the subgroup of $G$ that fixes $x$,

$$
G_{x}=\left\{g \in G: \phi_{g}(x)=x\right\}
$$

We call the action of $G$ on a space $X$ free if the stabiliser group is trivial at every point $x \in X$.
The product of two spaces that admit a $G$-action also carries a natural $G$-action. If $X, Y$ are topological spaces with a right $G$-action then we define the diagonal action of $g \in G$ on a point $(x, y) \in X \times Y$ to be

$$
(x, y) \cdot g=(x \cdot g, y \cdot g)
$$

Unless otherwise stated, it will be assumed that the product of two spaces with $G$-action is endowed with the diagonal action of $G$.

Proposition 2.2: Let $G$ be a topological group and $X, Y$ be topological spaces with a $G$-action. If $X$ has a free $G$-action, then the diagonal action of $G$ on $X \times Y$ is also free.

Proof. Let $(x, y) \in X \times Y$ and $g \in G$. Then the diagonal action $(x, y) \cdot g=(x \cdot g, y \cdot g)=(x, y)$ if and only if $x \cdot g=x$ and $y \cdot g=y$. Since $X$ has a free $G$-action, this is only true when $g$ is the identity and hence the diagonal action is also free.

One can consider the set of equivalence classes of orbits $X / G:=\{x \cdot G: x \in X\}$. The set of orbits is endowed with the coarsest topology such that the natural projection $X \xrightarrow{q} X / G$ is continuous and the resultant topological space is called the quotient space.

Definition 2.3: Let $X, Y$ be topological spaces with a right $G$-action. A map $f: X \rightarrow Y$ is said to be equivariant if

$$
f(x \cdot g)=f(x) \cdot g
$$

for every $x \in X$ and $g \in G$.
Remark 2.4: Note that an equivariant map defines a unique map $g: X / G \rightarrow Y / G$ such that the diagram below commutes.


Remark 2.5: Let $X$ be a topological space with right $G$-action. If $Y$ is any topological space, it can be endowed with a trivial $G$-action. An equivariant map $f: X \rightarrow Y$ is thus a map where

$$
f(x \cdot g)=f(x) \cdot g=f(x)
$$

for every $x \in X$. To avoid explicitly stating that $Y$ has been endowed with a trivial $G$-action, we will instead refer to maps $f: X \rightarrow Y$ such that $f(x \cdot g)=f(x)$ as a $G$-invariant maps.

### 2.1.2 The Borel Construction

When considering a topological group $G$ and a space $X$ with $G$-action, one might be tempted to study the cohomology of the quotient space $X / G$. Each point in the space $X / G$ corresponds to an orbit $x \cdot G$ which, so long as the action is free, is homeomorphic to $G$.

If the action is not free, then the orbit of a point $x \in X$ is homeomorphic to a different space, namely the quotient space $G / G_{x}$. In this case, two points in $X / G$ do not always give us the same topological information about the action of $G$. For this reason, we look for a different topological space to study - one that captures the group action on $X$ but also admits a free $G$ action. Proposition 2.2 shows that by first finding a topological space $Y$ on which $G$ acts freely, the space $X \times Y$ will admit a free action. In this case, a point in $(X \times Y) / G$ will correspond
to an orbit that is homeomorphic to $G$. So that $X \times Y$ is the same homotopy type as $X$, it is desirable that the space $Y$ is also contractible.

Showing that there exists a contractible space on which a group $G$ acts freely is a classical result but nonetheless, non-trivial. We will take it on faith that such a space exists in order to exploit its topological properties and return to proving this fact later in Section 3.2.

To motivate Section 2.1.3 we will state a precise definition, known as the Borel construction, and sketch a result which uses some terminology that has not been defined; namely the terms principal bundle, numerable principal bundle and fibre bundle (see Definitions 2.8, 2.22, 2.10 respectively).

Definition 2.6: Let $G$ be a topological group and $X$ be a topological space with right $G$-action. Then we define the equivariant cohomology of $X$ as

$$
H_{G}^{*}(X):=H^{*}((X \times E) / G)
$$

where $E$ is contractible and the total space of a numerable principal bundle.
From Borel [Bor60], we also have the following theorem showing that the equivariant cohomology of a topological space on which $G$ acts freely is the singular cohomology of the orbit space $X / G$.

Theorem 2.7: Let $G$ be a group and $X$ be a space with free right $G$-action. Then

$$
H_{G}^{*}(X)=H^{*}(X / G) .
$$

Sketch proof. The equivariant projection $X \times E \rightarrow X$ induces a projection

$$
(X \times E) / G \rightarrow X / G
$$

which is a fibre bundle with fibre $E$. In this situation, standard results from algebraic topology show the existence of a long exact sequence of homotopy groups

$$
\cdots \rightarrow \pi_{i}(E) \rightarrow \pi_{i}((X \times E) / G) \rightarrow \pi_{i}(X / G) \rightarrow \pi_{i-1}(E) \rightarrow \cdots
$$

for $i>0$. Since $E$ is a contractible space, $\pi_{i}(E)=\{0\}$ for every $i>0$ and thus $\pi_{i}((X \times E) / G) \cong$ $\pi_{i}(X / G)$ for every $i \geq 0$. (The case for $i=0$ follows from the fact that $X \times E$ and $X$ have the same number of connected components since $E$ is contractible.) Since there is a weak homotopy equivalence between $(X \times E) / G$ and $X / G$ it follows that

$$
H_{G}^{*}(X)=H^{*}((X \times E) / G)=H^{*}(X / G)
$$

### 2.1.3 Principal Bundles and the Classifying Space

The following section will develop the theory of principal bundles as well as justify some of the statements from Section 2.1.2.

Definition 2.8: Let $G$ be a Lie group, $M$ be a manifold and $P$ be a manifold with right $G$ action. Then a (smooth) principal $G$-bundle is a triple $(P, \pi, M)$, or $P \xrightarrow{\pi} M$, where the map $\pi: P \rightarrow M$ is smooth, surjective and meets the following conditions.

1. For every $x \in M, \pi^{-1}(x)$ is an orbit.
2. Every point $x \in M$ has an open neighbourhood $U$ and a smooth equivariant diffeomorphism $\varphi: \pi^{-1}(U) \rightarrow U \times G$ such that the diagram

commutes, where $p_{U}$ is projection onto $U$. The pair $(U, \varphi)$ is called a local trivialisation.
Remark 2.9: The most simple example of a principal $G$-bundle is the trivial bundle $M \times G \xrightarrow{\pi}$ $M$ where $\pi$ is projection onto $M$.

A topological principal $G$-bundle is the topological analogue, by letting $G$ be a topological group, $P, M$ topological spaces and

$$
\pi: P \rightarrow M
$$

a surjective map such that the local trivialisations are homeomorphisms. Smooth principal Gbundles will primarily be the examples of study and so the term 'principal $G$-bundle' will mostly denote a smooth principal $G$-bundle. In either case, we say that $M$ is the base space, $P$ is the total space, $\pi$ is the projection and $G$ is the structure group of the principal $G$-bundle. More generally, there is the notion of a fibre bundle.

Definition 2.10: Let $F, P, X$ be topological spaces. Then a fibre bundle is a quadruple $(F, P, \pi, X)$ where the map $\pi: P \rightarrow X$ is surjective and meets the following conditions.

1. For every $x \in X, \pi^{-1}(x)$ is homeomorphic to $F$.
2. Every point $x \in X$ has an open neighbourhood $U$ and a homeomorphism $\varphi: \pi^{-1}(U) \rightarrow U \times F$ such that the diagram

commutes, where $p_{U}$ is projection onto $U$. The pair $(U, \varphi)$ is called a local trivialisation.
Similarly, when the spaces $F, P, X$ are smooth manifolds, the projection map $\pi$ is smooth, and all local trivialisations are smooth diffeomorphisms, we call this construction a smooth fibre bundle. Fibre bundles will not be extensively studied in this thesis and will mainly be talked about in the context of what is normally called the associated fibre bundle.

Proposition 2.11: Let $P \xrightarrow{\pi} M$ be a principal $G$-bundles and $N$ a topological space with right $G$-action. Then the map $\tau:(P \times N) / G \rightarrow M$ defined by

$$
[p, n] \mapsto \pi(p)
$$

is a fibre bundle with fibre $N$. We call this the associated fibre bundle.
Proof. First, consider the following commutative diagram

where $p_{1}$ is the projection onto $P$ and $\rho$ is the quotient by the action of $G$. A local trivialisation of the principal bundle $P \rightarrow M$, say $(U, \varphi)$, yields a homeomorphism

$$
\left(\pi \circ p_{1}\right)^{-1}(U) \xrightarrow{\sim} U \times G \times N .
$$

Thus,

$$
\tau^{-1}(U)=\rho \circ\left(\pi \circ p_{1}\right)^{-1}(U) \cong U \times N
$$

defines local trivialisations $(U, \psi)$ of $\tau:(P \times N) / G \rightarrow M$.
Let $P \xrightarrow{\pi} M, Q \xrightarrow{\tau} N$ be topological principal $G$-bundles. The natural definition of a morphism between principal $G$-bundles would be a pair of maps $(f, \tilde{f})$ such that the diagram

commutes. Since the quotient $P / G$ is isomorphic to the base space $M$, an equivariant map $f: P \rightarrow Q$ induces a unique map $\tilde{f}: M \rightarrow N$ by Remark 2.4. Since $\tilde{f}$ is uniquely determined by $f$, a map of principal $G$-bundles (or bundle map) can thus be defined as an equivariant map between total spaces $f: P \rightarrow Q$. We say that $f$ is an isomorphism if there exists a bundle map $g: Q \rightarrow P$ such that $g \circ f$ and $f \circ g$ are the respective identity maps on $P$ and $Q$. A principal bundle is trivial if it is isomorphic to the trivial bundle.

Proposition 2.12: Let $P \xrightarrow{\pi} M, Q \xrightarrow{\tau} M$ be smooth principal $G$-bundles. Let $f: P \rightarrow Q$ be a bundle map such that the induced map on base spaces

$$
\tilde{f}: M \rightarrow M
$$

is the identity. Then $f$ is an isomorphism.
Proof. Let $U \subset M$ be a local trivialisation of $x \in M$. From the definition of a principal bundle, there are diagrams

that commute. The problem reduces to showing that when $f$ is restricted to $\pi^{-1}(U), \varphi_{Q} \circ f \circ \varphi_{P}^{-1}$ is an isomorphism for all local trivialisations $U$. For ease of notation, this map will be denoted

$$
f_{\varphi}=\varphi_{Q} \circ f \circ \varphi_{P}^{-1}
$$

and the rest of the proof will amount to showing that $f_{\varphi}$ is an isomorphism. Since $f$ induces the identity on base spaces, $f_{\varphi}$ is an equivariant map such that

$$
f_{\varphi}(u, g)=(u, g \sigma(u))
$$

for every $u \in U$ and some smooth map $\sigma: U \rightarrow G$. It is easy enough to construct an inverse of $f_{\varphi}$ by letting

$$
f_{\varphi}^{-1}(u, g)=\left(u, g \sigma(u)^{-1}\right)
$$

completing the proof.

Corollary 2.13: Let $P \xrightarrow{\pi} X$ be a principal $G$-bundle. Then $P \cong X \times G$ if and only if $P \xrightarrow{\pi} X$ admits a global section.

Proof. Suppose $P \xrightarrow{\pi} X$ admits a global section, $s: X \rightarrow P$. Consider the map $F: X \times G \rightarrow P$

$$
F(x, g)=s(p) \cdot g
$$

$F$ is a bundle map that induces the identity on base spaces, hence an isomorphism. Conversely, a global section $s: X \rightarrow X \times G$ can easily be constructed via $s(x)=(x, 1)$.

Corollary 2.14: Let $P \xrightarrow{\pi} X$ be a principal $G$-bundle with local trivialisations $\left\{\left(U_{i}, \varphi_{i}\right)\right\}_{i \in I}$. Then there are local sections of the principal bundle

$$
s_{i}: U_{i} \rightarrow \pi^{-1}\left(U_{i}\right) .
$$

Proof. Each local trivialisation defines a trivial principal bundle

$$
\pi^{-1}\left(U_{i}\right) \xrightarrow{\pi} U_{i}
$$

and the result clearly follows.
Let $P \xrightarrow{\pi} B$ be a principal $G$-bundle and $X$ be a topological space. For every map

$$
f: X \rightarrow B
$$

there is a space $f^{*}(P):=\{(x, p): f(x)=\pi(p)\} \subset X \times P$ with natural projections onto each factor that cause the diagram

to commute. This carries a right $G$-action

$$
\phi((x, p), g)=(x, p \cdot g)
$$

whence we note that for every $x \in X, p_{X}^{-1}(x)$ is clearly an orbit of $f^{*}(P)$. Furthermore, the $\operatorname{map} f: X \rightarrow B$ induces a principal $G$-bundle structure on $f^{*}(P) \rightarrow X$ since a local section of $P \rightarrow B$, say $s: U \rightarrow \pi^{-1}(U)$, defines a local section of $f^{*}(P) \rightarrow X, \tilde{s}: f^{-1}(U) \rightarrow\left(f \circ p_{X}\right)^{-1}(U)$ by

$$
\tilde{s}(x)=(x, f \circ s(x))
$$

which in turn defines local trivialisations by Corollary 2.14. Thus we have proved the following proposition.

Proposition 2.15: Let $P \xrightarrow{\pi} B$ be a principal $G$-bundle, $X$ be a topological space and $f: B \rightarrow$ $X$ a map. Then the canonical map

$$
f^{*}(P) \rightarrow X
$$

is the projection map in a principal $G$-bundle for the action of $G$ given above. The bundle $f^{*}(P) \rightarrow X$ is called the pullback bundle of $P \xrightarrow{\pi} B$ along $f$.

Remark 2.16: If $f$ is a smooth map then the pullback bundle is a smooth principal $G$-bundle.
Proposition 2.17: Let $P \xrightarrow{\pi} M$ be a principal $G$-bundle and $F$ a topological space with right $G$-action. To every equivariant map $f: P \rightarrow F$ we may associate a section $s$ of the natural projection

$$
(P \times F) / G \rightarrow M
$$

Moreover, this correspondence between equivariant maps $f: P \rightarrow F$ and sections $s: M \rightarrow(P \times F) / G$ is a bijection.

Proof. Let $f: P \rightarrow F$ be an equivariant map. Clearly this can be extended to an equivariant $\operatorname{map} f^{\prime}: P \rightarrow P \times F$ by

$$
f^{\prime}(p)=(p, f(p))
$$

where $G$ acts diagonally on $P \times F$. Then this defines a map on quotient spaces $\tilde{f}: P / G \rightarrow$ $(P \times F) / G$ given by

$$
\tilde{f}[p]=[p, f(p)]
$$

But $P / G \cong M$ so the map $\tilde{f}: M \rightarrow(P \times F) / G$ given by

$$
\tilde{f}(m)=[p, f(p)]
$$

for some $p \in \pi^{-1}(m)$ is well defined. Suppose $f^{\prime}: P \rightarrow F$ is equivariant and $\tilde{f}^{\prime}=\tilde{f}$. That is, for every $p \in P$

$$
(p, f(p))=\left(p \cdot g, f^{\prime}(p) \cdot g\right)
$$

for some $g \in G$. Since $G$ acts freely on $P, g$ is necessarily the identity and thus $f^{\prime}=f$. Alternatively, suppose there is a section $s: M \rightarrow(P \times F) / G$. The section induces a pullback bundle

where the map $\tilde{s}: s^{*}(P \times F) \rightarrow P \times F$ is the induced projection of the pullback bundle which is naturally equivariant. Further, $s^{*}(P \times F) \subset M \times P \times F$ and there is a bundle map $f: s^{*}(P \times F) \rightarrow P$ given by

$$
f(m, p, x)=p
$$

which induces the identity over $M$ and hence is an isomorphism by Proposition 2.12. Letting $p_{2}: P \times F \rightarrow F$ denote the equivariant projection onto $F$, a section $s: M \rightarrow(P \times F) / G$ thus induces an equivariant map $f_{s}=p_{2} \circ \tilde{s} \circ f^{-1}: P \rightarrow F$.

The correspondence in Proposition 2.17 is also a correspondence on particular homotopy classes. Accordingly, the notion of homotopy classes for sections of bundles and equivariant homotopy are defined below.

Definition 2.18: Let $G$ be a topological group, $P \rightarrow M$ be a topological principal $G$-bundle and $F$ a topological space with right $G$-action. Let $f_{0}, f_{1}: P \rightarrow F$ be equivariant maps. We say $f_{0}$ is equivariantly homotopic to $f_{1}$ if there is a homotopy $h: P \times I \rightarrow F$ such that $h(p, 0)=f_{0}(p)$, $h(p, 1)=f_{1}(p)$ and

$$
h(p \cdot g, t)=h(p, t) \cdot g
$$

for every $p \in P, g \in G$ and $t \in I$.
Definition 2.19: Let $P \xrightarrow{\pi} M$ and $Q \xrightarrow{\tau} M$ be continuous maps. Let $s_{0}, s_{1}: Q \rightarrow P$ be fibrewise maps (or maps over $M$ ). That is, $\pi s_{0}=\pi s_{1}$. We say $s_{0}$ is fibrewise homotopic (or homotopic over $M$ ) to $s_{1}$ if there is a homotopy $h: M \times I \rightarrow P$ such that

$$
\pi h(m, t)=m
$$

for every $m \in M$ and $t \in I$. That is, the diagram

commutes where all maps are over $M$.
Proposition 2.20: The correspondence above is a bijection on homotopy classes. That is, $f_{0}, f_{1}: P \rightarrow F$ are equivariantly homotopic if and only if the corresponding sections $\tilde{f}_{0}, \tilde{f}_{1}$ are fibrewise homotopic.

Proof. Let $\tilde{f}_{0}, \tilde{f}_{1}$ be sections and $f_{0}, f_{1}$ the corresponding equivariant maps by Proposition 2.17. Suppose $\tilde{f}_{0}, \tilde{f}_{1}$ are fibrewise homotopic with homotopy $\tilde{h}: M \times I \rightarrow(P \times F) / G$. This can be extended to a section of the projection

$$
\begin{equation*}
((P \times I) \times F) / G \rightarrow M \times I \tag{2.21}
\end{equation*}
$$

since $G$ acts trivially on $I$ in this case. This can best be seen by considering the pullback diagram

where $p_{M}$ is the obvious projection and $\tau$ is the projection

$$
\tau[p, x]=\pi(p)
$$

for $p \in P, x \in F$. The space $(M \times I) \times{ }_{M}(P \times F) / G$ is naturally homeomorphic to $((P \times I) \times F) / G$ by considering

$$
(m, t,[p, x]) \mapsto[(p, t), x] .
$$

Since $i(m, t)=\tau[(p, t)]$ precisely when $p \in \pi^{-1}(m)$, this map has a continuous inverse

$$
[(p, t), x] \mapsto(\pi(p), t,[p, x]) .
$$

Thus, the maps $\tilde{h}$, id induce a map $\tilde{s}$

which is clearly the section alluded to in (2.21). This section corresponds to an equivariant map

$$
s: P \times I \rightarrow F .
$$

Since $\tilde{h}(-, 0)=\tilde{f}_{0}$ and $\tilde{h}(-, 1)=\tilde{f}_{1}$, it follows that $s(-, 0)=f_{0}$ and $s(-, 1)=f_{1}$. Thus $s$ is precisely an equivariant homotopy between the maps $f_{0}, f_{1}$.

Alternatively, an equivariant homotopy $s: P \times I \rightarrow F$ between the maps $f_{0}, f_{1}$ defines a section

$$
\tilde{s}: M \times I \rightarrow((P \times I) \times F) / G .
$$

Composing with the projection $((P \times I) \times F) / G \rightarrow(P \times F) / G$, we see that this is precisely a fibrewise homotopy between the sections $\tilde{f}_{0}, \tilde{f}_{1}$.

In [Dol63], Dold defines a class of bundles called numerable bundles and shows that a certain class of numerable fibre bundles possess global sections. In particular we have the following definition and theorem.

Definition 2.22: An open covering $\left\{U_{i}\right\}_{i \in J}$ of a topological space $B$ is numerable provided there exists a locally finite partition of unity $\left\{u_{i}\right\}_{i \in J}$ such that the closure

$$
\overline{\overline{u_{i}^{-1}}((0,1])} \subset U_{i}
$$

for each $i \in J$. A fibre bundle $P \xrightarrow{\pi} B$ is a numerable bundle if there is a numerable covering $\left\{U_{i}\right\}_{i \in J}$ of $B$ such that each $U_{i}$ admits a local trivialisation.

Theorem 2.23: Let $P \rightarrow M$ be a principal $G$-bundle with numerable base $M$, and $E$ a contractible space with free $G$-action. Then there is a section of the associated fibre bundle

$$
(P \times E) / G \xrightarrow{\tau} M .
$$

Moreover, any two sections of $(P \times E) / G \xrightarrow{\tau} M$ are fibrewise homotopic.
This is a corollary of Dold's result that a numerable bundle with contractible fibre admits a global section (see [Dol63, Cor $2.8 \alpha$ ]). As Husemoller remarks in [Hus66, p. 48-49], every principal $G$-bundle over a paracompact space is numerable. For example, we have the following inclusions.

$$
\left\{\begin{array}{c}
\text { Topological principal } \\
G \text {-bundles }
\end{array}\right\} \supset\left\{\begin{array}{c}
\text { Numerable principal } \\
G \text {-bundles }
\end{array}\right\} \supset\left\{\begin{array}{c}
\text { Topological principal } \\
G \text {-bundles with } \\
\text { paracompact base }
\end{array}\right\} \supset\left\{\begin{array}{c}
\text { Topological principal } \\
G \text {-bundles with base a } \\
\text { CW-complex }
\end{array}\right\} \supset\left\{\begin{array}{c}
\text { Smooth principal } \\
G \text {-bundles }
\end{array}\right\}
$$

Proofs of the following two lemmas can be found in [Hus66, p. 48-51] and will help us prove the classification theorem that follows.

Lemma 2.24: Let $P \rightarrow M$ be a numerable bundle and $f: N \rightarrow M$ a map of topological spaces. Then the pullback bundle

$$
f^{*}(P) \rightarrow N
$$

is a numerable bundle.
Lemma 2.25: Let $P \xrightarrow{\pi} B$ be a numerable principal $G$-bundle and $f, g: X \rightarrow B$ be two homotopic maps. Then there is an isomorphism of pullback bundles

$$
f^{*}(P) \cong g^{*}(P)
$$

Theorem 2.26: Let $P \xrightarrow{\pi} M$ be a numerable principal $G$-bundle. Let $E \rightarrow B$ be a numerable principal G-bundle with contractible total space. Then there exists a map $f: M \rightarrow B$ such that there is an isomorphism of principal bundles

$$
P \rightarrow f^{*}(E)
$$

Moreover, the isomorphism class of bundles containing $P$ determines a unique $f$ up to homotopy.
Proof. It is clear that a map $f_{0}: M \rightarrow B$ defines a numerable principal $G$-bundle $f_{0}^{*}(E) \rightarrow M$ by Proposition 2.15 and Lemma 2.24. Moreover, if $f_{1}: M \rightarrow B$ is homotopic to $f_{0}$ then there is an isomorphism

$$
f_{0}^{*}(E) \cong f_{1}^{*}(E)
$$

by Lemma 2.25. On the other hand, let $P \xrightarrow{\pi} M$ be a numerable principal $G$-bundle. By Theorem 2.23 there is a section $s$ of the associated fibre bundle

$$
(P \times E) / G \rightarrow M
$$

By Proposition 2.17 there is a corresponding equivariant map $g_{s}: P \rightarrow E$ which induces a map $g: M \rightarrow B$ on base spaces. There is a corresponding bundle map $P \rightarrow f^{*}(E)$ given by

$$
p \mapsto\left(\pi(p), g_{s}(p)\right)
$$

which induces the identity over $M$ and is hence an isomorphism. By Proposition 2.20 this homotopy class of $g$ is uniquely determined by $s$ up to fibrewise homotopy. By Theorem 2.23 any two sections of the bundle are fibrewise homotopic and thus determine a unique $g$ up to homotopy.

Remark 2.27: Let $E \rightarrow B$ be a numerable principal bundle with $E$ contractible. Theorem 2.26 classifies numerable principal $G$-bundles and henceforth we will refer to a map $f: X \rightarrow B$ as a classifying map.

Corollary 2.28: Let $E_{1} \rightarrow B_{1}$ and $E_{2} \rightarrow B_{2}$ be numerable principal bundles with contractible total space. Then there is a G-homotopy equivalence $E_{1} \simeq E_{2}$ and a homotopy equivalence $B_{1} \simeq B_{2}$. Moreover, the definition of equivariant cohomology in Definition 2.6 does not depend on a choice of $E \rightarrow B$.

Proof. Let $E_{1} \rightarrow B_{1}, E_{2} \rightarrow B_{2}$ be two numerable principal $G$-bundles with contractible total space. From Theorem 2.26 there is an isomorphism $F: E_{1} \rightarrow E_{2}$ and classifying maps $f: B_{1} \rightarrow$ $B_{2}$ such that

$$
E_{1} \cong f^{*}\left(E_{2}\right)
$$

Moreover, the converse is true. That is, there is an isomorphism $H: E_{2} \rightarrow E_{1}$ and classifying maps $h: B_{2} \rightarrow B_{1}$ such that

$$
E_{2} \cong h^{*}\left(E_{1}\right)
$$

So we can write $E_{2}=(f \circ h)^{*}\left(E_{2}\right)$ with isomorphism $F \circ H:(f \circ g)^{*}\left(E_{2}\right) \rightarrow E_{2}$ and classifying map $f \circ h: B_{2} \rightarrow B_{2}$. By Theorem 2.26, it must be the case that there is a homotopy $f \circ h \simeq \operatorname{id}_{B_{2}}$ and a $G$-equivariant homotopy $F \circ H \simeq \mathrm{id}_{E_{2}}$. Similarly one shows that there is a homotopy $h \circ f \simeq \operatorname{id}_{B_{1}}$ and a $G$-equivariant homotopy $H \circ F \simeq \operatorname{id}_{E_{1}}$. Hence, given any topological space $X$ with right $G$ action, there is a $G$-homotopy equivalence

$$
X \times E_{1} \simeq X \times E_{2}
$$

which descends to a homotopy equivalence

$$
\left(X \times E_{1}\right) / G \simeq\left(X \times E_{2}\right) / G .
$$

Clearly it follows that the definition of equivariant cohomology does not depend on the choice of $E$.

Definition 2.29: The universal bundle is any fixed numerable principal bundle with contractible total space. We will use EG to denote the total space of the universal bundle and $B G$ to denote the base space of the universal bundle.

### 2.2 The Geometry of Principal Bundles

### 2.2.1 The Action of a Lie Algebra

Let $G$ be a Lie group with Lie algebra $\mathfrak{g}$ and $M$, a manifold with right $G$-action $\phi: M \times G \rightarrow M$. The de Rham complex $\Omega^{*}(M)$ inherits a natural right $G$-action from the action on $M$ via $\phi$. Explicitly, the induced action $\phi_{\Omega}: \Omega^{*}(M) \times G \rightarrow \Omega^{*}(M)$ for $\omega \in \Omega^{n}(M)$ can be written

$$
\phi_{\Omega}(\omega, g):=\phi_{g}^{*} \omega,
$$

however we will usually take the shorthand $\omega \cdot g$. A differential form is $G$-invariant if $\omega \cdot g=\omega$ for every $g \in G$.

The Lie algebra of $G$ carries information about the infinitesimal action of $G$ on $M$. In particular, there is a natural vector field associated to each Lie algebra element $\xi \in \mathfrak{g}$. The curve $\gamma_{x}:[-1,1] \rightarrow M$ through a point $x \in M$ given by

$$
\gamma_{x}(t)=\phi(x, \exp (t \xi))
$$

defines a tangent vector in $T_{x} M$ by calculating its derivative at zero. Using the notation $\mathfrak{X}(M)$ to denote smooth vector fields on $M$ we see that since the functions $\phi$ and exp are smooth, the vector field $X_{\xi}: M \rightarrow T M$ defined by

$$
X_{\xi}(x)=\left.\frac{d}{d t} \gamma_{x}(t)\right|_{t=0}
$$

is well defined and smooth for each $\xi \in \mathfrak{g}$. If the vector field $X_{\xi}$ does not vanish, we say the action of $G$ is locally free. Defining a basis $\left\{\xi_{1}, \ldots, \xi_{n}\right\}$ of $\mathfrak{g}$ in turn defines a corresponding basis $\left\{X_{\xi_{1}}, \ldots, X_{\xi_{n}}\right\}$ of vector fields generated by the infinitesimal action of $\mathfrak{g}$. The Lie bracket on $\mathfrak{g}$ defines associated structure constants $c_{i j}^{k} \in \mathbb{R}$ relative to the chosen basis where

$$
\left[\xi_{i}, \xi_{j}\right]=c_{i j}^{k} \xi_{k}
$$

and Einstein summation convention is observed. The vector fields generated by the infinitesimal action share a similar structure to the Lie algebra in that

$$
\left[X_{\xi_{i}}, X_{\xi_{j}}\right]=c_{i j}^{k} X_{\xi_{k}}=X_{\left[\xi_{i}, \xi_{j}\right]} .
$$

These vector fields are fundamental in the study of equivariant cohomology and possess many properties that allow an analogue of de Rham's theorem to emerge. Perhaps the most natural action that a vector field $X_{\xi} \in \mathfrak{X}(M)$ has on a differential form is via the interior product, $\iota_{\xi}: \Omega^{n}(M) \rightarrow \Omega^{n-1}(M)$, given by

$$
\begin{equation*}
\iota_{\xi} \omega\left(X_{1}, \ldots, X_{n-1}\right)=\omega\left(X_{\xi}, X_{1}, \ldots, X_{n-1}\right), \tag{2.30}
\end{equation*}
$$

for $X_{1}, \ldots, X_{n}$ smooth vector fields on $M$. Note that this notation is a contraction of the more standard $\iota_{X_{\xi}}$ which will be avoided for simplicity. One checks that

$$
\iota_{\xi}(\omega \wedge \mu)=\left(\iota_{\xi} \omega\right) \wedge \mu+(-1)^{n} \omega \wedge\left(\iota_{\xi} \mu\right)
$$

to verify that this is a graded derivation of degree -1 . An element of the Lie algebra also determines a one-parameter subgroup of $G$ which naturally acts on differential forms via

$$
t \mapsto \omega \cdot \exp (t \xi)
$$

Taking the derivative at $t=0$ of this map is precisely the Lie derivative of $\omega$ with respect to the vector field $X_{\xi}$, which shall be denoted $\mathcal{L}_{\xi}$. The Lie derivative observes the identity

$$
\begin{equation*}
\mathcal{L}_{\xi}=d \iota_{\xi}+\iota_{\xi} d \tag{2.31}
\end{equation*}
$$

which is known as 'Cartan's magic formula' and is attributed to Élie Cartan (and occasionally Henri Cartan), a proof of which can be found in [CCL99]. This identity immediately implies that $\mathcal{L}_{\xi}$ is a derivation of degree 0 and commutes with $d$. Since differential forms are linear in their first term, the sets spanned by these derivations are vector spaces with respective bases $\left\{\iota \xi_{1}, \ldots, \iota_{\xi_{n}}\right\}$ and $\left\{\mathcal{L}_{\xi_{1}}, \ldots, \mathcal{L}_{\xi_{n}}\right\}$ corresponding to the basis of $\mathfrak{g}$.

### 2.2.2 Connections and Curvature

Let $P \xrightarrow{\pi} B$ be a principal $G$-bundle. The action of $G$ on the total space is free and thus vector fields generated by the infinitesimal action of $\mathfrak{g}$ do not vanish. To each vector field $X_{\xi_{i}}$ there
exists a 1-form $\theta^{i} \in \Omega^{*}(P)$ that is in some sense 'dual' in that

$$
\theta^{i}\left(p ; X_{\xi_{j}}\right)=\delta_{i j}= \begin{cases}1 & \text { if } i=j \\ 0 & \text { if } i \neq j\end{cases}
$$

for each $p \in P$. If the collection of these forms $\left\{\theta^{i}\right\}$ span a $G$-invariant subspace of $\Omega^{1}(P)$, this is precisely the definition of 'connection forms' on the total space $P$ in [GS99]. A differential 1 -form that takes values in $\mathfrak{g}$ defined by

$$
\theta=\theta^{i} \otimes \xi_{i} \in \Omega^{1}(P) \otimes \mathfrak{g}
$$

(and where Einstein summation convention is observed) is an example of the more standard definition of a connection form. One can check that for any $\xi \in \mathfrak{g}$ and every $p \in P$,

$$
\theta\left(p ; X_{\xi}\right)=\xi .
$$

This differential form identifies tangent vectors generated by the Lie algebra and a 'complement' defined by

$$
\left\{u \in T_{p} P: \theta(p ; u)=0\right\}
$$

in a smooth (but not necessarily unique) way. This differential form can also be realised in a more classical way via parallel transport, as seen in Dupont [Dup78, Ch. 3], which motivates the following discussion. At a point $p \in P$ there is a map $v_{p}: \mathfrak{g} \rightarrow T_{p} P$ given by

$$
v_{p}(\xi)=X_{\xi}(p)
$$

corresponding to the derivative of the map $g \mapsto p \cdot g$ as seen in the definition of $X_{\xi}$. Note that this map is injective since the action of $G$ is free. The projection $\pi: P \rightarrow B$ is $G$-invariant and so results in the following short exact sequence

$$
0 \rightarrow \mathfrak{g} \xrightarrow{v_{p}} T_{p} P \xrightarrow{\pi_{*}} T_{\pi(p)} B \rightarrow 0
$$

where $\pi_{*}: T P \rightarrow T B$ is the derivative of $\pi$. At each point $p \in P$ the differential form $\theta$ defines a linear map

$$
\theta_{p}:=\theta(p ;-): T_{p} P \rightarrow \mathfrak{g}
$$

such that $\theta_{p} \circ v_{p}=\operatorname{id}_{\mathfrak{g}}$. Thus, the connection $\theta$ splits the exact sequence at every point and allows us to define the following.
Definition 2.32: Let $P \xrightarrow{\pi} B$ be a principal $G$-bundle, $\theta \in \Omega^{1}(P) \otimes \mathfrak{g}$ a connection on $P$ and $u \in T_{p} P$ for some $p \in P$. We say $u$ is vertical if $u \in \operatorname{ker}\left(\pi_{*}\right)$ and horizontal if $u \in \operatorname{ker}\left(\theta_{p}\right)$. Likewise, a vector field $X$ is called vertical if all vectors $X(p)$ are vertical and horizontal if all vectors $X(p)$ are horizontal. Denote the collection of all vertical vectors at a point $p \in P$ as $\mathcal{V}_{p}$ and the collection of all vertical vectors at a point $p \in P$ as $\mathcal{H}_{p}$.

Remark 2.33: The short exact sequence

$$
0 \rightarrow \mathfrak{g} \xrightarrow{v_{p}} T_{p} P \xrightarrow{\pi_{*}} T_{\pi(p)} B \rightarrow 0
$$

means that a vertical vector can equivalently be defined as a tangent vector $u \in T_{p} P$ such that $u \in \operatorname{im}\left(\theta_{p}\right)$.

Since the connection 1-form determines these subspaces of the tangent space, we would also like the definition of a connection to be 'equivariant' in the sense that it preserves these subspaces under the group action. Put more explicitly, we would like

$$
\mathcal{V}_{p \cdot g}=\mathcal{V}_{p} \cdot g, \quad \mathcal{H}_{p \cdot g}=\mathcal{H}_{p} \cdot g
$$

where the action of $g \in G$ is taken to be $\left(\phi_{g}\right)_{*}$, the derivative of action $\phi_{g}$. The derivative of the action of $g \in G$ on a vertical vector $X_{\xi}(p)$ is given by

$$
\begin{align*}
\left(\phi_{g}\right)_{*} X_{\xi}(p) & =\left.\left(\phi_{g}\right)_{*} \frac{d}{d t} \phi(x, \exp (t \xi))\right|_{t=0} \\
& =\left.\frac{d}{d t} \phi(x, \exp (t \xi) g)\right|_{t=0} \\
& =\left.\frac{d}{d t} \phi\left(x \cdot g, g^{-1} \exp (t \xi) g\right)\right|_{t=0} \\
& =X_{\operatorname{Ad}\left(g^{-1}\right) \xi}(p \cdot g) \tag{2.34}
\end{align*}
$$

where $\operatorname{Ad}\left(g^{-1}\right): \mathfrak{g} \rightarrow \mathfrak{g}$ is the adjoint representation of $g^{-1} \in G$, the derivative of the map $h \mapsto$ $g^{-1} h g$ at the identity. This immediately shows that $\mathcal{V}_{p \cdot g}=\mathcal{V}_{p} \cdot g$, trivially. Let $u=u_{v}+u_{h} \in T_{p} P$ where $u_{v}$ is vertical and $u_{h}$ is horizontal. If $\mathcal{H}_{p \cdot g}=\mathcal{H}_{p} \cdot g$ then it must be true that

$$
\left(\phi_{g}\right)_{*} u_{h} \in \mathcal{H}_{p \cdot g}
$$

or in terms of the connection this can rewritten as

$$
\begin{equation*}
\theta_{p \cdot g}\left(\left(\phi_{g}\right)_{*}\left(u_{h}\right)\right)=0 . \tag{2.35}
\end{equation*}
$$

If we let $u_{v}=X_{\xi}(p)$ for some $\xi \in \mathfrak{g}$, the effect that (2.35) has on a connection can thus be calculated by seeing that

$$
\begin{aligned}
\theta_{p \cdot g}\left(\left(\phi_{g}\right)_{*} u\right) & =\theta_{p \cdot g}\left(\left(\phi_{g}\right)_{*} u_{v}\right)+\theta_{p \cdot g}\left(\left(\phi_{g}\right)_{*} u_{h}\right) \\
& =\theta_{p \cdot g}\left(\left(\phi_{g}\right)_{*} X_{\xi}(p)\right) \\
& =\theta\left(p \cdot g ; X_{\operatorname{Ad}\left(g^{-1}\right) \xi}(p \cdot g)\right) \\
& =\operatorname{Ad}\left(g^{-1}\right) \xi \\
& =\operatorname{Ad}\left(g^{-1}\right) \theta_{p}(u) .
\end{aligned}
$$

More concisely, this calculation shows that $\mathcal{H}_{p \cdot g}=\mathcal{H}_{p} \cdot g$ implies that $\phi_{g}^{*} \theta=\operatorname{Ad}\left(g^{-1}\right) \circ \theta$. In fact, if $\phi_{g}^{*} \theta=\operatorname{Ad}\left(g^{-1}\right) \circ \theta$ it implies that $\mathcal{H}_{p \cdot g}=\mathcal{H}_{p} \cdot g$, so this can be taken to be an equivalent condition. With this in mind, we precisely define what is meant by a connection on a principal bundle.

Definition 2.36: Let $P \xrightarrow{\pi} B$ be a principal $G$-bundle. $A$ connection on $P$ is a $\mathfrak{g}$-valued 1 -form $\theta \in \Omega^{1}(P) \otimes \mathfrak{g}$ such that

1. $\theta_{p} \circ v_{p}=\mathrm{id}_{\mathfrak{g}}$, and
2. $\phi_{g}^{*} \theta=\operatorname{Ad}\left(g^{-1}\right) \circ \theta$
for all $p \in P$ and every $g \in G$.
Consider the principal $G$-bundle $G \rightarrow\{1\}$ where $G$ acts on itself by a right $G$-action. Since every vector in $T G$ is vertical and $G$ acts transitively, every vector $u \in T_{g} G$ can be written as

$$
u=g \cdot \xi
$$

for some $\xi \in \mathfrak{g}$ where the action of $g \in G$ on $\mathfrak{g}$ corresponds to the derivative of the map $h \mapsto g h$ at the identity. These correspond precisely to the vector fields generated by the infinitesimal action of $\mathfrak{g}$ since

$$
X_{\xi}(g)=\left.\frac{d}{d t} g \cdot \exp (t \xi)\right|_{t=0}=\left(\phi_{g}\right)_{*} \xi=g \cdot \xi
$$

The left Maurer-Cartan form $\theta_{L}$ on $G$ can explicitly defined as $\theta_{L}(g ; g \cdot \xi)=\xi$ or, less opaquely,

$$
\begin{equation*}
\theta_{L}(g ; u)=\left(\phi_{g^{-1}}\right) u \tag{2.37}
\end{equation*}
$$

One checks that $\phi_{g}^{*} \theta_{L}=\operatorname{Ad}\left(g^{-1}\right) \circ \theta_{L}$ to verify this is a connection form. Since we have such an explicit description of this connection we can calculate its exterior derivative

$$
\begin{aligned}
d \theta_{L}(X, Y) & =X \theta_{L}(Y)-Y \theta(X)-\theta_{L}([X, Y]) \\
& =\mathcal{L}_{X} \theta_{L}(Y)-\mathcal{L}_{Y} \theta(X)-\theta_{L}([X, Y]) .
\end{aligned}
$$

If we let $X, Y$ be vector fields generated by the infinitesimal action of $\mathfrak{g}$ we notice that it greatly simplifies this expression. For example, for $\xi, \eta \in \mathfrak{g}$,

$$
\begin{aligned}
d \theta_{L}\left(X_{\xi}, X_{\eta}\right) & =\mathcal{L}_{\xi} \theta_{L}\left(X_{\eta}\right)-\mathcal{L}_{\eta} \theta\left(X_{\xi}\right)-\theta_{L}\left(\left[X_{\xi}, X_{\eta}\right]\right) \\
& =-\theta_{L}\left(\left[X_{\xi}, X_{\eta}\right]\right) \\
& =-\theta_{L}\left(\left[X_{[\xi, \eta]}\right)\right. \\
& =-[\xi, \eta] \\
& =-\left[\theta_{L}\left(X_{\xi}\right), \theta_{L}\left(X_{\eta}\right)\right]
\end{aligned}
$$

since $\theta_{L}\left(X_{\xi}\right), \theta_{L}\left(X_{\eta}\right)$ are constant functions. Now it is enough to note that at a point $g \in G$, $X(g)=g \cdot \xi$ and $Y(g)=g \cdot \eta$ for some $\xi, \eta \in \mathfrak{g}$ and therefore the identity

$$
d \theta_{L}=-\frac{1}{2}\left[\theta_{L}, \theta_{L}\right],
$$

holds for every vector field $X, Y \in \mathfrak{X}(G)$; where for $\omega_{1}, \omega_{2} \in \Omega^{1}(M) \otimes \mathfrak{g}$,

$$
\left[\omega_{1}, \omega_{2}\right](X, Y)=\left[\omega_{1}(X), \omega_{2}(Y)\right]-\left[\omega_{1}(Y), \omega_{2}(X)\right] .
$$

This identity clearly carries over to the trivial principal bundle $B \times G \rightarrow B$ and thus a connection $\theta$ on a principal bundle $P \xrightarrow{\pi} B$ is said to be flat if

$$
d \theta=-\frac{1}{2}[\theta, \theta] .
$$

The 'curvature' of a principal bundle is then a measure of a connections failure to be flat. That is, for a connection form $\theta$, define the $\mathfrak{g}$-valued curvature 2 -form $\Omega$ by

$$
d \theta=\Omega-\frac{1}{2}[\theta, \theta] .
$$

Recall that by definition, $\theta$ vanishes on horizontal vectors. In contrast, the curvature 2 -form is horizontal.

Definition 2.38: Let $P \xrightarrow{\pi} B$ be a smooth principal $G$-bundle. A differential form $\omega \in \Omega^{*}(P)$ is said to be horizontal if it vanishes on vertical vector fields. Equivalently, a differential form is horizontal if

$$
\iota_{\xi} \omega=0
$$

for every $\xi \in \mathfrak{g}$.
The curvature form is an important ingredient for equivariant cohomology, so the following proposition will be useful for performing calculations.
Proposition 2.39: Let $P \xrightarrow{\pi} B$ be a smooth principal $G$-bundle with connection $\theta$ and curvature $\Omega$.

1. $\Omega$ is horizontal,
2. $\Omega$ is equivariant in the sense that $\phi_{g}^{*} \Omega=\operatorname{Ad}\left(g^{-1}\right) \circ \Omega$ and
3. $d \Omega=[\Omega, \theta]$.

In the same vein, Dupont's proof that every principal bundle admits a connection will be used in the discussion that follows. For a proof of these two propositions, the reader is directed to [Dup78, p. 47-49].

Proposition 2.40: Every principal bundle has a connection.
Associated to a basis of $\mathfrak{g}$ is a dual basis $\left\{\xi_{1}^{*}, \ldots, \xi_{n}^{*}\right\}$ of $\mathfrak{g}^{*}=\operatorname{Hom}(\mathfrak{g}, \mathbb{R})$. Thus, to each connection $\theta \in \Omega^{1}(P) \otimes \mathfrak{g}$ are 1-forms

$$
\theta^{i}:=\xi_{i}^{*} \theta \in \Omega^{1}(P) .
$$

Perhaps the most obvious equation these differential forms satisfy is

$$
\theta^{i}\left(p ; X_{\xi_{j}}\right)=\delta_{i j}
$$

for every $p \in P$, reminiscent of the connection forms as defined in [GS99]. By the same token, for $\Omega \in \Omega^{2}(P) \otimes \mathfrak{g}$, the curvature of $\theta$, define

$$
\mu^{i}:=\xi_{i}^{*} \Omega \in \Omega^{2}(P) .
$$

In terms of these differential forms, we have the following identities.

## Proposition 2.41:

1. $\iota_{\xi_{j}} \theta^{i}=\delta_{i j}$.
2. $d \theta^{i}=\mu^{i}-\frac{1}{2} c_{j k}^{i} \theta^{j} \wedge \theta^{k}$.
3. $\iota_{\xi_{j}} \mu^{i}=0$.
4. $d \mu^{i}=c_{j k}^{i} \mu^{j} \wedge \theta^{k}$.

Note that all these identities are corollaries of previous calculations in this section. We will revisit these identities in Section 2.3.1.

### 2.2.3 Basic Differential Forms

Suppose $P \xrightarrow{\pi} B$ is a principal $G$-bundle. By de Rham's theorem, the cohomology of $B$ can be calculated using differential forms via calculating the cohomology of the cochain complex $\left(\Omega^{*}(B), d\right)$.

$$
\Omega^{0}(B) \xrightarrow{d} \Omega^{1}(B) \xrightarrow{d} \Omega^{2}(B) \xrightarrow{d} \cdots
$$

The pullback $\pi^{*}: \Omega^{*}(B) \rightarrow \Omega^{*}(P)$ allows us to recover the cohomology of $B$ by only looking at the basic forms of $P$. That is, the subspace of basic differential forms

$$
\pi^{*}\left(\Omega^{*}(B)\right) \subset \Omega^{*}(P)
$$

is a well defined subcomplex of the de Rham complex of $P$ since it is closed under the differential d. This definition is clumsy for the purposes of performing any actual calculations and so a definition of this subcomplex using only information about $P$ is sought after.

Proposition 2.42: Let $P \xrightarrow{\pi} B$ be a principal $G$-bundle. A differential form $\omega \in \Omega^{*}(P)$ is basic if and only if $\iota \xi=0$ and $\omega \cdot g=\omega$ for every $\xi \in \mathfrak{g}$ and $g \in G$.

Proof. Let $\omega$ be a basic differential form in $\Omega^{q}(P)$. That is, there is a form $\nu \in \Omega^{q}(B)$ such that $\pi_{*} \nu=\omega$. For any $\xi \in \mathfrak{g}$ the vector field $X_{\xi}$ is vertical, hence

$$
\pi_{*} X(p)=0
$$

for every $p \in P$ and thus, $\iota_{\xi}\left(\pi^{*} \nu\right)=0$. Similarly we could ask how the action of $G$ affects the pullback $\pi^{*} \nu$. Let $g \in G$ and consider that since $\pi \circ \phi_{g}=\pi$, we have

$$
\begin{aligned}
\left(\pi^{*} \nu\right) \cdot g & =\phi_{g}^{*} \pi^{*} \nu \\
& =\left(\pi \circ \phi_{g}\right)^{*} \nu \\
& =\pi^{*} \nu
\end{aligned}
$$

These two calculations show that if $\omega$ is basic, then $\iota_{\xi} \omega=0$ and $\omega \cdot g=\omega$.
Now suppose $\iota_{\xi} \omega=0$ and $\omega \cdot g=\omega$ for every $\xi \in \mathfrak{g}$ and $g \in G$. Let $s: B \rightarrow P$ be a section. We assert that $s^{*} \omega \in \Omega^{*}(B)$ satisfies $\pi^{*} s^{*} \omega=\omega$. Note too, if $u \in T_{p} P$ is a tangent vector at $p \in P$, the vector $u-\left(\phi_{g} \circ s \circ \pi\right)_{*} u$ is vertical since

$$
\pi_{*}\left(\phi_{g} \circ s \circ \pi\right)_{*} u=\pi_{*} u
$$

for every $g \in G$. To check that $\omega=\pi^{*} s^{*} \omega$, it is enough to calculate

$$
\left(\omega-\pi^{*} s^{*} \omega\right)\left(p ; u_{1}, \ldots, u_{q}\right)
$$

at an arbitrary point $p$ with arbitrary tangent vectors $u_{1}, \ldots, u_{q} \in T_{p} P$. If

$$
(\pi \circ s)(p)=p \cdot g
$$

for some $g \in G$ then at the point $p$

$$
\begin{aligned}
& \left(\omega-\pi^{*} s^{*} \omega\right)\left(p ; u_{1}, \ldots, u_{q}\right) \\
= & \omega\left(p ; u_{1}, \ldots, u_{q}\right)-\omega\left((s \circ \pi)(p) ;(s \circ \pi)_{*} u_{1}, \ldots,(s \circ \pi)_{*} u_{q}\right) \\
= & \omega\left(p ; u_{1}, \ldots, u_{q}\right)-\left(\omega \cdot g^{-1}\right)\left((s \circ \pi)(p) ;(s \circ \pi)_{*} u_{1}, \ldots,(s \circ \pi)_{*} u_{q}\right) \\
= & \omega\left(p ; u_{1}, \ldots, u_{q}\right)-\omega\left(p ;\left(\phi_{g^{-1}} \circ s \circ \pi\right)_{*} u_{1}, \ldots,\left(\phi_{g^{-1}} \circ s \circ \pi\right)_{*} u_{q}\right) \\
= & \omega\left(p ; u_{1}-\left(\phi_{g^{-1}} \circ s \circ \pi\right)_{*} u_{1}, \ldots, u_{q}-\left(\phi_{g^{-1}} \circ s \circ \pi\right)_{*} u_{q}\right) \\
= & 0
\end{aligned}
$$

since $\omega$ vanishes on vertical vectors. So $\omega$ is basic when $P \rightarrow B$ admits a section. If $P \rightarrow B$ does not admit a section, it admits local sections by Corollary 2.14. Let $\left\{U_{i}\right\}_{i \in J}$ be local trivialisations with local sections $s_{i}: B \rightarrow P$ and define

$$
\nu_{i}:=s_{i}^{*}\left(\left.\omega\right|_{U_{i}}\right) \in \Omega^{q}\left(U_{i}\right)
$$

By letting $b \in U_{i} \cap U_{j}$ and $v_{1}, \ldots, v_{q} \in T_{b} B$ and supposing that $s_{i}(b)=s_{j}(b) \cdot g$ for some $g \in G$ we see that

$$
\begin{aligned}
& \left(\nu_{i}-\nu_{j}\right)\left(b ; v_{1}, \ldots, v_{q}\right) \\
= & \omega\left(s_{i}(b) ;\left(s_{i}\right)_{*} v_{1}, \ldots,\left(s_{i}\right)_{*} v_{q}\right)-\omega\left(s_{j}(b) ;\left(s_{j}\right)_{*} v_{1}, \ldots,\left(s_{j}\right)_{*} v_{q}\right) \\
= & \omega\left(s_{i}(b) ;\left(s_{i}\right)_{*} v_{1}, \ldots,\left(s_{i}\right)_{*} v_{q}\right)-\omega\left(s_{i}(b) ;\left(\phi_{g^{-1}} \circ s_{j}\right)_{*} v_{1}, \ldots,\left(\phi_{g^{-1}} \circ s_{j}\right)_{*} v_{q}\right) \\
= & \omega\left(s_{i}(b) ;\left(s_{i}\right)_{*} v_{1}-\left(\phi_{g^{-1}} \circ s_{j}\right)_{*} v_{1}, \ldots,\left(s_{i}\right)_{*} v_{q}-\left(\phi_{g^{-1}} \circ s_{j}\right)_{*} v_{q}\right) \\
= & 0
\end{aligned}
$$

since $\pi \circ s_{i}=\pi \circ \phi_{g^{-1}} \circ s_{j}=\mathrm{id}$. So defining $\nu \in \Omega^{*}(B)$ by $\left.\nu\right|_{U_{i}}=\nu_{i}$ is well defined since $\nu_{i}=\nu_{j}$ on $U_{i} \cap U_{j}$ for every $i, j \in J$ which shows that $\pi^{*} \nu=\omega$ as required.

Since the set of basic differential forms of a principal bundle $P \xrightarrow{\pi} B$ is closed under the differential $d$, the set of basic differential forms is also a complex. The following definition of basic will be more helpful for the purposes of calculation.

Definition 2.43: Let $P \xrightarrow{\pi} B$ be a smooth principal $G$-bundle. A differential form is said to be basic if it is horizontal and $G$-invariant. That is, $\iota_{\xi} \omega=0$ and $\omega \cdot g=\omega$ for every $\xi \in \mathfrak{g}$ and $g \in G$. The complex of basic differential forms is denoted $\Omega^{*}(P)_{b a s}$.

### 2.3 Equivariant de Rham Theory

### 2.3.1 The Weil Algebra

Let $G$ be a Lie group and $M$ be a manifold with right $G$-action. From the previous discussion of basic differential forms, one might wonder whether there is an equivalent way to find a de Rham complex for the total space of the principal bundle

$$
M \times E G \rightarrow(M \times E G) / G
$$

That is, if we can find a de Rham complex for $M \times E G$ then the basic subcomplex will calculate the equivariant cohomology of $M$. The space $E G$ does not admit a smooth structure in general, so de Rham theory can not be used in the ordinary sense. Instead, we will define a complex called the Weil algebra $W(\mathfrak{g})$ which acts as a surrogate for differential forms on $E G$. This allows us to form a complex

$$
W(\mathfrak{g}) \otimes \Omega^{*}(M)
$$

and study the basic forms of this complex. In this section we will define and study the complex $W(\mathfrak{g})$.

Definition 2.44: Let $G$ be a Lie group with Lie algebra $\mathfrak{g}$. Define the Weil Algebra $W(\mathfrak{g})$ to be the complex

$$
W(\mathfrak{g})=\Lambda\left(\mathfrak{g}^{*}\right) \otimes S\left(\mathfrak{g}^{*}\right)
$$

where $\Lambda, S$ are the exterior and symmetric algebras over $\mathbb{R}$ and $\mathfrak{g}^{*}$ is the dual space of $\mathfrak{g}$. The grading and differential of $W(\mathfrak{g})$ will be explained further in the exposition below.

Let $\mathfrak{g}$ have basis $\left\{\xi_{1}, \ldots, \xi_{n}\right\}$ and $\mathfrak{g}^{*}$ have dual basis $\left\{\xi_{1}^{*}, \ldots \xi_{n}^{*}\right\}$. Both the exterior and symmetric algebras are graded and generated by their degree 1 elements. The sets $\Lambda^{1}\left(\mathfrak{g}^{*}\right)$ and $S^{1}\left(\mathfrak{g}^{*}\right)$ can be naturally identified with $\mathfrak{g}^{*}$ as vector spaces, hence a choice of basis for $\mathfrak{g}$ induces generating sets for $\Lambda\left(\mathfrak{g}^{*}\right)$ and $S\left(\mathfrak{g}^{*}\right)$ which will be denoted $\left\{\theta^{1}, \ldots, \theta^{n}\right\}$ and $\left\{\mu^{1}, \ldots, \mu^{n}\right\}$ respectively. The Weil algebra is hence generated by the $\theta^{i}, \mu^{i}$ elements and inherits a grading by letting the $\theta^{i}$ have degree 1 and the $\mu^{i}$ have degree 2 . Explicitly, one might express the set of degree $n$ elements of $W(\mathfrak{g})$ by

$$
W^{n}(\mathfrak{g})=\bigoplus_{p+2 q=n} \Lambda^{p}\left(\mathfrak{g}^{*}\right) \otimes S^{q}\left(\mathfrak{g}^{*}\right)
$$

The notation is deliberately suggestive of the remarks following Proposition 2.40. To this end, we define an operator (of degree 1) on the generators of $W(\mathfrak{g})$ by defining

$$
d \theta^{i}=\mu^{i}-\frac{1}{2} c_{j k}^{i} \theta^{j} \theta^{k} \text { and } d \mu^{i}=c_{j k}^{i} \mu^{j} \theta^{k}
$$

Further, we define the linear operator (of degree -1 ) $\iota_{\xi_{j}}$ similarly by

$$
\iota_{\xi_{j}} \theta^{i}=\delta_{i j} \text { and } \iota_{\xi_{j}} \mu^{i}=0
$$

so as to mirror the identities in Proposition 2.41. (We take $\iota_{\xi}$ to act trivially on elements of order 0 .) By linearity it is clear that for any $\xi=k^{i} \xi_{i} \in \mathfrak{g}$ (for constants $k^{i} \in \mathbb{R}$ )

$$
\iota_{\xi}=\iota_{k^{i} \xi_{i}}=k^{i} \iota_{\xi_{i}}
$$

Clearly these operators can be extended to be derivations on $W(\mathfrak{g})$. The operator $\iota_{\xi}$ clearly satisfies $\iota_{\xi}^{2}=0$ and leads to an analogous definition of a horizontal element.

Definition 2.45: An element $\alpha \in W(\mathfrak{g})$ is said to be horizontal if

$$
\iota_{\xi} \alpha=0
$$

for every $\xi \in \mathfrak{g}$.
Proposition 2.46: The operator $d$ above satisfies $d^{2}=0$.
Proof. The proof that $\iota_{\xi_{j}}$ is a derivation is clear from its definition. As for $d$, since $\mu^{i}$ can be written as

$$
\mu^{i}=d \theta^{i}-\frac{1}{2} c_{j k}^{i} \theta^{j} \theta^{k}
$$

we need only check that $d^{2} \theta^{i}=0$. The calculation expands out as

$$
\begin{aligned}
d^{2} \theta^{i} & =d\left(\mu^{i}-\frac{1}{2} c_{j k}^{i} \theta^{j} \theta^{k}\right) \\
& =d \mu^{i}-\frac{1}{2} c_{j k}^{i} d \theta^{j} \theta^{k}+\frac{1}{2} c_{j k}^{i} \theta^{j} d \theta^{k} \\
& =d \mu^{i}-\frac{1}{2} c_{j k}^{i}\left(\mu^{j}-\frac{1}{2} c_{a b}^{j} \theta^{a} \theta^{b}\right) \theta^{k}+\frac{1}{2} c_{j k}^{i} \theta^{j}\left(\mu^{k}-\frac{1}{2} c_{a b}^{k} \theta^{a} \theta^{b}\right) .
\end{aligned}
$$

Some terms immediately cancel, for example

$$
-\frac{1}{2} c_{j k}^{i} \mu^{j} \theta^{k}=-\frac{1}{2} d \mu^{i}
$$

and thus

$$
d \mu^{i}-\frac{1}{2} c_{j k}^{i} \mu^{j} \theta^{k}+\frac{1}{2} c_{j k}^{i} \mu^{k} \theta^{j}=0
$$

since $c_{j k}^{i}=-c_{k j}^{i}$. The calculation of $d^{2} \theta^{i}=0$ thus reduces to showing that

$$
\begin{align*}
0 & =\frac{1}{4} c_{j k}^{i} c_{a b}^{j} \theta^{a} \theta^{b} \theta^{k}-\frac{1}{4} c_{j k}^{i} c_{a b}^{k} \theta^{j} \theta^{a} \theta^{b} \\
& =\frac{1}{2} c_{j k}^{i} c_{a b}^{j} \theta^{a} \theta^{b} \theta^{k} . \tag{2.47}
\end{align*}
$$

This rather tedious calculation can be summarised by observing that the Jacobi identity takes its form in the structure constants by requiring that they satisfy

$$
\begin{equation*}
c_{j k}^{i} c_{a b}^{j}+c_{j a}^{i} c_{b k}^{j}+c_{j b}^{i} c_{k a}^{j}=0 \tag{2.48}
\end{equation*}
$$

for every fixed $i$. Further observe that fixing $\alpha, \beta, \gamma$ we pull the term

$$
\begin{aligned}
& \frac{1}{2} c_{j \gamma}^{i} c_{\alpha \beta}^{j} \theta^{\alpha} \theta^{\beta} \theta^{\gamma}+\frac{1}{2} c_{j \beta}^{i} c_{\alpha \gamma}^{j} \theta^{\alpha} \theta^{\gamma} \theta^{\beta}+\frac{1}{2} c_{j \gamma}^{i} c_{\beta \alpha}^{j} \theta^{\beta} \theta^{\alpha} \theta^{\gamma}+\frac{1}{2} c_{j \alpha}^{i} c_{\beta \gamma}^{j} \theta^{\beta} \theta^{\gamma} \theta^{\beta} \\
& +\frac{1}{2} c_{j \beta}^{i} c_{\gamma \alpha}^{j} \theta^{\gamma} \theta^{\alpha} \theta^{\beta}+\frac{1}{2} c_{j \alpha}^{i} c_{\gamma \alpha}^{j} \theta^{\gamma} \theta^{\beta} \theta^{\alpha}
\end{aligned}
$$

out of the sum in 2.47 (where Einstein summation convention is not being observed). We can simplify this term to get

$$
\begin{aligned}
& \frac{1}{2} \theta^{\alpha} \theta^{\beta} \theta^{\gamma}\left(c_{j \gamma}^{i} c_{\alpha \beta}^{j}-c_{j \beta}^{i} c_{\alpha \gamma}^{j}-c_{j \gamma}^{i} c_{\beta \alpha}^{j}+c_{j \alpha}^{i} c_{\beta \gamma}^{j}+c_{j \beta}^{i} c_{\gamma \alpha}^{j}-c_{j \alpha}^{i} c_{\gamma \beta}^{j}\right) \\
& =\theta^{\alpha} \theta^{\beta} \theta^{\gamma}\left(c_{j \gamma}^{i} c_{\alpha \beta}^{j}+c_{j \alpha}^{i} c_{\beta \gamma}^{j}+c_{j \beta}^{i} c_{\gamma \alpha}^{j}\right)
\end{aligned}
$$

whence it becomes clear that $d^{2}=0$.
The algebra $W(\mathfrak{g})$ can thus be thought of a cochain complex with differential $d$. The de Rham complex of a contractible space is acyclic, so $W(\mathfrak{g})$ should be acyclic in order to mirror this property. The following proposition follows a similar approach to [GS99] and [Mei06].

Theorem 2.49: $W(\mathfrak{g})$ is an acyclic algebra.
Proof. Note that the algebra $W(\mathfrak{g})$ can be generated by the elements $\left\{\theta^{i}, d \theta^{i}\right\}$, since the equation

$$
\mu^{i}=d \theta^{i}+\frac{1}{2} c_{j k}^{i} \theta^{j} \theta^{k}
$$

shows that any element $w \in W^{p}(\mathfrak{g})$ may be written in the form

$$
w=\sum_{n+2 m=p} k_{n, m} \theta^{\alpha_{1}} \cdots \theta^{\alpha_{n}} d \theta^{\beta_{1}} \cdots d \theta^{\beta_{m}}=\sum_{n+2 m=p} k_{n, m} w_{n, m}
$$

where $k_{n, m}$ is some real constant and $w_{n, m} \in W^{n+2 m}(\mathfrak{g})$. Note that the set

$$
\left\{w_{n, m}: n+2 m=p\right\}
$$

is a basis for $W^{p}(\mathfrak{g})$ when thought of as a vector space. On these generators of $W(\mathfrak{g})$ we can define a derivation $Q$ by $Q\left(\theta^{i}\right)=0$ and $Q\left(d \theta^{i}\right)=\theta^{i}$. Calculating $d Q w$ on its summands we find

$$
\begin{aligned}
d Q\left(w_{n, m}\right)= & d Q\left(\theta^{\alpha_{1}} \cdots \theta^{\alpha_{n}} d \theta^{\beta_{1}} \cdots d \theta^{\beta_{m}}\right) \\
= & d\left(\sum_{i=1}^{m} \theta^{\beta_{i}} \theta^{\alpha_{1}} \cdots \theta^{\alpha_{n}} d \theta^{\beta_{1}} \cdots d \hat{\theta^{\beta_{i}}} \cdots d \theta^{\beta_{m}}\right) \\
= & \sum_{i=1}^{n} \sum_{i=1}^{m}(-1)^{j} \theta^{\beta_{i}} \theta^{\alpha_{1}} \cdots \theta^{\hat{\alpha}_{j}} \cdots \theta^{\alpha_{n}} d \theta^{\alpha_{j}} d \theta^{\beta_{1}} \cdots d \hat{\theta}^{\beta_{i}} \cdots d \theta^{\beta_{m}} \\
& +\sum_{i=1}^{m} \theta^{\alpha_{1}} \cdots \theta^{\alpha_{n}} d \theta^{\beta_{1}} \cdots d \theta^{\beta_{m}}
\end{aligned}
$$

where the caret denotes omission from the sequence (e.g. $\theta^{\hat{\alpha}_{j}}$ ). Similarly, calculating $Q d w$ on its summands we find

$$
\begin{aligned}
Q d\left(w_{n, m}\right) & =Q d\left(\theta^{\alpha_{1}} \cdots \theta^{\alpha_{n}} d \theta^{\beta_{1}} \cdots d \theta^{\beta_{m}}\right) \\
& =Q\left(\sum_{i=1}^{n}(-1)^{j} \theta^{\alpha_{1}} \cdots \theta^{\hat{\alpha}_{j}} \cdots \theta^{\alpha_{n}} d \theta^{\alpha_{j}} d \theta^{\beta_{1}} d \theta^{\beta_{m}}\right) \\
& =\sum_{i=1}^{n} \theta^{\alpha_{1}} \cdots \theta^{\alpha_{n}} d \theta^{\beta_{1}} \cdots d \theta^{\beta_{m}} \\
& +\sum_{i=1}^{m} \sum_{i=1}^{n}(-1)^{j+1} \theta^{\beta_{i}} \theta^{\alpha_{1}} \cdots \theta^{\hat{\alpha}_{j}} \cdots \theta^{\alpha_{n}} d \theta^{\alpha_{j}} d \theta^{\beta_{1}} \cdots d \hat{\theta}^{\beta_{i}} \cdots d \theta^{\beta_{m}}
\end{aligned}
$$

whence it becomes clear that

$$
(d Q+Q d) w_{n, m}=(n+m) w_{n, m}
$$

for each summand $w_{n, m}$. Since the $w_{n, m}$ elements form a basis for $W^{p}(\mathfrak{g})$ it is possible to define a linear map $Q_{n, m}: W^{p}(\mathfrak{g}) \rightarrow W^{p-1}(\mathfrak{g})$ by

$$
Q_{n, m}\left(w_{s, t}\right)= \begin{cases}\frac{1}{n+m} Q w_{s, t} & \text { if } s=n, t=m \\ 0 & \text { otherwise }\end{cases}
$$

and hence a chain homotopy $K$ where $K_{p}=\sum_{n+2 m=p} Q_{n, m}$. That is, it has been shown that

$$
d K+K d=\mathrm{id}
$$

and hence, $W(\mathfrak{g})$ is acyclic.
Remark 2.50: In fact, this proof shows that any cochain complex generated by $\left\{\theta^{i}, d \theta^{i}\right\}$ (where $d \theta^{i} \neq 0$ for any $i$ ) is acyclic.

The complex $W(\mathfrak{g})$ also carries a natural action of $G$. The action $\phi_{\mathfrak{g}^{*}}: \mathfrak{g}^{*} \times G \rightarrow \mathfrak{g}^{*}$ is induced by the contragredient (or coadjoint) action of $G$ on $\mathfrak{g}^{*}$. When considering the natural bilinear product $\langle\cdot, \cdot\rangle: \mathfrak{g}^{*} \times \mathfrak{g} \rightarrow \mathbb{R}$, the contragredient action is the unique action such that

$$
\left\langle\xi^{*} \cdot g, \eta \cdot g\right\rangle=\left\langle\xi^{*}, \eta\right\rangle=\xi^{*}(\eta)
$$

for every $\xi^{*} \in \mathfrak{g}^{*}, \eta \in \mathfrak{g}, g \in G$. Since both $\Lambda\left(\mathfrak{g}^{*}\right)$ and $S\left(\mathfrak{g}^{*}\right)$ are generated by their elements of order 1 (and $\mathfrak{g}^{*} \cong \Lambda^{1}\left(\mathfrak{g}^{*}\right) \cong S^{1}\left(\mathfrak{g}^{*}\right)$ as vector spaces) the contragredient action defines an action on $W(\mathfrak{g})$.

Definition 2.51: An element of $W(\mathfrak{g})$ is said to be basic if it is horizontal and $G$-invariant. That is, $\iota_{\xi} \omega=0$ and $\omega \cdot g=\omega$ for every $\xi \in \mathfrak{g}$ and $g \in G$. The complex of basic differential forms is denoted $W(\mathfrak{g})_{\text {bas }}$.

The action of $G$ on $W(\mathfrak{g})$ further induces an action of $\mathfrak{g}$ via the Lie derivative which again agrees with Cartan's magic formula

$$
\mathcal{L}_{\xi}=d \iota_{\xi}+\iota_{\xi} d .
$$

This formula makes it much easier to calculate the action of $\mathfrak{g}$ on $W(\mathfrak{g})$ and indeed,

$$
\begin{aligned}
\mathcal{L}_{\xi_{j}}\left(\theta^{i}\right) & =\left(d \iota \xi_{j}+\iota_{\xi_{j}} d\right) \theta^{i} \\
& =\iota_{\xi_{j}}\left(\mu^{i}-\frac{1}{2} c_{a b}^{i} \theta^{a} \theta^{b}\right) \\
& =-\frac{1}{2} c_{j b}^{i} \theta^{b}+\frac{1}{2} c_{a j}^{i} \theta^{a} \\
& =-c_{j k}^{i} \theta^{k}
\end{aligned}
$$

since $a, b$ sum over the same numbers and

$$
\begin{aligned}
\mathcal{L}_{\xi_{k}}\left(\mu^{i}\right) & =\left(d \iota_{\xi_{k}}+\iota \iota_{k} d\right) \mu^{i} \\
& =\iota_{\xi_{k}}\left(c_{a b}^{i} \mu^{a} \theta^{b}\right) \\
& =c_{a k}^{i} \mu^{a} .
\end{aligned}
$$

It follows that the differential $d$ may be redefined as

$$
d \theta^{i}=\mu^{i}-\frac{1}{2} \theta^{j} \mathcal{L}_{\xi_{j}}\left(\theta^{i}\right)
$$

on the $\Lambda\left(\mathfrak{g}^{*}\right)$ elements and

$$
\begin{equation*}
d \mu^{i}=\theta^{k} \mathcal{L}_{\xi_{k}}\left(\mu^{i}\right) \tag{2.52}
\end{equation*}
$$

on the $S\left(\mathfrak{g}^{*}\right)$ elements. With this in mind, the Weil algebra can be thought of as the total complex of a double complex $\left(C^{*, *}, \delta_{1}, \delta_{2}\right)$ where

$$
C^{p, q}=\Lambda^{p-q}\left(\mathfrak{g}^{*}\right) \otimes S^{q}\left(\mathfrak{g}^{*}\right)
$$

and $C^{p, q}=0$ when $p-q<0$. The map $\delta_{2}: C^{p, q} \rightarrow C^{p, q+1}$ is defined on generators by

$$
\delta_{2}\left(\theta^{i}\right)=\mu^{i}, \quad \delta_{2}\left(\mu^{i}\right)=0
$$

and the map $\delta_{1}: C^{p, q} \rightarrow C^{p+1, q}$ is defined on generators by

$$
\begin{equation*}
\delta_{1}\left(\theta^{i}\right)=-\frac{1}{2} \theta^{j} \mathcal{L}_{\xi_{j}}\left(\theta^{i}\right), \quad \delta_{1}\left(\mu^{i}\right)=\theta^{k} \mathcal{L}_{\xi_{k}}\left(\mu^{i}\right) \tag{2.53}
\end{equation*}
$$



Lemma 2.54: Let $\alpha \in W(\mathfrak{g})$. Then

$$
\iota_{\xi} \alpha=0
$$

for every $\xi \in \mathfrak{g}$ if and only if $\alpha \in \Lambda^{0}\left(\mathfrak{g}^{*}\right) \otimes S^{m}\left(\mathfrak{g}^{*}\right)$ for some integer $m$.
Proof. The statement is trivial for $m=0$. Showing that $\iota_{\xi} \alpha=0$ implies $\alpha \in \Lambda^{0}\left(\mathfrak{g}^{*}\right) \otimes S^{m}\left(\mathfrak{g}^{*}\right)$ for $m>0$ can be done most concisely by observing that the equation

$$
\theta^{i} \iota_{\xi_{i}}=n \cdot \mathrm{id}
$$

holds on $\Lambda^{n}\left(\mathfrak{g}^{*}\right) \otimes S^{m}\left(\mathfrak{g}^{*}\right)$ for any $n>1$. The converse follows by the definition of $\iota_{\xi}$.
By Lemma 2.54 there are no horizontal elements in $\Lambda^{p-q}\left(\mathfrak{g}^{*}\right) \otimes S^{q}\left(\mathfrak{g}^{*}\right)$ where $p-q>0$. But $C^{p, q}=0$ when $p-q<0$ hence the only horizontal elements lie in $C^{q, q}=\Lambda^{0}\left(\mathfrak{g}^{*}\right) \otimes S^{q}\left(\mathfrak{g}^{*}\right)$. Since $\iota_{\xi} \mu^{i}=0$ for every $\xi \in \mathfrak{g}$ the horizontal elements are precisely those in $\Lambda^{0}\left(\mathfrak{g}^{*}\right) \otimes S^{q}\left(\mathfrak{g}^{*}\right)$. The differential $\delta_{2}$ is trivial on the horizontal elements. Since the horizontal elements are generated by $S\left(\mathfrak{g}^{*}\right)$, for a basic element $w \in W(\mathfrak{g})_{\text {bas }}$

$$
\delta_{1} w=\theta^{k} \mathcal{L}_{\xi_{k}} w=0
$$

since $\mathcal{L}_{\xi} w=0$ for all $\xi \in \mathfrak{g}$ if $w$ is $G$-invariant. Taking the total complex of the basic subalgebra of this double complex yields the complex

$$
\Lambda^{0}\left(\mathfrak{g}^{*}\right) \otimes S^{0}\left(\mathfrak{g}^{*}\right) \rightarrow 0 \rightarrow \Lambda^{0}\left(\mathfrak{g}^{*}\right) \otimes S^{1}\left(\mathfrak{g}^{*}\right) \rightarrow 0 \rightarrow \Lambda^{0}\left(\mathfrak{g}^{*}\right) \otimes S^{2}\left(\mathfrak{g}^{*}\right) \rightarrow \cdots
$$

where every arrow is the 0 map. Consequently, we have proved the following theorem.
Theorem 2.55: $W(\mathfrak{g})_{\text {hor }} \cong S\left(\mathfrak{g}^{*}\right)$ and hence $W(\mathfrak{g})_{\text {bas }} \cong S^{*}\left(\mathfrak{g}^{*}\right)^{G}$. Moreover,

$$
H^{*}\left(W(\mathfrak{g})_{b a s}\right)=S\left(\mathfrak{g}^{*}\right)^{G}
$$

since $d$ is trivial on $W(\mathfrak{g})_{\text {bas }}$.

### 2.3.2 The Weil Model

Let $G$ be a compact Lie group and $M$ be a manifold with right $G$-action. For any principal $G$-bundle $P \xrightarrow{\pi} B$, the space $P \times M$ is a manifold with free $G$-action and so

$$
(P \times M) / G
$$

is also a manifold and hence admits a de Rham complex. By Proposition 2.42 we can identify the differential forms on $(P \times M) / G$ thusly

$$
\Omega^{*}((P \times M) / G)=\Omega_{b a s}^{*}(P \times M) \cong\left(\Omega^{*}(P) \otimes \Omega^{*}(M)\right)_{b a s}
$$

Treating $W(\mathfrak{g})$ as a de Rham complex for $E G$ motivates the following definition.

Definition 2.56: Let $G$ be a compact Lie group and $M$ a manifold with right $G$-action. The Weil model for the equivariant cohomology of $M$ is defined to be the complex

$$
\left(W(\mathfrak{g}) \otimes \Omega^{*}(M)\right)_{b a s} .
$$

The fact that this is an adequate model for the equivariant cohomology of $M$ is a well understood result and accordingly we have the following classical theorem which will be proved in the final chapter of this thesis.

Theorem 2.57: Let $G$ be a compact Lie group and $M$ a manifold with right $G$-action. There is an isomorphism

$$
H_{G}(M) \cong H^{*}\left(\left(W(\mathfrak{g}) \otimes \Omega^{*}(M)\right)_{b a s}\right)
$$

### 2.3.3 The Chern-Weil Homomorphism

Let $P \xrightarrow{\pi} B$ be a principal $G$-bundle with connection $\theta_{P} \in \Omega^{1}(P) \otimes \mathfrak{g}$ and curvature $\Omega_{P} \in$ $\Omega^{2}(P) \otimes \mathfrak{g}$. Recall from Section 2.2.2 that a choice of connection is equivalent to choosing 1-forms

$$
\theta_{P}^{i}:=\xi_{i}^{*} \theta \in \Omega^{1}(P) .
$$

such that $\theta^{i}\left(p ; X_{\xi_{j}}\right)=\delta_{i j}$ such that the subspace they span is invariant under the action of $G$. There are also 2 -forms

$$
\mu_{P}^{i}:=\xi_{i}^{*} \Omega \in \Omega^{2}(P)
$$

related to the curvature form $\Omega$. Associated to the choice of connection is a unique homomorphism $w\left(\theta_{P}\right): W(\mathfrak{g}) \rightarrow \Omega^{*}(P)$ such that

$$
w\left(\theta_{P}\right)\left(\theta^{i}\right)=\theta_{P}^{i}, \quad w\left(\theta_{P}\right)\left(\mu^{i}\right)=\mu_{P}^{i} .
$$

This is the Weil homomorphism which is an equivariant chain map for which one can easily check that the identities

1. $d w\left(\theta_{P}\right)-w\left(\theta_{P}\right) d=0$ and
2. $\iota_{\xi} w\left(\theta_{P}\right)-w\left(\theta_{P}\right) \iota_{\xi}=0$
hold for every $\xi \in \mathfrak{g}$. In particular, this means that $w\left(\theta_{P}\right)$ descends to a chain map on basic differential forms and the following diagram commutes

since $W(\mathfrak{g})_{\text {bas }} \cong S\left(\mathfrak{g}^{*}\right)^{G}$. Moreover, from Theorem 2.55 the basic cohomology ring of $W(\mathfrak{g})$ is $S\left(\mathfrak{g}^{*}\right)^{G}$ so the map further induces the classical map in cohomology called the Chern-Weil homomorphism

$$
\kappa_{G}: S\left(\mathfrak{g}^{*}\right)^{G} \rightarrow H^{*}(B)
$$

which does not depend on the choice of connection $\theta_{P}$ (see [Bot73] or [AB82] for details).

### 2.3.4 The Mathai-Quillen Isomorphism

Let $G$ be a Lie group with corresponding Lie algebra $\mathfrak{g}$ of dimension $n$ and basis $\left\{\xi_{1}, \cdots, \xi_{n}\right\}$. Let $M$ be a manifold with right $G$-action. Consider the operator

$$
\zeta:=\theta^{i} \otimes \iota_{\xi_{i}}: W(\mathfrak{g}) \otimes \Omega^{*}(M) \rightarrow W(\mathfrak{g}) \otimes \Omega^{*}(M)
$$

where for $\alpha \in W(\mathfrak{g})$ and $\omega \in \Omega^{*}(M)$

$$
\begin{equation*}
\zeta(\alpha \otimes \omega)=\sum_{i=1}^{n} \theta^{i} \alpha \otimes \iota_{\xi_{i}} \omega . \tag{2.58}
\end{equation*}
$$

Proposition 2.59: The series

$$
\exp (\zeta)=1+\zeta+\frac{1}{2!} \zeta^{2}+\cdots
$$

converges.
Proof. Since $\theta^{i} \theta^{i}=0$, by the pigeonhole principle one notes that

$$
\theta^{i_{1}} \cdots \theta^{i_{n+1}}=0
$$

and hence $\zeta^{n+1}=0$.
Since $\exp (\zeta)$ converges, it has an inverse $\exp (-\zeta)$ and is thus an automorphism of $W(\mathfrak{g}) \otimes$ $\Omega^{*}(M)$ which is known as the Mathai-Quillen isomorphism. One notes that $\zeta$ is equivariant and hence $\exp (\zeta)$ is equivariant. The derivations $d$ and $\iota_{\xi}$ are not preserved by $\exp (\zeta)$ and so we turn to calculations of [MQ86], [Kal93] via [GS99, p. 41-44].

Theorem 2.60: The automorphism $\exp (\zeta)$ satisfies

$$
\begin{equation*}
\exp (\zeta) d \exp (-\zeta)=d-\mu^{k} \otimes \iota_{\xi_{k}}+\theta^{k} \otimes \mathcal{L}_{\xi_{k}} \tag{2.61}
\end{equation*}
$$

and

$$
\begin{equation*}
\exp (\zeta)\left(1 \otimes \iota_{\xi}+\iota_{\xi} \otimes 1\right) \exp (-\zeta)=\iota_{\xi} \otimes 1 \tag{2.62}
\end{equation*}
$$

for every $\xi \in \mathfrak{g}$.

The identity 2.62 shows that the automorphism $\exp (\zeta)$ can be restricted to the horizontal subspace $\left(W(\mathfrak{g}) \otimes \Omega^{*}(M)\right)_{h o r}$ to yield the following corollary.

Corollary 2.63: $\exp (\zeta):\left(W(\mathfrak{g}) \otimes \Omega^{*}(M)\right)_{h o r} \rightarrow S\left(\mathfrak{g}^{*}\right) \otimes \Omega^{*}(M)$.
Proof. Let $\alpha \in\left(W(\mathfrak{g}) \otimes \Omega^{*}(M)\right)_{h o r}$. Then $\alpha$ satisfies

$$
\left(\iota_{\xi} \otimes 1\right) \exp (\zeta) \alpha=0
$$

thus $\exp (\zeta) \alpha \in W(\mathfrak{g})_{\text {hor }} \otimes \Omega^{*}(M) \cong S\left(\mathfrak{g}^{*}\right) \otimes \Omega^{*}(M)$ by Theorem 2.55.
The horizontal subspace is not closed under $d$, but the basic subspace is. Thus the automorphism $\exp \zeta$ restricts further to an algebra automorphism on the basic subalgebra.

### 2.3.5 The Cartan Model

Following the last section (specifically Corollary 2.63), the Mathai-Quillen isomorphism defines an algebra isomorphism

$$
\exp (\zeta):\left(W(\mathfrak{g}) \otimes \Omega^{*}(M)\right)_{b a s} \rightarrow\left(S\left(\mathfrak{g}^{*}\right) \otimes \Omega^{*}(M)\right)^{G}
$$

The differential as described in 2.61 can be further simplified on $G$-invariant elements, too. By the calculation in 2.52,

$$
d=d \otimes 1+1 \otimes d=\theta^{k} \mathcal{L}_{\xi_{k}} \otimes 1+1 \otimes d
$$

and hence

$$
\begin{aligned}
\exp (\zeta) d \exp (-\zeta) & =\theta^{k} \mathcal{L}_{\xi_{k}} \otimes 1+1 \otimes d-\mu^{k} \otimes \iota \iota_{\xi_{k}}+\theta^{k} \otimes \mathcal{L}_{\xi_{k}} \\
& =1 \otimes d-\mu^{k} \otimes \iota \iota_{\xi_{k}}+\theta^{k} \otimes 1\left(\mathcal{L}_{\xi_{k}} \otimes 1+1 \otimes \mathcal{L}_{\xi_{k}}\right)
\end{aligned}
$$

Since the basic subalgebra is $G$-invariant, $\mathcal{L}_{\xi_{k}} \otimes 1+1 \otimes \mathcal{L}_{\xi_{k}}=0$ on $\left(S\left(\mathfrak{g}^{*}\right) \otimes \Omega^{*}(M)\right)^{G}$ and the differential simplifies to

$$
d_{G}:=1 \otimes d-\mu^{k} \otimes \iota_{\xi_{k}}
$$

Definition 2.64: Let $M$ be a manifold and $G$ be a Lie group with Lie algebra $\mathfrak{g}$. Define the Cartan Model to be the complex

$$
\left(S\left(\mathfrak{g}^{*}\right) \otimes \Omega^{*}(M)\right)^{G}
$$

with differential

$$
d_{G}:=1 \otimes d-\mu^{k} \otimes \iota_{\xi_{k}}
$$

Taking Theorem 2.57 for granted, we have proved the following theorem about the Cartan model for equivariant cohomology.
Theorem 2.65: Let $G$ be a compact Lie group and $M$ a manifold with right $G$-action. Then there is an isomorphism

$$
H_{G}^{*}(M) \cong H^{*}\left(\left(S\left(\mathfrak{g}^{*}\right) \otimes \Omega^{*}(M)\right)^{G}\right)
$$

## Chapter 3

## Simplicial Methods

### 3.1 Simplicial and Cosimplicial Objects

### 3.1.1 The Simplicial Category

Define the simplicial category, $\Delta$, to be the category whose objects are ordered sets of integers $[n]=\{0<1<\cdots<n\}$ (for $n \geq 0$ ) and whose morphisms $\mu:[n] \rightarrow[m]$ are non-decreasing maps (i.e. $\mu(i) \leq \mu(j)$ if $i<j$ ). In particular, for an injective non-decreasing map $\mu:[n-1] \rightarrow[n]$ there are only a total of $n+1$ morphisms to choose from, which may canonically be indexed by $d^{i}:[n-1] \rightarrow[n]$ for $0 \leq i \leq n$ as

$$
d^{i}(k)=j \text { if } k<i \text { and } d^{i}(k)=k+1 \text { if } k \geq i
$$

These canonical maps are often referred to as the coface maps (or cofaces). Similarly we may also define non-decreasing maps $s^{i}:[n+1] \rightarrow[n]$ for $0 \leq i \leq n$ as

$$
s^{i}(k)=k \text { if } k \leq i \text { and } s^{i}(k)=k-1 \text { if } k>i
$$

that can be seen to be, in some sense, complementary to the $d^{i}$ morphisms and are often referred to as the codegeneracy maps (or codegeneracies). With these definitions it is not difficult to check that the following cosimplicial identities hold whenever their composition is defined.

$$
\begin{align*}
& d^{j} d^{i}=d^{i} d^{j-1}  \tag{3.1}\\
& s^{j} d^{i}=\left\{\begin{array}{cl}
d^{i} s^{j-1} & \text { if } i<j . \\
\text { id } i<j . \\
d^{i-1} s^{j} & \text { if } i=j \text { or } i=j+1 . \\
s^{j} s^{i}=s^{i} s^{j+1} & \text { if } i \leq j .
\end{array}\right. \tag{3.2}
\end{align*}
$$

The codegeneracies are complementary to the cofaces in the sense that $d^{i} s^{i}=\mathrm{id}$ and that any morphism $\mu:[n] \rightarrow[m]$ can be written as the composition of these morphisms as seen in the following result of May [May67].

Proposition 3.4: Let $\mu:[n] \rightarrow[m]$ be a map in $\Delta$. Then $\mu$ decomposes into a unique sequence of maps

$$
\mu=d^{i_{r}} \cdots d^{i_{1}} s^{j_{1}} \cdots s^{j_{t}}
$$

where $0 \leq i_{1} \leq \cdots \leq i_{r} \leq m$ and $0 \leq j_{1} \leq \cdots \leq j_{s} \leq m$.
Proof. The image of $\mu$ contains at most $n$ elements. Let $I=\left\{i_{1}, i_{2}, \ldots i_{r}\right\}$ be the set of elements that are not in the image of $\mu$ in increasing order and let $J=\left\{j_{i}, \ldots, j_{t}\right\}$ be the set of elements such that $\mu\left(j_{i}\right)=\mu\left(j_{i}+1\right)$ in increasing order. We check that the map decomposes into

$$
\mu=d^{i_{r}} \cdots d^{i_{1}} s^{j_{1}} \cdots s^{j_{t}}
$$

by applying induction.
First suppose that $\mu(0)=p_{0}$. Note that $s^{i}(0)=0$ for every $i \geq 0$ and hence we need only check how $d^{i}$ affects the calculation. Since $\mu$ is non-decreasing, $0,1, \ldots, p_{0}-1$ are necessarily in $I$ and one notes that $d^{p_{0}-1} d^{p_{0}-2} \cdots d^{0}(0)=p_{0}$. But $p_{0} \notin I$ and $d^{i}\left(p_{0}\right)=p_{0}$ for every $i>p_{0}$ and so

$$
\mu(0)=d^{i_{r}} \cdots d^{i_{1}} s^{j_{1}} \cdots s^{j_{t}}(0) .
$$

Now assume that $\mu(k)=d^{i_{r}} \cdots d^{i_{1}} s^{j_{1}} \cdots s^{j_{t}}(k)$. If $\mu(k)=\mu(k+1)$ then $k \in J$. Note that if $i \geq k+1$ then $s^{i}(k)=k$ and $s^{i}(k+1)=k+1$ and in particular, $s^{k} s^{i}(k)=k$ and $s^{k} s^{i}(k+1)=k$. From this observation we can deduce that induction holds if $\mu(k)=\mu(k+1)$. If we suppose that $\mu(k+1)=\mu(k)+c$ for some $c \neq 0$ then $k \notin J$ and so

$$
s^{j_{1}} \cdots s^{j_{t}}(k+1)=s^{j_{1}} \cdots s^{j_{t}}(k)+1 .
$$

Also, it must be true that $k+1, \ldots, k+c-1 \in I$ and so

$$
d^{i_{r}} \cdots d^{i_{1}} s^{j_{1}} \cdots s^{j_{t}}(k+1)=d^{i_{r}} \cdots d^{i_{1}} s^{j_{1}} \cdots s^{j_{t}}(k)+1+c-1=\mu(k+1)
$$

as required. In fact, since $n-t$ is the number of elements in the image $\mu([n])$ and $r$ is the number of missed elements, it is true that $n-t+r=m$ which confirms that $d^{i_{r}} \cdots d^{i_{1}} s^{j_{1}} \cdots s^{j_{t}}$ is indeed a morphism from $[n]$ to $[m]$.

In category theory there is the notion of the opposite category. For any category $\mathscr{C}$ there is its opposite category $\mathscr{C}^{o p}$ with objects $A^{o p}$ for each object $A \in \mathscr{C}$, morphisms $a^{o p}: B^{o p} \rightarrow A^{o p} \in$ $\operatorname{Hom}\left(B^{o p}, A^{o p}\right)$ for each morphism $a: A \rightarrow B \in \operatorname{Hom}(A, B)$ and insisting that $a^{o p} b^{o p}=(b a)^{o p}$ whenever the morphism $b a$ is defined.

Definition 3.5: A simplicial object in a category $\mathscr{C}$ is a functor

$$
F: \Delta^{o p} \rightarrow \mathscr{C} .
$$

If $F$ and $G$ are simplicial objects in $\mathscr{C}$ then a simplicial map from $F$ to $G$ is a natural transformation

$$
\alpha: F \rightarrow G \text {. }
$$

Thus the simplicial objects in $\mathscr{C}$, together with the simplicial maps between them form a category $s \mathscr{C}$. Moreover, let $d^{i}:[n-1] \rightarrow[n]$ be a coface map of $\Delta$ for $0 \leq i \leq n$. The map $d_{i}:=F\left(d^{i}\right)$ is called a face map of $F$. Similarly, let $s^{i}:[n+1] \rightarrow[n]$ be a codegeneracy map of $\Delta$ for $0 \leq i \leq n$. The map $s_{i}:=F\left(s^{i}\right)$ is called a degeneracy map of $F$.

This definition is helpful in understanding the relationships between simplicial objects later in the discussion, but may not be satisfying to the average reader. To help develop the idea of simplicial objects, some simplicial objects will be defined more explicitly and then shown to be equivalent to their definition as functors. It will thus be useful to have the following corollary of Proposition 3.4.

Corollary 3.6: Let $\mu^{o p}:[m]^{o p} \rightarrow[n]^{o p}$ be a morphism in the category $\Delta^{o p}$. Then $\mu^{o p}$ decomposes into a unique sequence of maps

$$
\mu^{o p}=\left(s^{j_{t}}\right)^{o p} \cdots\left(s^{j_{1}}\right)^{o p}\left(d^{i_{1}}\right)^{o p} \cdots\left(d^{i_{r}}\right)^{o p}
$$

where $0 \leq i_{1} \leq \cdots \leq i_{r} \leq m$ and $0 \leq j_{1} \leq \cdots \leq j_{s} \leq m$.
This corollary means that a simplicial object $F: \Delta^{o p} \rightarrow \mathscr{C}$ can be uniquely determined by the images of objects $F_{i}=F([i])$, face maps $d_{i}$ and degeneracy maps $s_{i}$ so long as they meet the simplicial identities corresponding to (3.1) - (3.3),

$$
\begin{align*}
& d_{i} d_{j}=d_{j-1} d_{i}  \tag{3.7}\\
& d_{i} s_{j}=\left\{\begin{array}{cl}
s_{j-1} d_{i} & \text { if } i<j \\
\text { id } i<j \\
s_{j} d_{i-1} & \text { if } i=j \text { or } i=j+1 \\
s_{i} s_{j}=s_{j+1} s_{i} & \text { if } i \leq j+1
\end{array}\right. \tag{3.8}
\end{align*}
$$

Since a simplicial map $f: F \rightarrow G$ is a natural transformation between simplicial objects, it can simply be checked that

$$
d_{i} f=f d_{i} \quad \text { and } \quad s_{i} f=f s_{i}
$$

for every corresponding pair of face and degeneracy map of $F$ and $G$. Although simplicial objects will be the main focus of later sections, it will be helpful to first have an example of a particular cosimplicial object first.

### 3.1.2 Cosimplicial Objects

Definition 3.10: A cosimplicial object in a category $\mathscr{C}$ is a functor

$$
F: \Delta \rightarrow \mathscr{C}
$$

If $F$ and $G$ are cosimplicial objects in $\mathscr{C}$ then a cosimplicial map from $F$ to $G$ is a natural transformation

$$
\alpha: F \rightarrow G .
$$

Thus the cosimplicial objects in $\mathscr{C}$, together with the cosimplicial maps between them form a category. Moreover, let $d^{i}:[n-1] \rightarrow[n]$ be a coface map of $\Delta$ for $0 \leq i \leq n$. The map $d^{i}:=F\left(d^{i}\right)$ is called a coface map of $F$. Similarly, let $s^{i}:[n+1] \rightarrow[n]$ be a codegeneracy map of $\Delta$ for $0 \leq i \leq n$. The map $s^{i}:=F\left(s^{i}\right)$ is called a codegeneracy map of $F$.

Similarly, Proposition 3.4 implies that a cosimplicial object $F: \Delta \rightarrow \mathscr{C}$ can be uniquely determined by the images of objects $F_{i}=F([i])$, face maps $d^{i}$ and degeneracy maps $s^{i}$ meeting the cosimplicial identities (3.1) - (3.3). One example of a cosimplicial object that will appear several times in this thesis is the collection of topological $n$-simplices, $\Delta^{\bullet}$.

Example 3.11: The standard topological $n$-simplex is the space

$$
\Delta^{n}=\left\{\left(t_{0}, t_{1}, \ldots, t_{n}\right) \in \mathbb{R}^{n+1}: t_{0}, t_{1}, \cdots, t_{n} \geq 0, \sum_{i=0}^{n} t_{i}=1\right\}
$$

If we let $\left\{e_{0}, \ldots, e_{n}\right\}$ be the standard basis of $\mathbb{R}^{n+1}$, equivalently $\Delta^{n}$ is the convex hull of this basis. A map $\alpha:[m] \rightarrow[n]$ induces a unique linear map $\tilde{\alpha}: \Delta^{m} \rightarrow \Delta^{n}$ determined by

$$
\tilde{\alpha}\left(e_{i}\right)=e_{\alpha(i)} .
$$

We can also explicitly define the coface and codegeneracy maps which, as mentioned in 3.1.1, will uniquely determine a functor $F: \Delta^{o p} \rightarrow \mathscr{C}$. The $n$-simplex can be canonically embedded in the ( $n+1$ )-simplex by defining coface maps $d^{i}: \Delta^{n} \rightarrow \Delta^{n+1}$ for every $0 \leq i \leq n$, which maps the $n$-simplex into the ' $i$ th boundary component' by

$$
d^{i}\left(t_{0}, \ldots, t_{n}\right)=\left(t_{0}, \ldots, t_{i-1}, 0, t_{i}, \ldots, t_{n}\right) .
$$

Note that the $n$-simplex has $n+1$ vertices where the $i^{t h}$ vertex is at $t_{i}=1, t_{j}=0$ for $j \neq i$. There are then codegeneracy maps $s^{i}: \Delta^{n} \rightarrow \Delta^{n-1}$ which 'collapse the $i^{\text {th }}$ vertex' defined by

$$
s^{i}\left(t_{0}, \ldots, t_{n}\right)=\left(t_{0}, \ldots, t_{i-1}, t_{i}+t_{i+1}, t_{2} \ldots, t_{n}\right) .
$$

With the coface and codegeneracy maps thus defined, it becomes apparent that $\Delta^{\bullet}=\left\{\Delta^{n}\right\}_{n \geq 0}$ is a cosimplicial object by defining a functor $F: \Delta \rightarrow$ Top by the obvious assignment

$$
F([n])=\Delta^{n}, \quad F\left(d^{i}\right)=d^{i}, \quad F\left(s^{i}\right)=s^{i},
$$

and noting that the maps satisfy the cosimplicial identities (3.1) - (3.3).

### 3.1.3 Simplicial Objects

The following construction of the cosimplicial object $\Delta^{\bullet}$ leads naturally to the singular simplicial set and singular homology. Let $X$ be a topological space and define a singular $n$-simplex $\sigma$ to be a continuous map from the topological $n$-simplex into $X$,

$$
\sigma: \Delta^{n} \rightarrow X
$$

Denote the set of all singular $n$-simplices of $X$ by $S_{n}(X)$. Note that there are natural face and degeneracy maps on the family of sets $\left\{S_{n}(X)\right\}_{n \geq 0}$ induced by the coface and codegeneracy maps on $\Delta^{\bullet}$. Namely, for an $n$-simplex $\sigma$, we define the face maps $d_{i}: S_{n}(X) \rightarrow S_{n-1}(X)$ by the composition

$$
\begin{equation*}
d_{i}(\sigma)=\sigma \circ d^{i}: \Delta^{n-1} \rightarrow X \in S_{n-1}(X) \tag{3.12}
\end{equation*}
$$

and respectively define the degeneracy maps $s_{i}: S_{n}(X) \rightarrow S_{n+1}(X)$ by the composition

$$
\begin{equation*}
s_{i}(\sigma)=\sigma \circ s^{i}: \Delta^{n+1} \rightarrow X \in S_{n+1}(X) \tag{3.13}
\end{equation*}
$$

for every $0 \leq i \leq n$. One checks that these satisfy the simplicial identities (3.7) - (3.9). Denote the family of sets $\left\{S_{n}(X)\right\}_{n \geq 0}$ together with face and degeneracy maps the singular simplicial set of a topological space $X$, which can be thought of as a functor

$$
S_{\bullet}(X): \Delta^{o p} \rightarrow \text { Set. }
$$

Letting $\sigma: \Delta^{n} \rightarrow X$ be an $n$-simplex of $X$, a continuous map $f: X \rightarrow Y$ induces a map on the simplicial set $S(f): S_{n}(X) \rightarrow S_{n}(Y)$ for each $n \geq 0$ by

$$
S(f) \sigma=f \circ \sigma: \Delta^{n} \rightarrow Y
$$

For an $n$-simplex of $X$, it is a simple calculation to check that

$$
\begin{aligned}
d_{i}(S(f) \sigma) & =d_{i}(f \sigma) \\
& =f \sigma d^{i} \\
& =f\left(d_{i} \sigma\right) \\
& =S(f)\left(d_{i} \sigma\right)
\end{aligned}
$$

and similarly for the degeneracy maps; thus $S(f)$ is a simplicial map. Leaving the categorical definition behind, we offer an alternative definition of a simplicial set.

Definition 3.14: $A$ simplicial set $X_{\bullet}$ is a family of sets $X_{\bullet}=\left\{X_{q}\right\}_{q \geq 0}$ together with face operators $d_{i}: X_{q} \rightarrow X_{q-1}$ and degeneracy operators $s_{i}: X_{q} \rightarrow X_{q+1}, i=0,1, \ldots, q$, such that
the identities (3.7) - (3.9) hold.

$$
\begin{aligned}
& d_{i} d_{j}=d_{j-1} d_{i} \\
& d_{i} s_{j}=\left\{\begin{array}{cl}
s_{j-1} d_{i} & \text { if } i<j \\
\text { id } & \text { if } i=j \text { or } i=j+1 . \\
s_{j} d_{i-1} & \text { if } i>j+1 .
\end{array}\right. \\
& s_{i} s_{j}=s_{j+1} s_{i} \quad \text { if } i \leq j .
\end{aligned}
$$

A map of simplicial sets $f: X_{\bullet} \rightarrow Y_{\bullet}$ is then defined to be a sequence of functions $\left\{f_{q}: X_{q} \rightarrow\right.$ $\left.Y_{q}\right\}_{q \geq 0}$ such that they commute with the face and degeneracy operators. That is, $f_{q} d_{i}=d_{i} f_{q+1}$ and $f_{q+1} s_{i}=s_{i} f_{q}$ for every $q \geq 0$. The collection of simplicial sets forms the category of simplicial sets which we will denote $s$ Set.

Remark 3.15: We may also take $X_{\bullet}$ to be a family of topological spaces, manifolds, groups, etc and replace the face and degeneracy maps with the appropriate morphisms - continuous maps, smooth maps, homomorphisms, etc respectively.

Proposition 3.16: The category sSet of simplicial sets is equal to the category of functors $F: \Delta^{o p} \rightarrow$ Set.

Proof. Let $X_{\bullet}=\left\{X_{q}\right\}_{q \geq 0}$ be a simplicial set. In Corollary 3.6 we saw that any map $\mu^{o p}:[n]^{o p} \rightarrow$ $[m]^{o p}$ in the category $\Delta^{o p}$ can be decomposed uniquely into the map $\left(s^{j_{t}}\right)^{o p} \cdots\left(s^{j_{1}}\right)^{o p}\left(d^{i_{1}}\right)^{o p} \cdots\left(d^{i_{r}}\right)^{o p}$. Then define a functor $F: \Delta^{o p} \rightarrow$ Set such that

$$
F([q])=X_{q}, \quad F\left([n] \xrightarrow{\mu^{o p}}[m]\right)=s_{j_{t}} \cdots s_{j_{1}} d_{i_{1}} \cdots d_{i_{r}}: X_{n} \rightarrow X_{m} .
$$

Conversely, by using identities (3.7) - (3.9) that any combination of face and degeneracy maps on the simplicial set $X_{\bullet}$, say $\nu: X_{n} \rightarrow X_{m}$, may also be rearranged such that

$$
\nu=s_{j_{t}} \cdots s_{j_{1}} d_{i_{1}} \cdots d_{i_{r}} .
$$

Now let $Y_{\bullet}=\left\{Y_{q}\right\}_{q \geq 0}$ be a simplicial set associated to the functor $G: \Delta^{o p} \rightarrow$ Set and suppose we have a map $f: X_{\bullet} \rightarrow Y_{\bullet}$. Necessarily the diagrams

commute for all $q \geq 0$. This can be rewritten in the language of functors, in which case the diagrams become

after which it becomes clear that $f: X_{\bullet} \rightarrow Y_{\bullet}$ can be realised as a natural transformation between functors $f: F \rightarrow G$ since we can write all morphisms in the simplicial category $\Delta$ as a combination of the face and degeneracy maps.

Denote the free vector space of singular $n$-simplices over $\mathbb{R}$ by $C_{n}(X)$. That is, a general element of $C_{n}(X)$, or a singular n-chain, will be a finite formal sum of elements

$$
\sum_{i} c_{i} \sigma_{i} \in C_{n}(X)
$$

for $n$-simplices $\sigma_{i}$ and coefficients $c_{i} \in \mathbb{R}$. We define the face and degeneracy maps to be the linear extensions of $d_{i}, s_{i}$ (i.e. (3.12), (3.13)) on the formal sums of $n$-simplices. Let Vect $\mathbb{R}_{\mathbb{R}}$ denote the category of vector spaces over $\mathbb{R}$, whose morphisms are linear maps. One notes that the family of vector spaces $C_{\bullet}(X)=\left\{C_{n}(X)\right\}_{n \geq 0}$ can thus be thought of as a functor

$$
F: \Delta^{o p} \rightarrow \operatorname{Vect}_{\mathbb{R}}
$$

We call $C \bullet(X)$ the singular simplicial chain complex of the topological space, $X$. Since a continuous map $f: X \rightarrow Y$ induces a map $S(f): C_{\bullet}(X) \rightarrow C_{\bullet}(Y)$, the linear extension $f_{\#}: C_{\bullet}(X) \rightarrow C_{\bullet}(X)$ is a simplicial map. That is, given a singular $n$-chain $\sum_{i} c_{i} \sigma_{i}$, define

$$
f_{\#} \sum_{i} c_{i} \sigma_{i}=\sum_{i} c_{i} S(f) \sigma_{i}
$$

We recall (e.g. [Hat01]) that there is a differential operator

$$
\partial_{n}: C_{n}(X) \rightarrow C_{n-1}(X)
$$

sometimes called the boundary operator, such that an $n$-simplex is sent to the sum of its boundary components and $\partial_{n} \partial_{n+1}=0$. This boundary operator can be constructed using the face maps by

$$
\partial_{n}=\sum_{i=0}^{n}(-1)^{i} d_{i}
$$

One checks that using the relation in (3.7)

$$
\begin{aligned}
\partial_{n} \partial_{n+1} & =\sum_{i, j}(-1)^{i+j} d_{i} d_{j} \\
& =\sum_{i<j}(-1)^{i+j} d_{j-1} d_{i}+\sum_{j \leq i}(-1)^{i+j} d_{i} d_{j} \\
& =\sum_{q<p+1}(-1)^{p+q+1} d_{p} d_{q}+\sum_{j \leq i}(-1)^{i+j} d_{i} d_{j} \\
& =0
\end{aligned}
$$

since $q<p+1$ is equivalently restated as $q \leq p$ and sums over the same integers.
If $M$ is a manifold, one may also consider a smooth $n$-simplex on $M$ to be a smooth map

$$
\sigma: \Delta^{n} \rightarrow M
$$

One may also consider the subspace $S_{\bullet}^{\infty}(M) \subset S_{\bullet}(M)$ of smooth singular simplices on $M$ and hence $C_{\bullet}^{\infty}(M) \subset C_{\bullet}(M)$ the smooth singular chains on $M$. By the Whitney Approximation Theorem any singular simplex is homotopic to a smooth singular simplex and the inclusion

$$
C_{n}^{\infty}(M) \rightarrow C_{n}(M)
$$

is an isomorphism in homology of chain complexes (see [Lee02, Theorem 16.6] for further details). By dualising the singular complex $C_{n}(X)$ one obtains the set of singular n-cochains $C^{n}(X)$ whose elements are maps

$$
\epsilon: C_{n}(X) \rightarrow \mathbb{R}
$$

These vector spaces naturally carry face maps $d^{i}: C^{n}(X) \rightarrow C^{n+1}$ by the precomposition

$$
d^{i} \epsilon=\epsilon \circ d_{i}
$$

and degeneracy maps

$$
s^{i} \epsilon=\epsilon \circ s_{i} .
$$

Similarly, $C^{n}(X)$ is endowed with a natural differential operator $d: C^{n}(X) \rightarrow C^{n+1}(X)$ given by

$$
d=\sum_{i=0}^{n}(-1)^{i} d^{i}
$$

for each $n \geq 0$. For any topological space, one defines the cohomology of $X$ with real coefficients by the sequence of cohomology groups $H^{n}(X)$ where

$$
H^{n}(X)=\frac{\operatorname{ker} d \cap C^{n}(X)}{\operatorname{im} d \cap C^{n}(X)}
$$

in the usual way (e.g. [Hat01]). Let $M$ be a manifold and $C_{\infty}^{n}(M)$ denote the subspace of smooth singular cochains from dualising $C_{n}(X)$. The Whitney Approximation Theorem tells us that there is an isomorphism

$$
H^{n}(M) \cong \frac{\operatorname{ker} d \cap C_{\infty}^{n}(M)}{\operatorname{im} d \cap C_{\infty}^{n}(M)}
$$

which we will use later in a proof of de Rham's theorem.

### 3.1.4 The Nerve of a Category

Definition 3.17: Let $\mathscr{C}$ be a category with objects $\operatorname{Ob}(\mathscr{C})$, morphisms $\operatorname{Hom}(\mathscr{C})$ and denote $\operatorname{Hom}(\mathscr{C}) \circ \operatorname{Hom}(\mathscr{C})$ by the class of pairs of composable morphisms. $A$ topological category $\mathscr{C}$ is a category where $\mathrm{Ob}(\mathscr{C})$ and $\operatorname{Hom}(\mathscr{C})$ are both topological spaces and

- The source map $S: \operatorname{Hom}(\mathscr{C}) \rightarrow \mathrm{Ob}(\mathscr{C}), S(A \rightarrow B)=A$, is continuous,
- the target map $T: \operatorname{Hom}(\mathscr{C}) \rightarrow \mathrm{Ob}(\mathscr{C}), T(A \rightarrow B)=B$, is continuous and
- composition $C: \operatorname{Hom}(\mathscr{C}) \circ \operatorname{Hom}(\mathscr{C}) \rightarrow \operatorname{Hom}(\mathscr{C}), C(f, g)=g \circ f$, is continuous where $A, B \in \operatorname{Ob}(\mathscr{C})$ and $f, g \in \operatorname{Hom}(\mathscr{C})$ with $T(f)=S(g)$.

Let $\mathscr{C}$ be a topological category. The nerve of the category $\mathscr{C}, N \mathscr{C}_{\bullet}=\left\{N \mathscr{C}_{i}\right\}_{i \geq 0}$, is the simplicial space where $N \mathscr{C}_{0}=\operatorname{Ob}(\mathscr{C}), N \mathscr{C}_{1}=\operatorname{Hom}(\mathscr{C})$ and for $n>1$

$$
N \mathscr{C}_{n}=\operatorname{Hom}(\mathscr{C}) \circ \cdots \circ \operatorname{Hom}(\mathscr{C}) \quad(\mathrm{n} \text { times })
$$

is the subset of $n$ composable morphisms in $\mathscr{C}$. For example, consider the string of morphisms

$$
A_{n+1} \xrightarrow{f_{n}} A_{n} \xrightarrow{f_{n-1}} \cdots \xrightarrow{f_{2}} A_{2} \xrightarrow{f_{1}} A_{1} .
$$

Then $\left(f_{1}, \ldots, f_{n}\right)$ is an element of $N \mathscr{C}_{n}$. We define face maps $d_{i}: N \mathscr{C}_{n} \rightarrow N \mathscr{C}_{n-1}$ by

$$
d_{i}\left(f_{1}, \ldots, f_{n}\right)= \begin{cases}\left(f_{2}, \ldots, f_{n}\right) & \text { if } i=0  \tag{3.18}\\ \left(f_{1}, \ldots, f_{i} \circ f_{i+1}, \ldots, f_{n}\right) & \text { if } 0<i<n \\ \left(f_{1}, \ldots, f_{n-1}\right) & \text { if } i=n\end{cases}
$$

and degeneracy maps $s_{i}: N \mathscr{C}_{n} \rightarrow N \mathscr{C}_{n+1}$ for $i=0, \ldots, n$ by

$$
\begin{equation*}
s_{i}\left(f_{1}, \ldots, f_{n}\right)=\left(f_{1}, \ldots, f_{i-1}, \operatorname{id}_{A_{i}}, f_{i}, \ldots, f_{n}\right) \tag{3.19}
\end{equation*}
$$

where $X=S\left(f_{i}\right)=T\left(f_{i-1}\right)$.
Remark 3.20: If $\mathscr{C}, \mathscr{D}$ are topological categories, then there is a natural notion of a continuous functor from $\mathscr{C}$ to $\mathscr{D}$. The topological categories and continuous functors between them form a category $\mathrm{Cat}_{T}$. Note that one may consider the nerve $N: \mathrm{Cat}_{T} \rightarrow$ Top as a functor. For a continuous functor $F: \mathscr{C} \rightarrow \mathscr{D}, N F: N \mathscr{C}_{\bullet} \rightarrow N \mathscr{D} \bullet$ is a simplicial map of simplicial topological spaces.

We finish this subsection with an example of a simplicial object that will become ubiquitous in the rest of this thesis.

Example 3.21: A topological group $G$ can be considered a topological category where the only object is the group itself endowed with the trivial topology, $\operatorname{Ob}(G)=\{G\}$, and the morphisms are multiplication by group elements, $\operatorname{Hom}(G)=G$ endowed with the topology of the group. That is, the only object is the group itself and the morphisms of the group are the group elements, $g \in G$.


Since every pair of morphisms in $G$ is composable, $\operatorname{Hom}(G) \circ \operatorname{Hom}(G)=G \times G$ and moreover, the nerve of this category $N G$ is the simplicial space where $N G_{0}$ is the single object $\{G\}$ (treated as a point) and in general

$$
N G_{n}=G^{n}=G \times G \times \cdots \times G \quad(n \text { times })
$$

Explicitly, the face maps $d_{i}: N G_{n} \rightarrow N G_{n-1}$ are

$$
d_{i}\left(g_{1}, \ldots, g_{n}\right)= \begin{cases}\left(g_{2}, \ldots, g_{n}\right) & \text { if } i=0  \tag{3.22}\\ \left(g_{1}, \ldots, g_{i} g_{i+1}, \ldots, g_{n}\right) & \text { if } 0<i<n \\ \left(g_{1}, \ldots, g_{n-1}\right) & \text { if } i=n\end{cases}
$$

and the degeneracy maps $s_{i}: N G_{n} \rightarrow N G_{n+1}$ are

$$
\begin{equation*}
s_{i}\left(g_{1}, \ldots, g_{n}\right)=\left(g_{1}, \ldots, g_{i-1}, 1, g_{i}, \ldots, g_{n}\right) \tag{3.23}
\end{equation*}
$$

Perhaps more naturally, one may also consider a topological group as a category $\bar{G}$ whose objects are the group elements, $\mathrm{Ob}(\bar{G})=G$, endowed with the topology of the group and whose morphisms are the maps $\operatorname{Hom}(\bar{G})=\{g \rightarrow h: g, h \in G\}=G \times G$ endowed with the product topology. We could think of a map $g \rightarrow h$ between elements of $G$ as a pair $(h, g)$ to make this clearer.


Two morphisms $g \rightarrow h$ and $g^{\prime} \rightarrow h^{\prime}$ with $h=g^{\prime}$ may be composed

$$
(g \rightarrow h) \circ\left(g^{\prime} \rightarrow h^{\prime}\right)=g \rightarrow h^{\prime} .
$$

Phrasing this in the pair notation, two pairs $(h, g)$ and $\left(h^{\prime}, g^{\prime}\right)$ with $h=g^{\prime}$ may be composed $\left(h^{\prime}, g^{\prime}\right) \circ(h, g)=\left(h^{\prime}, g\right)$. In this way, an element $g_{0} \rightarrow g_{1} \rightarrow g_{2}$ of $\operatorname{Hom}(\bar{G}) \circ \operatorname{Hom}(\bar{G})$ can be thought of as a triple $\left(g_{2}, g_{1}, g_{0}\right)$. Explicitly, the face maps $d_{i}: N \bar{G}_{n} \rightarrow N \bar{G}_{n-1}$ are

$$
\begin{equation*}
d_{i}\left(g_{0}, \ldots, g_{n}\right)=\left(g_{0}, \ldots, g_{i-1} g_{i}, \ldots, g_{n}\right) \tag{3.24}
\end{equation*}
$$

and the degeneracy maps $s_{i}: N \bar{G}_{n} \rightarrow N \bar{G}_{n+1}$ are

$$
\begin{equation*}
s_{i}\left(g_{0}, \ldots, g_{n}\right)=\left(g_{0}, \ldots, g_{i-1}, g_{i}, g_{i}, \ldots, g_{n}\right) . \tag{3.25}
\end{equation*}
$$

Consider the functor $\Gamma: \bar{G} \rightarrow G$ where $\gamma(g)=G$ for every $g \in G$ and

$$
\operatorname{Hom}(\bar{G}) \ni(h, g) \stackrel{\Gamma}{\longmapsto} h g^{-1} \in \operatorname{Hom}(G) .
$$

Clearly the functor is continuous and hence $N \Gamma$ is a simplicial map under the nerve. Specifically, the simplicial map $\gamma=N \Gamma: N \overline{G_{\bullet}} \rightarrow N G_{\bullet}$ is the collection of maps $\left\{\gamma_{n}: G^{n+1} \rightarrow G^{n}\right\}_{n \geq 0}$ where

$$
\gamma_{n}\left(g_{0}, \ldots, g_{n}\right)=\left(g_{0} g_{1}^{-1}, g_{1} g_{2}^{-1}, \ldots, g_{n-1} g_{n}^{-1}\right)
$$

In fact, this is a simplicial principal $G$-bundle in the sense of the following definition.
Definition 3.26: Let $G$ be a Lie group. A simplicial principal $G$ bundle $P_{\bullet} \rightarrow B_{\mathbf{0}}$ is a family of principal $G$-bundles $P_{\bullet}=\left\{P_{q}\right\}_{q \geq 0}$ together with face bundle maps $d_{i}: P_{q} \rightarrow P_{q-1}$ and degeneracy bundle maps $s_{i}: P_{q} \rightarrow P_{q+1}, i=0,1, \ldots, q$, such that the identities (3.7) - (3.9) hold.

$$
\begin{aligned}
& d_{i} d_{j}=d_{j-1} d_{i} \\
& d_{i} s_{j}=\left\{\begin{array}{cl}
s_{j-1} d_{i} & \text { if } i<j . \\
\text { id } & \text { if } i=j \text { or } i=j+1 . \\
s_{j} d_{i-1} & \text { if } i>j+1 .
\end{array}\right. \\
& s_{i} s_{j}=s_{j+1} s_{i} \\
& \text { if } i \leq j .
\end{aligned}
$$

### 3.1.5 Geometric Realisation

In this thesis, simplicial methods will be used to prove cohomological results. Since cohomology is a topological property there will be machinery needed to relate a simplicial object to a topological space. In the paper [Mil57], Milnor introduced the notion of geometric realisation which assigned a topological space to a simplicial set.

Definition 3.27: Let $X_{\bullet}=\left\{X_{n}\right\}_{n \geq 0}$ be a simplicial space. The geometric realisation of $X$ is the topological space

$$
\left|X_{\bullet}\right|=\coprod_{n \geq 0} X_{n} \times \Delta^{n} / \sim
$$

where, for $x \in X_{n}, t \in \Delta^{n-1}$, we have the identification

$$
\left(d_{i} x, t\right) \sim\left(x, d^{i} t\right)
$$

and for $x \in X_{n}, t \in \Delta^{n+1}$, we have the identification

$$
\left(s_{i} x, t\right) \sim\left(x, s^{i} t\right)
$$

The definition of geometric realisation above may also be extended to all simplicial sets by endowing them with the discrete topology.

Proposition 3.28: Geometric realisation, $|-|: s$ Top $\rightarrow$ Top, is a functor.
Proof. Clearly for $X_{\bullet}=\left\{X_{n}\right\}_{n \geq 0}$ a simplicial space $\left|X_{\bullet}\right|$ is a topological space. Consider $f: X_{\bullet} \rightarrow Y_{\bullet}$ a family of maps $\left\{f_{n}: X_{n} \rightarrow Y_{n}\right\}_{n \geq 0}$. The map $|f|:\left|X_{\bullet}\right| \rightarrow\left|Y_{\bullet}\right|$ is the map

$$
[x, t] \mapsto[f(x), t]
$$

where $[x, t]$ denotes an equivalence class in $\left|X_{\bullet}\right|$. This is well defined because $f: X_{\bullet} \rightarrow Y_{\bullet}$, being a map of simplicial spaces, commutes with the face and degeneracy operators. From this construction it is immediately clear that $\left|\operatorname{id}_{X_{\bullet}}\right|=\operatorname{id}_{\left|X_{\bullet}\right|}:\left|X_{\bullet}\right| \rightarrow\left|X_{\bullet}\right|$.
Now let $Y=\left\{Y_{n}\right\}_{n \geq 0}, Z=\left\{Z_{n}\right\}_{n \geq 0}$ be simplicial sets and $f, g$ be simplicial maps

$$
X_{\bullet} \xrightarrow{f} Y_{\bullet} \xrightarrow{g} Z_{\bullet} .
$$

First we need to show that given $f: X_{\bullet} \rightarrow Y_{\bullet},|f|:\left|X_{\bullet}\right| \rightarrow\left|Y_{\bullet}\right|$ is continuous. First consider the diagram

where $\tilde{f}(x, t)=(f(x), t)$. A set $U$ is open in $\left|Y_{\bullet}\right|$ if and only if there is an open set

$$
\tilde{U} \subset \coprod_{n \geq 0} Y_{n} \times \Delta^{n}
$$

that is sent to $U$ under the quotient topology. Then, for an open set $U \subset\left|Y_{\bullet}\right|$,

$$
|f|^{-1}(U)=\left\{[x, t] \in\left|X_{\bullet}\right|:[f(x), t] \in U\right\}
$$

is open if and only if

$$
\tilde{f}^{-1}(U)=\left\{(x, t) \in\left|X_{\bullet}\right|:(f(x), t) \in U\right\}
$$

is open in $\coprod_{n \geq 0} X_{n} \times \Delta^{n}$. Since $f$ is a map of simplicial spaces, $\tilde{f}^{-1}(U)$ will be open in the product topology and hence $|f|:\left|X_{\bullet}\right| \rightarrow\left|Y_{\bullet}\right|$ is a continuous map. Finally,

$$
\begin{aligned}
|g \circ f|[x, t] & =[(g \circ f)(x), t] \\
& =[g(f(x)), t] \\
& =|g|[f(x), t] \\
& =(|g| \circ|f|)[x, t] .
\end{aligned}
$$

Hence $|g \circ f|=|g| \circ|f|$.
In Dupont's monograph [Dup78] he uses the fat realisation. There will be more exposition comparing these two topological constructions in Section 4.1.2.

Definition 3.29: Let $X_{\bullet}=\left\{X_{n}\right\}_{n \geq 0}$ be a simplicial space. The fat realisation of $X_{\bullet}$ is the topological space

$$
\left\|X_{\bullet}\right\|=\coprod_{n \geq 0} X_{n} \times \Delta^{n} / \sim
$$

where, for $x \in X_{n}, t \in \Delta^{n-1}$, we have the identification

$$
\left(d_{i} x, t\right) \sim\left(x, d^{i} t\right)
$$

Corollary 3.30: Fat realisation, $\|-\|: s \mathrm{Top} \rightarrow$ Top, is a functor.
Proof. This proof immediately follows from Proposition 3.28.
For the following theorems regarding the geometric realisation of products require that we must restrict ourselves to the category $\mathcal{U}$ of compactly generated Hausdorff spaces. Specifically we turn our attention to the category $\mathcal{S U}$, a subcategory of $\mathcal{S}$ Top, whose objects are functors

$$
F: \Delta^{o p} \rightarrow \mathcal{U}
$$

For more details, the reader is directed to [May72, Ch. 11].
Theorem 3.31: Let $X_{\bullet}, Y_{\bullet}$ be simplicial spaces in the category $\mathcal{S U}$. Then there is a homeomorphism

$$
\left|X_{\bullet} \times Y_{\bullet}\right| \rightarrow\left|X_{\bullet}\right| \times\left|Y_{\bullet}\right| .
$$

Proof. The reader is directed to [May72, Theorem 11.5] for a proof of this statement.
Corollary 3.32: Let $f: X_{\bullet} \rightarrow B_{\bullet}$ and $p: Y_{\bullet} \rightarrow B_{\bullet}$ be maps in the category $\mathcal{S U}$. Then $\left|X_{\bullet} \times{ }_{B_{\bullet}} Y_{\bullet}\right|$ is naturally homeomorphic to $\left|X_{\bullet}\right| \times_{\left|B_{\bullet}\right|}\left|Y_{\bullet}\right|$ via the map

$$
\left|p_{X}\right| \times\left|p_{Y}\right|:\left|X_{\bullet} \times_{B_{\bullet}} Y_{\bullet}\right| \rightarrow\left|X_{\bullet}\right| \times_{\left|B_{\bullet}\right|}\left|Y_{\bullet}\right|
$$

where $p_{X}, p_{Y}$ are the projections onto $X_{\bullet}, Y_{\bullet}$ respectively.
Proof. The reader is directed to [May72, Corollary 11.6] for a proof of this statement.
Example 3.33: As Segal illustrates in [Seg68], if $X \bullet$ is a simplicial space its geometric realisation $\left|X_{0}\right|$ has a natural filtration

$$
\left|X_{\bullet}\right|_{0} \subset\left|X_{\bullet}\right|_{1} \subset\left|X_{\bullet}\right|_{2} \subset \cdots \subset\left|X_{\bullet}\right|
$$

where $\left|X_{\bullet}\right|_{i}$ is the image of $\Delta^{i} \times X_{i}$ in $\left|X_{\bullet}\right|$. Applying this to the simplicial principal $G$-bundle

$$
N \bar{G}_{\bullet} \xrightarrow{\gamma} N G_{\bullet}
$$

one obtains the natural filtration below.


One can also 'reverse engineer' the geometric realisation of a simplicial space $X$ • given enough data. Since the geometric realisation is a gluing along degeneracies and faces, the space $\left|X_{\bullet}\right|_{n}$ can be built from $\left|X_{\bullet}\right|_{n-1}$, the space $\Delta^{n} \times X_{n}$ and the gluing instructions. The gluing instructions for the faces are contained in the image of

$$
\partial \Delta^{n} \times X_{n}
$$

and the gluing instructions for the degeneracies are contained in the image of

$$
\Delta^{n-1} \times \bigcup_{i=0}^{n} s_{i}\left(X_{n}\right) .
$$

We will be referring to the union of the sets $s_{i}\left(X_{n}\right)$ with some frequency and so the notation

$$
\begin{equation*}
s\left(X_{n}\right)=\bigcup_{i=0}^{n} s_{i}\left(X_{n}\right) \tag{3.34}
\end{equation*}
$$

will be adopted for clarity and brevity. The construction alluded to above is best described in the following proposition.

Proposition 3.35: If $X_{\bullet}$. is a simplicial space, the following diagram is a pushout diagram of topological spaces.


Proof. The reader is directed to [May74, Theorem A.4] or [GJ99, Proposition 1.7, Ch. VII] for a proof of this statement.

### 3.2 A Simplicial Construction of the Universal Bundle

In section 2.1.2 equivariant cohomology of a topological space $X$ with right $G$-action was defined as the singular cohomology of the quotient

$$
H^{*}((X \times E G) / G)
$$

where $E G$ is any model for the universal $G$-bundle. The following section will motivate a model for the universal bundle constructed via a simplicial principal $G$-bundle. The advantage of this model will be that the model for the universal bundle, which is typically not a smooth principal $G$-bundle, will be built from a sequence of smooth principal $G$-bundles which preserve cohomological properties under geometric realisation. This section will primarily focus on the construction of $E G \rightarrow B G$ which will then be used extensively in the last chapter.

### 3.2.1 Basic Properties of $\left|N \bar{G}_{\bullet}\right|$

Let $G$ be a topological group and $X$ be a topological space with right $G$-action. The space

$$
X \times_{X / G} X \subset X \times X
$$

is the set of pairs $(x, y) \in X \times X$ such that $x=y \cdot g$ for some $g \in G$. We say that the action of $G$ on $X$ is strongly free if there is a continuous function $\tau: X \times_{X / G} X \rightarrow G$ satisfying

$$
\begin{equation*}
y=x \cdot \tau(x, y) . \tag{3.36}
\end{equation*}
$$

Example 3.37: Let $G$ act on itself by right multiplication. Then for any $g, h \in G$, clearly

$$
\tau(g, h)=g^{-1} h .
$$

This map is clearly continuous since the inverse map and right multiplication map are both continuous on a topological group.

Lemma 3.38: Let $G$ be a topological group. Then the action of $G$ is strongly free on the space $\left|N \bar{G}_{\bullet}\right|$.

Proof. Firstly note that since $N \bar{G}_{\boldsymbol{\bullet}}$ is the total space of the simplicial principal $G$-bundle over $N G_{\bullet}$, we may associate the orbits of $N \bar{G}_{n}$ with the space $N G_{n}$. The action of $G$ on the space $N \bar{G}_{n}$ is clearly strongly free for every $n \geq 0$. Specifically, there is a map

$$
\tau_{n}: N \bar{G}_{n} \times_{N G_{n}} N \bar{G}_{n} \rightarrow G
$$

that satisfies Equation 3.36. In fact, this defines a simplicial map

$$
\tau: N \bar{G}_{\bullet} \times_{N G}, N \bar{G}_{\bullet} \rightarrow G
$$

since the face and degeneracy maps are equivariant. Taking geometric realisation, there is a continuous map

$$
|\tau|:\left|N \bar{G}_{\bullet} \times N G_{\bullet} N \bar{G}_{\bullet}\right| \rightarrow G
$$

and by Corollary 3.32 , there is a homeomorphism induced by the respective projections

$$
\left|N \bar{G}_{\bullet} \times_{N G_{\bullet}} N \bar{G}_{\bullet}\right| \xrightarrow{\sim}\left|N \bar{G}_{\bullet}\right| \times_{\left|N G_{\bullet}\right|}\left|N \bar{G}_{\bullet}\right|
$$

which completes the proof.
In order to show $\left|N \bar{G}_{\bullet}\right|$ is contractible, we will use the following theorem without proof. For a complete proof of this fact, the reader is directed to [Eng89, p. 151].

Theorem 3.39: For every locally compact space $X$ and any quotient mapping $g: Y \rightarrow Z$, the Cartesian product $f=\operatorname{id}_{X} \times g: X \times Y \rightarrow X \times Z$ is a quotient mapping.

Lemma 3.40: The space $\left|N \overline{G_{\bullet}}\right|$ is contractible.
Proof. Let $\left[g_{0}, \ldots, g_{n} ; u_{0}, \ldots, u_{n}\right]$ denote an equivalence class in $N \bar{G} \bullet$ with $g_{i} \in G$ and $\left(u_{0}, \ldots, u_{n}\right) \in$ $\Delta^{n}$. Let $h:\left|N \bar{G}_{\bullet}\right| \times I \rightarrow\left|N \bar{G}_{\bullet}\right|$ be the homotopy

$$
h\left(\left[g_{0}, \ldots, g_{n} ; u_{0}, \ldots, u_{n}\right], t\right)=\left[1, g_{0}, \ldots, g_{n} ; t,(1-t) u_{0}, \ldots,(1-t) u_{n}\right] .
$$

Note that by the construction of $h$,

$$
\begin{aligned}
h\left(\left[g_{0}, \ldots, g_{n} ; u_{0}, \ldots, u_{n}\right], 0\right) & =\left[1, g_{0}, \ldots, g_{n} ; d^{0}\left(u_{0}, \ldots, u_{n}\right)\right] \\
& =\left[g_{0}, \ldots, g_{n} ; u_{0}, \ldots, u_{n}\right]
\end{aligned}
$$

and also

$$
\begin{aligned}
h\left(\left[g_{0}, \ldots, g_{n} ; u_{0}, \ldots, u_{n}\right], 1\right) & =\left[1, g_{0}, \ldots, g_{n} ; d^{n} \cdots d^{1}(1)\right] \\
& =[1 ; 1] .
\end{aligned}
$$

It is perhaps easiest to show that the homotopy $h$ is continuous by noting that it lifts to a continuous map

$$
\tilde{h}: \coprod_{n \geq 0} G^{n+1} \times \Delta^{n} \times I \rightarrow \coprod_{n \geq 0} G^{n+1} \times \Delta^{n}
$$

given by the obvious choice of lift, for $\left(g_{0}, \ldots, g_{n} ; u_{0}, \ldots, u_{n}\right) \in \coprod_{n \geq 0} G^{n+1} \times \Delta^{n}$ and $t \in I$,

$$
\tilde{h}\left(\left(g_{0}, \ldots, g_{n} ; u_{0}, \ldots, u_{n}\right), t\right)=\left(1, g_{0}, \ldots, g_{n} ; t,(1-t) u_{0}, \ldots,(1-t) u_{n}\right)
$$

Consider the commutative diagram below.

$$
\begin{aligned}
& \coprod_{n \geq 0} \Delta^{n} \times G^{n+1} \times I \xrightarrow{\tilde{h}} \underset{n \geq 0}{\amalg} \Delta^{n} \times G^{n+1} \\
&\left.\left\lvert\, \begin{array}{ll} 
\\
q \times \operatorname{id}_{I} & \\
& \\
& \left|N \bar{G}_{\bullet}\right| \times I \xrightarrow{l} \\
& h
\end{array}\right.\right)\left|N \bar{G}_{\bullet}\right|
\end{aligned}
$$

The space $I$ is locally compact so by Theorem 3.39 the map $q \times \mathrm{id}_{I}$ is a quotient map and thus an open mapping. Hence, for an open set $U \subset\left|N \bar{G}_{\bullet}\right|$,

$$
h^{-1}(U)=\left(q \times \operatorname{id}_{I} \circ \tilde{h}^{-1} \circ q^{-1}\right)(U)
$$

which is clearly open and thus $h$ is continuous.
Lemma 3.41: Under the quotient of a topological group $G$ there is a homeomorphism

$$
\left|N \bar{G}_{\bullet}\right| / G \cong\left|N G_{\bullet}\right|
$$

Proof. Define $\gamma_{n}: G^{n+1} \rightarrow G^{n}$ by the map

$$
\begin{equation*}
\gamma_{n}\left(g_{0}, \ldots, g_{n}\right)=\left(g_{0} g_{1}^{-1}, \ldots, g_{n-1} g_{n}^{-1}\right) \tag{3.42}
\end{equation*}
$$

and note that the collection of maps $\left\{\gamma_{n}\right\}_{n \geq 0}=: \gamma: N \bar{G}_{\bullet} \rightarrow N G_{\bullet}$ is a map of simplicial manifolds. Moreover, $\gamma$ is equivariant since

$$
\begin{aligned}
\gamma_{n}\left(\left(g_{0}, \ldots, g_{n}\right) \cdot h\right) & =\gamma_{n}\left(\left(g_{0} h, \ldots, g_{n} h\right)\right) \\
& =\left(g_{0} h\left(g_{1} h\right)^{-1}, \ldots, g_{n-1} h\left(g_{n} h\right)^{-1}\right) \\
& =\gamma_{n}\left(g_{0}, \ldots, g_{n}\right)
\end{aligned}
$$

for every $n \geq 0$ and every $h \in G$. The map $\gamma$ descends to a map

$$
\gamma_{G}: N \bar{G}_{\bullet} / G \rightarrow N G_{\bullet}
$$

under the identifications of the quotient by $G$ since it is a $G$-invariant map. Moreover, we define a map $\psi_{G}: N G_{\bullet} \rightarrow N \bar{G}_{\bullet} / G$ defined by the collection of maps

$$
\psi_{n}\left(g_{1}, \cdots, g_{n}\right)=\left[g_{1} g_{2} \cdots g_{n}, g_{2} g_{3} \cdots g_{n}, \ldots, g_{n}, 1\right] .
$$

Notice that $\psi_{G}$ is a simplicial map and a continuous inverse to $\gamma_{G}$. Since $\gamma_{G}$ and $\psi_{G}$ are simplicial maps, they descend again to continuous maps under geometric realisation and we thus have shown that

$$
\left|N \bar{G}_{\bullet} / G\right| \cong\left|N G_{\bullet}\right| .
$$

To show that $\left|N \bar{G}_{\bullet} / G\right|=\left|N \bar{G}_{\bullet}\right| / G$ it suffices to note that for $x \in N \bar{G}_{\bullet},|x| \in\left|N \bar{G}_{\bullet}\right|$ its corresponding equivalence class and any $g \in G$

$$
|x \cdot g|=|x| \cdot g .
$$

Hence, we have shown that $\left|N \bar{G}_{\bullet}\right| / G=\left|N \bar{G}_{\bullet} / G\right| \cong N G_{\bullet}$.

### 3.2.2 Principal Bundles and Local Trivialisations

Lemma 3.43: Let $G$ be a topological group and $X$ be a topological space with strongly free $G$ action. Then $X \xrightarrow{\pi} X / G$ is a trivial bundle if and only if $\pi: X \rightarrow X / G$ has a continuous section.

Proof. Suppose $\pi: X \rightarrow X / G$ is a trivial bundle. That is, there is a homeomorphism $\varphi: X \rightarrow$ $(X / G) \times G$ such that the induced map on base spaces $X / G \rightarrow X / G$ is the identity. Let $[x]$ denote the equivalence class in $X / G$ such that $\pi(x)=[x]$. There is an obvious choice of section for the bundle $(X / G) \times G \rightarrow(X / G), s:(X / G) \rightarrow(X / G) \times G$ given by

$$
s([x])=([x], e)
$$

after which we note that $\varphi \circ s:(X / G) \rightarrow X$ is also a continuous global section.
Now suppose instead that $\pi: X \rightarrow X / G$ has a continuous section, $s: X / G \rightarrow X$. Since $G$ is a strongly free action, there is a continuous map $\tau: X^{*} \rightarrow G$ and another map $Q: X \rightarrow(X / G) \times G$ defined by

$$
Q(x)=([x], \tau(s([x]), x)) .
$$

Note that $Q$ is an equivariant homeomorphism with continuous inverse defined by

$$
Q^{-1}([x], g)=s([x]) \cdot g .
$$

Thus $X \cong(X / G) \times G$ and $X \xrightarrow{\pi} X / G$ is a trivial bundle.
Corollary 3.44: Let $G$ be a topological group and $X$ be a topological space with strongly free $G$-action. Then $X \xrightarrow{\pi} X / G$ is a Principal $G$-bundle if and only if $\pi: X \rightarrow X / G$ has continuous local sections.

Proof. Consider $U_{i} \subset X / G$. It follows from the above lemma that local sections $s_{i}: U_{i} \rightarrow$ $\pi^{-1}\left(U_{i}\right)$ correspond to trivialisations of $\pi^{-1}\left(U_{i}\right)$ since $G$ is strongly free on $\pi^{-1}\left(U_{i}\right)$.

Lemma 3.45: Let $G$ be a group and $X$ be a topological set with right $G$-action. If $U$ is a $G$-stable subset of $X$ then an equivariant map

$$
f: U \rightarrow G
$$

is equivalent to a local section $s: U / G \rightarrow U$.
Proof. Suppose there exists such a map $f: U \rightarrow G$ and let [ $u$ ] be an equivalence class in $U / G$. Define the map $s: U / G \rightarrow U$ by

$$
s[u]=u \cdot f(u)^{-1} .
$$

The map is well defined since for any representative $u \cdot g \in[u]$,

$$
\begin{aligned}
s[u \cdot g] & =u \cdot g \cdot f(u \cdot g)^{-1} \\
& =u \cdot g \cdot(f(u) \cdot g)^{-1} \\
& =u \cdot f(u)^{-1} .
\end{aligned}
$$

Remark 3.46: Note that the converse of this lemma is true when the action of $G$ is strongly free.

### 3.2.3 The Homotopy Extension Property and NDR Pairs

Definition 3.47: Let $(X, A)$ be a pair of spaces with $A \stackrel{i}{\hookrightarrow} X$. We say that $(X, A)$ has the Homotopy Extension Property (HEP), or that A has the HEP with respect to $X$, if for every map $F: X \rightarrow Y$ and for every homotopy $h: A \times I \rightarrow Y$ such that $h(a, 0)=F \circ i(a)$ there exists a map

$$
H: X \times I \rightarrow Y
$$

such that $H \circ(i \times 1)=h$ and $H(x, 0)=F(x)$.
If we let $i_{0}(x)=(x, 0)$ we can rephrase this definition by requiring that there exists a map $H$ that makes the diagram below commute.


The following theorem of Palais leads to a great number of examples of pairs $(X, A)$ that have the HEP.

Theorem 3.48: Let $X$ be a metrisable manifold and let $A$ be a closed subspace of $X$ which is also a manifold. Then $(X, A)$ has the HEP.

Proof. The reader is directed to [Pal65, Theorem 6] for a proof of this statement.
Remark 3.49: If $G$ is a Lie group then this theorem implies that ( $G,\{1\}$ ) has the HEP.
Lemma 3.50 (Pasting Lemma): Let $X, Y$ be closed subspaces of a topological space $A=X \cup Y$. If a function $f: A \rightarrow B$ is continuous when restricted to both $X$ and $Y$, then $f$ is continuous.

Proof. Let $C$ be a closed subset of $B$. Then since $f$ is continuous when restricted to $\mathrm{X}, f^{-1}(C) \cap X$ is closed and similarly $f^{-1}(C) \cap Y$ is closed. Then the set

$$
f^{-1}(C)=\left(f^{-1}(C) \cap X\right) \cup\left(f^{-1}(C) \cap Y\right)
$$

is also closed, hence $f: A \rightarrow B$ is continuous.
Proposition 3.51: Let $X$ be a topological space and $A \subset X$ be a closed subspace. The pair of spaces $(X, A)$ has the HEP if and only $A \times I \cup X \times\{0\}$ is a retract of $X \times I$.

Proof. Suppose $A \times I \cup X \times\{0\}$ is a retract of $X \times I$ with retraction

$$
r: X \times I \rightarrow A \times I \cup X \times\{0\} .
$$

If there is a map $F: X \rightarrow Y$ and a homotopy $h: A \times I \rightarrow Y$ such that $F \circ i=h \circ i_{0}$ then we define a new function $g: A \times I \cup X \times\{0\} \rightarrow Y$ where

$$
g(x, t)=\left\{\begin{array}{ll}
F(x) & \text { if } t=0 \\
h(x, t) & \text { if } t \neq 0
\end{array} .\right.
$$

The function $g$ is well defined since $x \in A$ if $t \neq 0$ and continuous by the previous pasting lemma. Then we may define a homotopy $H=g \circ r: X \times I \rightarrow Y$.

Now suppose $(X, A)$ has the HEP. Then by letting $F: X \rightarrow A \times I \cup X \times\{0\}$ be the function

$$
F(x)=(x, 0)
$$

and the homotopy $h: A \times I \rightarrow A \times I \cup X \times\{0\}$ be the inclusion

$$
h(a, t)=(a, t)
$$

there is a function $H: X \times I \rightarrow A \times I \cup X \times\{0\}$ such that $\left.H\right|_{A \times I}=h$ and $H(x, 0)=F(x)$. Note that $H$ is precisely a retract of $X \times I$ since

$$
H(a, t)=h(a, t)=(a, t)
$$

for every $(a, t) \in A \times I$.

Example 3.52: For any $n \geq 1$, consider the pair ( $D^{n}, S^{n-1}$ ) where

$$
D^{n}=\left\{x \in \mathbb{R}^{n}:|x| \leq 1\right\}
$$

and $S^{n-1}=\partial D^{n}$. We wish to find a retraction $r: D^{n} \times I \rightarrow D^{n} \times\{0\} \cup S^{n-1} \times I$. First, embed $D^{n} \times I \hookrightarrow D^{n} \times \mathbb{R}$ and fix a point $N=(x, t) \in D^{n} \times \mathbb{R}$ where $x$ is in the interior of $D^{n}$ and $t>1$. Then for any point $M=(y, s) \in D^{n} \times I$ consider the straight line $L$ passing through $N$ and $(y, s)$. Then define $r(M)$ to be the point

$$
r(M)=L \cap\left(D^{n} \times\{0\} \cup S^{n-1} \times I\right)
$$

One may check that this map is well defined, continuous and the identity on

$$
D^{n} \times\{0\} \cup S^{n-1} \times I,
$$

hence a retraction. Thus, the pair $\left(D^{n}, S^{n-1}\right)$ has the HEP. Since the topological $n$-simplex is homeomorphic to $D^{n}$, and similarly its boundary is homeomorphic to $S^{n-1}$, we may conclude that the pair ( $\Delta^{n}, \partial \Delta^{n}$ ) has the HEP.

Definition 3.53: A pair $(X, A)$ is a neighbourhood deformation retract pair, or an NDR pair, if there is a map $u: X \rightarrow I$ such that $u^{-1}(0)=A$ and a homotopy $h: X \times I \rightarrow X$ such that:

- $h(-, 0)=\mathrm{id}_{X}$,
- $h(a, t)=a$ for all $a \in A, t \in I$ and
- $h(x, 1) \in A$ if $u(x)<1$.

We say an NDR pair $(X, A)$ is a deformation retract pair, or a DR pair, if $u(x)<1$ for all $x \in X$.

The following three results are proven in [May99] but first proved by Puppe in [Pup67].
Proposition 3.54: Let $(X, A)$ and $(Y, B)$ be NDR pairs. Then

$$
(X \times Y, A \times Y \cup X \times B)
$$

is an NDR pair. Moreover, if $(X, A)$ or $(Y, B)$ is a DR pair, then

$$
(X \times Y, A \times Y \cup X \times B)
$$

is a DR pair.
The proof is technical and will be omitted for brevity, but the reader is referred to [May99, p. 45] for a complete proof.

Corollary 3.55: Let $X$ be a topological space and $A \subset X$ a closed subspace. Then $(X, A)$ is an $N D R$ pair if and only if $A \times I \cup X \times\{0\}$ is a retract of $X \times I$.

Proof. This follows from the fact that $(I,\{0\})$ is a DR pair. This is shown by letting $u=\operatorname{id}_{I}$ and $h: I \times I \rightarrow I$ be defined by

$$
h(s, t)=t(1-s)
$$

Thus, from the proposition above, $(X \times I, A \times I \cup X \times\{0\})$ is a DR pair with homotopy $k:(X \times I) \times I \rightarrow X \times I$. Then there is a retraction $r: X \times I \rightarrow A \times I \cup X \times\{0\}$ given by

$$
r(x, t)=k((x, t), 1)
$$

Now suppose there is a retraction $r: X \times I \rightarrow A \times I \cup X \times\{0\}$. Let $p_{X}: X \times I \rightarrow X$ and $p_{I}: X \times I \rightarrow I$ be the projections and define $u: X \rightarrow I$ by

$$
u(x)=\sup \left\{t-\left(p_{I} \circ r\right)(x, t): t \in I\right\}
$$

and $h: X \times I \rightarrow X$ by

$$
h(x, t)=p_{X} \circ r(x, t)
$$

Then $h(-, 0)=\operatorname{id}_{X}, h(a, t)=a$ for all $a \in A, t \in I$ and $h(x, 1) \in A$ if $u(x)<1$. We observe that $u^{-1}(0) \supset A$ since if $a \in A$ then

$$
p_{I}(a, t)=p_{I} r(a, t) \Longrightarrow t=p_{I} r(a, t) \text { for every } t \in I
$$

Suppose $x \in X \backslash A$. Since $r$ is continuous there is a neighbourhood $V$ of $x$ and an $\epsilon>0$ such that $r(V \times[0, \epsilon)) \subset X \times\{0\}$. But then if $(x, t) \in V \times(0, \epsilon), p_{I}(x, t)>p_{I} r(x, t)$ in which case $u(x)>0$.

Corollary 3.56: Let $X$ be a topological space and $A \subset X$ be a closed subspace. Then $(X, A)$ has the HEP if and only if it is an NDR pair.

This corollary means that for a Lie group $G,(G,\{1\})$ is an NDR pair. We will use this fact in conjunction with the following lemma.

Lemma 3.57: If $(X, A)$ is an $N D R$ pair then there is an open set $U \subset X$ such that $A \subset U$ and there is a retraction

$$
r: U \rightarrow A
$$

Proof. Recall that since $(X, A)$ is an NDR pair, there is a continuous map $u: X \rightarrow I$ and a homotopy $h: X \times I \rightarrow X$ satisfying certain properties. By taking $\epsilon \in(0,1]$ and letting

$$
U=u^{-1}((0, \epsilon))
$$

there is a retraction $r: U \rightarrow A$ given by $r(x)=h(x, 1)$ for every $x \in U$.

### 3.2.4 Constructing Local Sections

We are particularly interested in $s\left(N G_{n}\right)$ which, by Equation 3.34 , is the space

$$
s\left(N G_{n}\right)=\bigcup_{i=0}^{n+1} s_{i}\left(N G_{n}\right)=\bigcup_{i=0}^{n+1} G^{i} \times\{1\} \times G^{n-i} .
$$

The pair $\left(N G_{n+1}, s\left(N G_{n}\right)\right)$ has the HEP by Theorem 3.48 and hence is an NDR pair by Corollary 3.56. Also note the space

$$
s\left(N \bar{G}_{n}\right)=\bigcup_{i=0}^{n+1} s_{i}\left(N \bar{G}_{n}\right)
$$

contains elements $\left(g_{0}, \ldots, g_{n}\right)$ where $g_{i}=g_{i+1}$ for some $i=0,1, \ldots, n-1$. Since $\left(N G_{n+1}, s\left(N G_{n}\right)\right)$ and ( $\Delta^{n+1}, \partial \Delta^{n+1}$ ) are both NDR pairs, Proposition 3.54 and Corollary 3.56 implies that

$$
\begin{equation*}
\left(\Delta^{n+1} \times N G_{n+1}, \partial \Delta^{n+1} \times N G_{n+1} \cup \Delta^{n+1} \times s\left(N G_{n+1}\right)\right) \tag{3.58}
\end{equation*}
$$

has the HEP. Moreover, we have a pullback diagram

and hence both vertical maps are the projections of trivial principal $G$-bundles. Because of this, we have equivariant homeomorphisms

$$
\varphi: \Delta^{n+1} \times N \bar{G}_{n+1} \xrightarrow{\sim}\left(\Delta^{n+1} \times N G_{n+1}\right) \times G
$$

and

$$
\varphi^{\prime}: \partial \Delta^{n+1} \times N \bar{G}_{n+1} \cup \Delta^{n+1} \times s\left(N G_{n+1}\right) \xrightarrow{\sim}\left(\partial \Delta^{n+1} \times N G_{n+1} \cup \Delta^{n+1} \times s\left(N G_{n+1}\right)\right) \times G
$$

Since the pair in Equation 3.58 is an NDR pair, Lemma 3.57 implies that there is an open set $U \subset \Delta^{n+1} \times N G_{n+1}$ and a retraction

$$
\begin{equation*}
r: U \rightarrow \partial \Delta^{n+1} \times N G_{n+1} \cup \Delta^{n+1} \times s\left(N G_{n+1}\right) \tag{3.59}
\end{equation*}
$$

Let $V=\gamma_{n+1}^{-1}(U)$ and notice that this set is $G$-stable. We may construct an equivariant retraction

$$
\begin{equation*}
\rho: V \rightarrow \partial \Delta^{n+1} \times N \bar{G}_{n+1} \cup \Delta^{n+1} \times s\left(N \bar{G}_{n+1}\right) \tag{3.60}
\end{equation*}
$$

defined by

$$
\rho=\varphi^{\prime-1} \circ(r \times 1) \circ \varphi
$$

Since the maps $\varphi^{\prime-1},(r \times 1), \varphi$ are equivariant, so too is the map $\rho$. We first start by constructing the $G$-stable open set $U_{0} \subset\left|N \bar{G}_{\bullet}\right|_{0}=\Delta^{0} \times G$ and equivariant map $h_{0}: U_{0} \rightarrow G$. This is clearly achieved by letting $U_{0}=\left|N \bar{G}_{\bullet}\right|_{0}$ and projecting onto $G$,

$$
h_{0}(t, g)=g
$$

Now, assume inductively that we have a $G$-stable set $U_{n} \subset\left|N \bar{G}_{\bullet}\right|_{n}$ and an equivariant map $h_{n}: U_{n} \rightarrow G$. Note that there is a map

$$
\partial \Delta^{n+1} \times N \bar{G}_{n+1} \cup \Delta^{n+1} \times s\left(N \bar{G}_{n+1}\right) \xrightarrow{m_{n}}\left|N \bar{G}_{\bullet}\right|_{n}
$$

where

$$
\begin{aligned}
& m_{n}\left(d^{i} t ; g_{0}, \ldots, g_{n}\right)=\left[t ; g_{0}, \ldots, \hat{g}_{i}, \ldots, g_{n}\right] \& \\
& m_{n}\left(t ; g_{0}, \ldots, g_{i}, g_{i}, \ldots, g_{n}\right)=\left[t ; g_{0}, \ldots, g_{i}, g_{i+1}, \ldots, g_{n}\right]
\end{aligned}
$$

which is clearly a continuous equivariant map. Hence, the set

$$
W_{n}=m_{n}^{-1}\left(U_{n}\right) \subset \partial \Delta^{n+1} \times N \bar{G}_{n+1} \cup \Delta^{n+1} \times s\left(N \bar{G}_{n+1}\right)
$$

is a $G$-stable set. That is, since $U_{n}$ is $G$-stable, and for $w \in W_{n}, m(w \cdot g)=m(w) \cdot g \in U_{n}$ and therefore, $w \cdot g \in W_{n}$. By Equation 3.60, there is a $G$-equivariant retraction from an open set $A \subset \Delta^{n+1} \times N \bar{G}_{n+1}$ to $\partial \Delta^{n+1} \times N \bar{G}_{n+1} \cup \Delta^{n+1} \times s\left(N \bar{G}_{n+1}\right)$

$$
r: A \rightarrow \partial \Delta^{n+1} \times N \bar{G}_{n+1} \cup \Delta^{n+1} \times s\left(N \bar{G}_{n+1}\right)
$$

Hence, the retraction may be restricted to the set $W_{n}$ by letting $V_{n}=r^{-1}\left(W_{n}\right) \subset \Delta^{n} \times N \bar{G}_{n+1}$

$$
r_{n}=\left.r\right|_{V_{n}}: V_{n} \rightarrow W_{n}
$$

Hence, we have a $G$-equivariant function $k_{n}=h_{n} \circ m_{n} \circ r_{n}: V_{n} \rightarrow G$. Then let $U_{n+1}=V_{n} \cup_{W_{n}} U_{n}$ be the pushout and $h_{n+1}: U_{n+1} \rightarrow G$ be the unique map defined by the diagram below.


It follows that $U_{n+1}$ is $G$-stable since $U_{n}$ and $V_{n}$ are $G$-stable and $h_{n+1}: U_{n+1} \rightarrow G$ is equivariant since $k_{n}$ and $h_{n}$ are equivariant. Finally, the set $U_{n+1}$ can naturally be thought of as a subset of $\left|N \bar{G}_{\bullet}\right|_{n+1}$ and is open since both $U_{n}$ and $V_{n}$ are open. Thus, we have proven the proposition.

Proposition 3.61: Let $G$ be a topological group. Then

$$
\left|N \bar{G}_{\bullet}\right| \xrightarrow{|\gamma|}\left|N G_{\bullet}\right|
$$

is a principal G-bundle with contractible total space.
A proof that $\left|N \bar{G}_{\bullet}\right| \rightarrow\left|N G_{\bullet}\right|$ is numerable can be found in [Dol63] and hence Proposition 3.61 yields a model for the universal bundle $E G \rightarrow B G$.

Let $G$ be a Lie group and $M$ be a manifold with right $G$-action. Note that $M$ can be turned into a simplicial manifold $M_{\bullet}$ by letting $M_{q}=M$ for every $q \geq 0$ and setting each face and degeneracy map to the identity

$$
d_{i}=\operatorname{id}_{M}: M_{n} \rightarrow M_{n-1}, s_{i}=\operatorname{id}_{M}: M_{n} \rightarrow M_{n+1}
$$

for every $0 \leq i \leq n$. It is simple to check that $\left|M_{\bullet}\right|=M$ in this case. If $P_{\bullet} \rightarrow B_{\bullet}$ is a simplicial principal $G$-bundle then, as a slight abuse of notation, we will write $P_{\bullet} \times M$ instead of $P_{\bullet} \times M_{\bullet}$ and the corresponding simplicial principal $G$-bundle as

$$
P_{\bullet} \times M \rightarrow P_{\bullet} \times{ }_{G} M
$$

where we define $P_{\bullet} \times{ }_{G} M:=\left(P_{\bullet} \times M\right) / G$ for simpler notation.
Corollary 3.62: Let $G$ be a Lie group and $M$ be a manifold with right $G$-action. Then

$$
\left|N \bar{G}_{\bullet} \times M\right|=E G \times M
$$

and moreover

$$
\left|N \bar{G} \bullet \times_{G} M\right|=(E G \times M) / G
$$

Proof. This is simply application of Theorem 3.31 to Proposition 3.61.

## Chapter 4

## Simplicial Equivariant de Rham Theory

### 4.1 Dupont's Simplicial de Rham Theorem

### 4.1.1 The Double Complex of a Simplicial Space

As seen in Chapter 3, associated to every topological space $X$ there is a singular cochain complex $C^{*}(X)$. For any simplicial topological space $X_{\bullet}$ there is thus a sequence of associated singular cochain complexes $C^{*}\left(X_{p}\right)$. The face maps $d_{i}: X_{p} \rightarrow X_{p-1}$ for $0 \leq i \leq p$ of $X_{\bullet}$ induce coface maps $d_{i}^{\#}: C^{*}\left(X_{p-1}\right) \rightarrow C^{*}\left(X_{p}\right)$ from which we can construct a differential $\delta: C^{*}\left(X_{p-1}\right) \rightarrow$ $C^{*}\left(X_{p}\right)$ by defining

$$
\begin{equation*}
\delta=\sum_{i=0}^{p}(-1)^{i} d_{i}^{\#} \tag{4.1}
\end{equation*}
$$

and noting that (3.7) - (3.9) implies that $\delta^{2}=0$ in keeping with the calculation in Section 3.1.3. So, for a fixed $p \geq 0$ we obtain a cochain complex $C^{q}\left(X_{\bullet}\right)$. Since we have two differential operators on $C^{p, q}\left(X_{\bullet}\right):=C^{q}\left(X_{p}\right)$ we have a double complex $\left(C^{p, q}\left(X_{\bullet}\right), d, \delta\right)$ which can be drawn diagrammatically as

in which every square commutes. If $M_{\bullet}$ is a simplicial manifold, there is also a de Rham complex $\Omega^{*}\left(M_{p}\right)$ associated to every $M_{p}$ and $p \geq 0$. The face and degeneracy maps on $M_{\bullet}$ induce face and degeneracy maps on $\Omega^{*}\left(M_{p}\right)$ and once again we define a 'horizontal' differential

$$
\begin{equation*}
\delta=\sum_{i=0}^{p}(-1)^{i} d_{i}^{*}: \Omega^{*}\left(M_{p}\right) \rightarrow \Omega^{*}\left(M_{p+1}\right) \tag{4.2}
\end{equation*}
$$

such that we obtain a cochain complex $\Omega^{q}\left(M_{\bullet}\right)$ for a fixed $q \geq 0$. Clearly the differential operators $d$ and $\delta$ commute (as pullbacks commute through $d$ ) so in the same way we define $\Omega^{p, q}\left(M_{\bullet}\right):=\Omega^{q}\left(M_{p}\right)$ and define the associated double complex $\left(\Omega^{p, q}\left(M_{\bullet}\right), d, \delta\right)$.


Let $\left(B^{*, *}, d_{B}, \delta_{B}\right),\left(C^{*, *}, d_{C}, \delta_{C}\right)$ be two double complexes. A morphism of double complexes or chain map is a homomorphism $f: B^{*, *} \rightarrow C^{*, *}$ such that

$$
f \circ d_{B}=d_{C} \circ f \text { and } f \circ \delta_{B}=\delta_{C} \circ f
$$

Associated to every double complex $\left(B^{*, *}, d, \delta\right)$ is the total complex whose elements of degree $n$ are

$$
\operatorname{Tot}^{n}(B)=\bigoplus_{p+q=n} B^{p, q}
$$

Since $d, \delta$ commute

$$
\begin{equation*}
D=\delta+(-1)^{p} d: \bigoplus_{p+q=n} B^{p, q} \rightarrow \bigoplus_{p+q=n} B^{p, q} \tag{4.3}
\end{equation*}
$$

naturally defines a differential operator on $\operatorname{Tot}^{*}(B)$. Note that a map of double complexes $f: B^{*, *} \rightarrow C^{*, *}$ determines a chain map $f: \operatorname{Tot}^{*}(B) \rightarrow \operatorname{Tot}^{*}(C)$ since

$$
f \circ\left(\delta+(-1)^{p} d\right)=\left(\delta+(-1)^{p} d\right) \circ f
$$

Thus, to each double complex we may associate cohomology groups where the $n^{\text {th }}$ cohomology group is defined to be

$$
H_{\mathrm{Tot}}^{n}(B):=H^{n}\left(\operatorname{Tot}^{*}(B)\right)=\frac{\operatorname{ker} D \cap \operatorname{Tot}^{n}(B)}{\operatorname{im} D \cap \operatorname{Tot}^{n}(B)}
$$

and a map of double complexes induces a map $f^{*}: H_{\mathrm{Tot}}^{n}(B) \rightarrow H_{\mathrm{Tot}}^{n}(C)$. The classical result of de Rham's gives us a result about the singular and de Rham cohomology groups of a manifold $M$.

Theorem 4.4 (de Rham's Theorem): Let $M$ be a manifold and define the map $I(-): \Omega^{q}(M) \rightarrow$ $C_{\infty}^{q}(M) b y$

$$
I(\omega)(\sigma)=\int_{\Delta^{q}} \sigma^{*} \omega
$$

where $\omega \in \Omega^{q}(M)$ and $\sigma: \Delta^{q} \rightarrow M$ is a smooth map. It is clear that $I(\omega)$ extends linearly to $a$ singular cochain in $C_{\infty}^{q}(M)$. Then the map I induces an isomorphism of cohomology groups

$$
H^{n}\left(\Omega^{*}(M)\right) \cong H^{n}\left(C^{*}(M)\right)
$$

for every non-negative integer $n$.
We refer the reader to [Lee02] or [Dup78] for the proof of this theorem. For a simplicial manifold $M_{\bullet}$, we thus have the following application.

Corollary 4.5: Let $M_{\bullet}$ be a simplicial manifold and consider the map $I(-): \Omega^{q}\left(M_{p}\right) \rightarrow$ $C_{\infty}^{q}\left(M_{p}\right)$ defined by

$$
I(\omega)(\sigma)=\int_{\Delta^{q}} \sigma^{*} \omega
$$

where $\omega \in \Omega^{q}\left(M_{p}\right)$ and $\sigma: \Delta^{q} \rightarrow M_{p}$ is a smooth map. Then the map I induces an isomorphism of cohomology groups

$$
H^{n}\left(\Omega^{p, *}\left(M_{\bullet}\right)\right) \cong H^{n}\left(C^{p, *}\left(M_{\bullet}\right)\right)
$$

for every non-negative integer $n$ and $p$.

Lemma 4.6: Let $B^{*, *}, C^{*, *}$ be two double chain complexes and $f: B^{*, *} \rightarrow C^{*, *}$ be a chain map of double complexes. Then $f$ restricts to a chain map on columns

$$
f_{p}: B^{p, *} \rightarrow C^{p, *}
$$

If $f_{p}$ induces an isomorphism $H^{*}\left(B^{p, *}\right) \cong H^{*}\left(C^{p, *}\right)$ for every $p \geq 0$ then $f$ induces an isomorphism

$$
H_{\mathrm{Tot}}^{*}(B) \cong H_{\mathrm{Tot}}^{*}(C)
$$

Proof. The reader is directed to Proposition 9.13 in [BT82] or Lemma 2.7.3 of [Wei94].
Letting $f: M \rightarrow N$ be a smooth map, it is a simple calculation to show that

$$
\begin{aligned}
I\left(f^{*} \omega\right)\left(\sum_{i} c_{i} \sigma_{i}\right) & =\sum_{i} c_{i} \int_{\Delta^{p}} \sigma_{i}^{*} f^{*} \omega \\
& =\sum_{i} c_{i} \int_{\Delta^{p}}\left(f \circ \sigma_{i}\right)^{*} \omega \\
& =I(\omega)\left(\sum_{i} c_{i}\left(f \circ \sigma_{i}\right)\right) \\
& =f^{\#} I(\omega)\left(\sum_{i} c_{i} \sigma_{i}\right)
\end{aligned}
$$

establishing that $I \circ f^{*}=f^{\#} \circ I$. In particular, this means that

$$
I \circ \delta=\delta \circ I
$$

which implies that $I$ is a map of double complexes and yields the following corollary of Theorem 4.4.

Corollary 4.7: The map I can be thought of as a map

$$
I: \Omega^{*, *}\left(M_{\bullet}\right) \rightarrow C^{*, *}\left(M_{\bullet}\right)
$$

that induces an isomorphism in cohomology

$$
H_{\text {Tot }}^{*}\left(\Omega^{*, *}\left(M_{\bullet}\right)\right) \cong H_{\text {Tot }}^{*}\left(C^{*, *}\left(M_{\bullet}\right)\right)
$$

### 4.1.2 Geometric Realisation of a Simplicial Manifold

The goal of this section is to show that the double complex $\Omega^{*, *}\left(M_{\bullet}\right)$ calculates the cohomology of the geometric realisation $\left|M_{\bullet}\right|$. Firstly we have the following result of Dupont.

Lemma 4.8: Let $X_{\bullet}=\left\{X_{p}\right\}_{p \geq 0}$ be a simplicial topological space. Then there is an isomorphism in cohomology

$$
H^{*}\left(\left\|X_{\bullet}\right\|\right) \cong H_{\mathrm{Tot}}^{*}\left(C^{*, *}\left(X_{\bullet}\right)\right) .
$$

Proof. The reader is directed to Proposition 5.15 in [Dup78].
Secondly, we observe that the work of Segal establishes a homotopy equivalence between the fat and geometric realisation under suitable conditions.

Definition 4.9: A simplicial space $X_{\bullet}$ is good if every inclusion

$$
s_{i}\left(X_{n}\right) \hookrightarrow X_{n+1}
$$

is a closed cofibration for every degeneracy map $s_{i}: X_{n} \rightarrow X_{n+1}$ and $n \geq 0$.
Lemma 4.10: Let $X_{\bullet}$ be a simplicial topological space. If $X_{\bullet}$ is good, then there is a homotopy equivalence

$$
\left\|X_{\bullet}\right\| \xrightarrow{\simeq}\left|X_{\bullet}\right| .
$$

Proof. The reader is directed to proposition A. 1 of Segal in [Seg72].
Remark 4.11: If the pairs $\left(X_{n+1}, s_{i}\left(X_{n}\right)\right)$ have the HEP and $s_{i}\left(X_{n}\right)$ is closed in $X_{n+1}$ for every $n \geq 0$ and $0 \leq i \leq n$ then $X$. is good.
Example 4.12: Let $G$ be a Lie group. Then the simplicial manifold $N \bar{G}_{\bullet}$ is good. The image of $s_{i}$ on $N \bar{G}_{n}$ is precisely

$$
s_{i}\left(G^{n+1}\right)=G^{i} \times\{1\} \times G^{n+1-i}
$$

as demonstrated in Chapter 3, which is clearly closed in $N \bar{G}_{n+1}$. It remains to show that the inclusion is a cofibration. This is also demonstrated in Chapter 3 since this is an NDR pair and hence a HEP pair. A pair $\left(s_{i}\left(N \bar{G}_{n}\right), N \bar{G}_{n+1}\right)$ has the HEP precisely when the inclusion is a cofibration.

It remains to show that a simplicial manifold is always good in order to prove the original stated goal of this section.

Lemma 4.13: A simplicial manifold $M_{\bullet}$ is good.
Proof. The reader is directed to [Pal65] for proof that if $M$ is a smooth manifold and $A \subset M$ is closed, then the pair $(M, A)$ has the HEP. Since $d_{i} s_{i}=\mathrm{id}$ and $s_{i} d_{i}: M_{n+1} \rightarrow s_{i}\left(M_{n}\right)$ is a retraction, the map

$$
s_{i}: M_{n} \rightarrow s_{i}\left(M_{n+1}\right)
$$

is a homeomorphism. Both $M_{n}, M_{n+1}$ are smooth manifolds and are thus completely metrizable. Combining these facts means that $s_{i}\left(M_{n}\right)$ is closed in $M_{n+1}$ since $M_{n}$ is closed. Hence $\left(M_{n+1}, s_{i}\left(M_{n}\right)\right)$ has the HEP, and $s_{i}\left(M_{n}\right)$ is closed for every $n \geq 0$ and $0 \leq i \leq n$ which completes the proof by Remark 4.11.

Theorem 4.14: Let $M_{\bullet}=\left\{M_{p}\right\}_{p \geq 0}$ be a simplicial manifold. Then there is an isomorphism in cohomology

$$
H^{*}\left(\left|M_{\bullet}\right|\right) \cong H_{\mathrm{Tot}}^{*}\left(\Omega^{*, *}\left(M_{\bullet}\right)\right)
$$

Proof. From Lemma 4.10 and Lemma 4.13 we have an isomorphism of cohomology

$$
H^{*}\left(\left|M_{\bullet}\right|\right) \cong H^{*}\left(\left\|M_{\bullet}\right\|\right)
$$

By also considering Lemma 4.8 and Lemma 4.7, the sequence of isomorphisms

$$
H^{*}\left(\left|M_{\bullet}\right|\right) \cong H^{*}\left(\left\|M_{\bullet}\right\|\right) \cong H_{\mathrm{Tot}}^{*}\left(C^{*, *}\left(M_{\bullet}\right)\right) \cong H_{\mathrm{Tot}}^{*}\left(\Omega^{*, *}\left(M_{\bullet}\right)\right)
$$

becomes apparent.

### 4.1.3 Simplicial Differential Forms

In the final section of Chapter 3 , we saw that we can build $M \times E G$ by taking the geometric realisation of a simplicial space $M \times N \bar{G}_{\bullet}$. In [Dup78], Dupont defines geometric objects called simplicial differential forms as a way of defining sequences of differential forms on simplicial spaces to approximate a de Rham complex for the topological fat realisation of a simplicial manifold $\left\|M_{\bullet}\right\|$.

Definition 4.15: Let $M_{\bullet}=\left\{M_{p}\right\}_{p \geq 0}$ be a simplicial manifold. A simplicial (differential) $q$-form $\omega_{\bullet}$ on $M_{\bullet}$ is a sequence of differential $q$-forms $\omega_{p} \in \Omega^{q}\left(\Delta^{p} \times M_{p}\right)$ such that

$$
\begin{equation*}
\left(d^{i} \times \mathrm{id}\right)^{*} \omega_{p+1}=\left(\mathrm{id} \times d_{i}\right)^{*} \omega_{p} \tag{4.16}
\end{equation*}
$$

for every $p \geq 0$ and $i=0,1, \ldots, p$. The vector space of simplicial $q$-forms will be denoted $A^{*}\left(M_{\bullet}\right)$. Moreover, the differential d on each complex $\Omega^{*}\left(\Delta^{p} \times M_{p}\right)$ commutes with pullbacks and so $A^{*}\left(M_{\bullet}\right)$ is naturally a complex with differential $d$.

The wedge product also commutes with pullbacks and so there is a natural wedge product defined on $A^{*}\left(M_{\bullet}\right)$,

$$
\wedge: A^{n}\left(M_{\bullet}\right) \otimes A^{m}\left(M_{\bullet}\right) \rightarrow A^{n+m}\left(M_{\bullet}\right)
$$

Let $M$ and $F$ be manifolds and $M \times F \rightarrow M$ be a trivial fibre bundle. If $F$ is compact, oriented and of dimension $k$, one may integrate along the fibre

$$
\int_{F}: \Omega^{q}(M \times F) \rightarrow \Omega^{q-k}(M)
$$

Consequently, there is a sensible notion of integrating a differential form $\omega_{p} \in \Omega^{q}\left(\Delta^{p} \times M_{p}\right)$ over $\Delta^{p}$ to be left with a differential form

$$
\int_{\Delta^{p}} \omega_{p} \in \Omega^{q-p}\left(M_{p}\right)
$$

For any simplicial differential form $\omega_{\bullet}=\left\{\omega_{p}\right\} \in A^{*}\left(M_{\bullet}\right)$, each differential form $\omega_{p}$ can be thought of as a sum

$$
\begin{equation*}
\omega_{p}=\sum_{k, l} \omega_{p}^{k, l} \tag{4.17}
\end{equation*}
$$

where $\omega_{p}^{k, l}$ is thought of loosely as a $k$-form on $\Delta^{p}$ and a l-form on $M_{p}$. This is in the sense that $\omega_{p}^{k, l}$ can locally be written in the form

$$
\omega_{p}^{k, l}=\sum f_{k, l} \cdot d t_{i_{1}} \cdots d t_{i_{k}} d \varphi_{j_{1}} \cdots d \varphi_{j_{k}}
$$

where $f: \Delta^{p} \times M \rightarrow \mathbb{R}$ and $\left\{t_{i}\right\},\left\{\phi_{i}\right\}$ are the local coordinates of $\Delta^{p}, M_{p}$ respectively. The decomposition of the simplicial form $\omega_{\bullet}$ in Equation 4.17 satisfies

$$
\sum_{k, l}\left(d^{i} \times \mathrm{id}\right)^{*} \omega_{p+1}^{k, l}=\sum_{k, l}\left(\mathrm{id} \times d_{i}\right)^{*} \omega_{p}^{k, l}
$$

for every $0 \leq i \leq p$ by Equation 4.16 and hence

$$
\left(d^{i} \times \mathrm{id}\right)^{*} \omega_{p+1}^{k, l}=\left(\mathrm{id} \times d_{i}\right)^{*} \omega_{p}^{k, l}
$$

for every $p \geq 0$ by linear independence.
Moreover, one defines a differential $d_{\Delta}: A_{\bullet}^{k, l}\left(M_{\bullet}\right) \rightarrow A_{\bullet}^{k+1, l}\left(M_{\bullet}\right)$ by restricting $d$ to the coordinates of $\Delta^{p}$ and $d_{M_{\bullet}}: A_{\bullet}^{k, l}\left(M_{\bullet}\right) \rightarrow A_{\bullet}^{k, l+1}\left(M_{\bullet}\right)$ by restricting $d$ to the coordinates on $M_{p}$. This means we have a natural decomposition of $A^{*}\left(M_{\bullet}\right)$ into a double complex $A^{k, l}\left(M_{\bullet}\right)$ and from construction it is clear that

$$
\operatorname{Tot}^{*}\left(A^{*, *}\left(M_{\bullet}\right)\right) \cong A^{*}\left(M_{\bullet}\right)
$$

Letting $\omega_{\bullet}=\left\{\omega_{p}\right\} \in A^{k, l}\left(M_{\bullet}\right)$ be a simplicial form, we have a map of double complexes $I_{\Delta}$ : $A^{k, l}\left(M_{\bullet}\right) \rightarrow \Omega^{k, l}\left(M_{\bullet}\right)$

$$
I_{\Delta} \omega_{\bullet}=\int_{\Delta^{k}} \omega_{k} \in \Omega^{l}\left(M_{k}\right)
$$

By Stokes' theorem and the identifications in Equation 4.16

$$
\begin{aligned}
I_{\Delta} d_{\Delta \omega_{\bullet}} & =\int_{\Delta^{k+1}} d_{\Delta^{k}} \omega_{k+1} \\
& =\int_{\partial \Delta^{k+1}} \omega_{k+1} \\
& =\sum_{i=0}^{k}(-1)^{i} \int_{\Delta^{k}}\left(d^{i} \times \mathrm{id}\right)^{*} \omega_{k+1} \\
& =\sum_{i=0}^{k}(-1)^{i} \int_{\Delta^{k}}\left(\mathrm{id} \times d_{i}\right)^{*} \omega_{k} \\
& =\sum_{i=0}^{k}(-1)^{i} d_{i}^{*} \int_{\Delta^{k}} \omega_{k}
\end{aligned}
$$

and hence $I_{\Delta} d_{\Delta}=\delta I_{\Delta}$. Also, it is easy for one to check

$$
I_{\Delta} d_{M}=d I_{\Delta}
$$

and thus $I_{\Delta}$ is a chain map.
Dupont also constructs a chain map of double complexes $E_{\Delta}: \Omega^{*, *}\left(M_{\bullet}\right) \rightarrow A^{*, *}\left(M_{\bullet}\right)$ where

$$
\begin{equation*}
E_{\Delta}(\omega)_{p}=p!\sum_{s=0}^{p}(-1)^{s} t_{i_{s}} d t_{i_{0}} \cdots d \hat{t}_{i_{s}} \cdots d t_{i_{p}} \wedge p_{M}^{*} \omega \tag{4.18}
\end{equation*}
$$

and $\omega_{\bullet}=\left\{E_{\Delta}(\omega)_{p}\right\}$ defines a simplicial differential form. The reader is directed to [Dup75] for more details on the map $E_{\Delta}$ in which he establishes the identity

$$
\begin{equation*}
I_{\Delta} \circ E_{\Delta}=\text { id. } \tag{4.19}
\end{equation*}
$$

An important theorem proved in [Dup78] is the following.
Theorem 4.20: Let $M_{\bullet}$ be a simplicial manifold. Then the maps $I_{\Delta}$ and $E_{\Delta}$ induce natural isomorphisms on cohomology

$$
H^{*}\left(A^{*}\left(M_{\bullet}\right)\right) \cong H_{\mathrm{Tot}}^{*}\left(\Omega^{*, *}\left(M_{\bullet}\right)\right) \cong H^{*}\left(\left|M_{\bullet}\right|\right) .
$$

### 4.2 Simplicial Chern-Weil Theory

### 4.2.1 Basic Simplicial Differential Forms

Let $G$ be a Lie group and suppose $M_{\bullet}$ is a simplicial manifold with right $G$-action

$$
\phi_{\bullet}: M_{\bullet} \times G \rightarrow M_{\bullet} .
$$

Letting $G$ act trivially on $\Delta^{p}$, there is a natural right action on each manifold $\Delta^{p} \times M_{p}$ and thus the de Rham complex $\Omega^{*}\left(\Delta^{p} \times M_{p}\right)$. Moreover, the simplicial identities (4.16) clearly commute with the action of $G$ and so $A^{*}\left(M_{\bullet}\right)$ inherits an action induced by $\phi_{\bullet}$,

$$
\phi_{A}: A^{*}\left(M_{\bullet}\right) \times G \rightarrow A^{*}\left(M_{\bullet}\right) .
$$

The complex $A^{*}\left(M_{\bullet}\right)$ inherits an action of the Lie algebra of $G, \mathfrak{g}$, in the usual sense too. That is, for a simplicial differential form $\omega_{\bullet} \in A^{k}\left(M_{\bullet}\right)$ and $\xi \in \mathfrak{g}$ we define an operator $\iota_{\xi}$ : $A^{k}\left(M_{\bullet}\right) \rightarrow A^{k-1}\left(M_{\bullet}\right)$ defined by

$$
\iota_{\xi} \omega_{\bullet}:=\left\{\iota \xi \omega_{n}\right\}_{n \geq 0} .
$$

To show this is a simplicial differential form, we will first prove the following lemma.

Lemma 4.21: Let $f: M \rightarrow N$ be an equivariant map between manifolds $M, N$ with right $G$ action with derivative $f_{*}: T M \rightarrow T N$. Let $X_{\xi} \in \mathfrak{X}(M)$ and $Y_{\xi} \in \mathfrak{X}(N)$ be the vector fields generated by the infinitesimal action of $\xi \in \mathfrak{g}$ on $M, N$ respectively. Then

$$
f_{*} X_{\xi}(x)=Y_{\xi}(f(x))
$$

for every $x \in M$ and every $\xi \in \mathfrak{g}$. Put diagrammatically, this square

commutes for every $\xi \in \mathfrak{g}$.
Proof. By definition of $X_{\xi}$, the left hand side of the equation is precisely

$$
f_{*} X_{\xi}(x)=\left.f_{*} \frac{d}{d t} \phi(x, \exp (t \xi))\right|_{t=0}
$$

where $\phi: M \times G \rightarrow M$ is the right action of $G$ on $M$. By the chain rule, this is precisely the derivative of the composition $t \mapsto f \circ \phi(x, \exp (t \xi))$ at $t=0$, hence

$$
f_{*} X_{\xi}(x)=\left.\frac{d}{d t} f \circ \phi(x, \exp (t \xi))\right|_{t=0}
$$

By equivariance, $f(x) \cdot g=f(x \cdot g)$ - or in the notation above $f \circ \phi(x, \exp (t \xi))=\phi(f(x), \exp (t \xi))$ - and hence

$$
f_{*} X_{\xi}(x)=\left.\frac{d}{d t} \phi(f(x), \exp (t \xi))\right|_{t=0}
$$

at which point it is noted that the right hand side is precisely the definition of $Y_{\xi}(f(x))$.
Corollary 4.22: Let $f: M \rightarrow N$ be an equivariant map. Then

$$
f^{*} \iota_{\xi}=\iota_{\xi} f^{*}
$$

for every $\xi \in \mathfrak{g}$.
Proof. Let $X_{\xi}, Y_{\xi}$ be the vector fields generated by the infinitesimal action of $\xi \in \mathfrak{g}$ on $M, N$ respectively. Let $\omega_{\bullet}=\left\{\omega_{q}\right\}_{q \in \mathbb{N}}$ and $x \in M$. Then

$$
\begin{aligned}
f^{*}\left(\iota_{\xi} \omega_{q}\right)\left(x ; Y_{0}, \ldots, Y_{n-1}\right) & =\iota_{\xi} \omega_{q}\left(f(x) ; f_{*} Y_{0}, \ldots, f_{*} Y_{n-1}\right) \\
& =\omega_{q}\left(f(x) ; X_{\xi}, f_{*} Y_{0}, \ldots, f_{*} Y_{n-1}\right) \\
& =f^{*} \omega_{q}\left(x ; Y_{\xi}, Y_{0}, \ldots, Y_{n-1}\right) \\
& =\iota_{\xi}\left(f^{*} \omega_{q}\right)\left(x ; Y_{0}, \ldots, Y_{n-1}\right)
\end{aligned}
$$

by Corollary 4.22 , where $f_{*}$ is the derivative of $f$.

So $\iota_{\xi}$ commutes with the equivariant maps (4.16) on $M_{\bullet}$ and can thus be considered a well defined derivation (of degree -1 ) on $A^{*}\left(M_{\bullet}\right)$. We say a simplicial differential form $\omega_{\bullet}$ is horizontal if

$$
\iota_{\xi} \omega_{\bullet}=0
$$

for every $\xi \in \mathfrak{g}$. From Cartan's Magic Formula, it follows that

$$
\mathcal{L}_{\xi}=d \iota \xi+\iota_{\xi} d
$$

is a derivation (of degree 0 ) on $A^{*}\left(M_{\bullet}\right)$ and may be explicitly be defined to be

$$
\mathcal{L}_{\xi} \omega_{\bullet}:=\left\{\mathcal{L}_{\xi} \omega_{n}\right\}_{n \geq 0} .
$$

Suppose $P_{\bullet} \xrightarrow{\pi_{\bullet}} B_{\bullet}$ is a simplicial principal $G$-bundle. From Proposition 2.42 we know that for every $n \geq 0$ there is an isomorphism $\Omega^{*}\left(B_{n}\right) \cong \Omega^{*}\left(P_{n}\right)_{\text {bas }}$ and hence it follows that there is an isomorphism

$$
A^{*}\left(P_{\bullet}\right)_{\text {bas }} \cong A^{*}\left(B_{\bullet}\right)
$$

Definition 4.23: Let $P_{\bullet} \xrightarrow{\pi_{\bullet}} B_{\bullet}$ be a simplicial principal $G$-bundle. A simplicial differential form $\omega_{\bullet}$ is said to be basic if it is horizontal and $G$-invariant. That is, $\iota_{\xi} \omega_{\bullet}=0$ and $\omega_{\bullet} \cdot g=\omega_{\bullet}$ for every $\xi \in \mathfrak{g}$ and $g \in G$. The complex of basic differential forms is denoted $A^{*}\left(P_{\bullet}\right)_{\text {bas }}$.

### 4.2.2 Simplicial Connections and Curvature

The complex $A^{*}(N \bar{G})$ gives us a model for differential forms on $E G$ and thus we would like to further define connection and curvature elements on this complex in keeping with previous calculations in Chapter 2.

Definition 4.24: Let $P_{\bullet} \xrightarrow{\pi} B_{\bullet}$ be a simplicial principal $G$-bundle. $A$ simplicial connection on $P_{\bullet}$ is a $\mathfrak{g}$-valued 1 -form

$$
\theta_{\bullet}=\left\{\theta_{n}\right\}_{n \geq 0} \in A^{1}\left(P_{\bullet}\right) \otimes \mathfrak{g}
$$

such that each $\theta_{n}$ is a connection form on the bundle $\Delta^{n} \times P_{n} \rightarrow \Delta^{n} \times B_{n}$.
Recall the connection $\theta_{L}$ on the trivial $G$-bundle $G \rightarrow\{1\}$ as defined in (2.37). When considering the manifold $N \bar{G}_{n}=G^{n+1}$ we could define projections $p_{i}: N \bar{G}_{n} \rightarrow G$ where

$$
p_{i}\left(g_{0}, \ldots, g_{n}\right)=g_{i}
$$

for $i=0,1, \ldots, n$. We would like to show that $p_{i}^{*} \theta_{L}$ is a connection on the bundle $N \bar{G}_{n} \rightarrow N G_{n}$ for each $i$ which amounts to proving the following lemma.

Corollary 4.25: Let $f: P \rightarrow Q$ be an equivariant map of principal bundles and $\theta$ be a connection on $Q$. Then $f^{*} \theta \in \Omega^{1}(P) \otimes \mathfrak{g}$ is a connection on $P$.

Proof. Let $X_{\xi}$ be the vector field generated by the infinitesimal action of $\xi$ on $P$. By the previous lemma, we have that

$$
f^{*} \theta\left(x ; X_{\xi}\right)=\theta\left(f(x), Y_{\xi}\right)=\xi
$$

and hence $f^{*} \theta$ is itself a connection.
The projection maps $p_{i}$ are clearly equivariant bundle maps, and hence define connections $p_{i}^{*} \theta_{L}$ on $\Omega^{1}\left(N \bar{G}_{n}\right) \otimes \mathfrak{g}$. In fact, we are trying to build connection forms on the bundle

$$
N \bar{G}_{n} \times \Delta^{n} \rightarrow N G_{n} \times \Delta^{n}
$$

where $G$ acts trivially on $\Delta^{n}$. We now sketch a standard result about connections.
Proposition 4.26: Any convex combination of connections is again a connection.
Proof. Let $\theta_{1}, \ldots, \theta_{k}$ be connections on a principal bundle $P$ and $\lambda_{1}, \ldots, \lambda_{k}$ be smooth, real valued functions on $P$ such that $\sum_{i=0}^{k} \lambda_{i}=1$. For any vector field $\xi \in \mathfrak{g}$ one calculates that

$$
\sum_{i=0}^{k} \lambda_{i} \theta_{i}\left(x ; X_{\xi}\right)=\sum_{i=0}^{k} \lambda_{i}(x) \xi=\xi
$$

It is also clear that for any $g \in G$,

$$
\sum_{i=0}^{k} \phi_{g}^{*} \lambda_{i} \theta_{i}\left(x ; X_{\xi}\right)=\sum_{i=0}^{k} \lambda_{i}(x \cdot g) \operatorname{Ad}\left(g^{-1}\right) \xi=\operatorname{Ad}\left(g^{-1}\right) \xi .
$$

These two calculations verify that $\sum_{i=0}^{k} \lambda_{i} \theta_{i}$ is indeed a connection.
On the standard $n$-simplex $\Delta^{n}$ we use the coordinates $\left(t_{0}, \ldots, t_{n}\right)$ where $\sum_{i=0}^{n} t_{i}=1$. From this and the previous proposition the differential form defined by

$$
\theta_{n}=\sum_{i=0}^{n} t_{i} p_{i}^{*} \theta_{L} \in \Omega^{*}\left(N \bar{G}_{n} \times \Delta^{n}\right) \otimes \mathfrak{g}
$$

is a connection form. Moreover, by construction it is true that

$$
\left(d^{i} \times \mathrm{id}\right)^{*} \theta_{n}=\left(\mathrm{id} \times d_{i}\right)^{*} \theta_{n-1}
$$

for each $i=0,1, \ldots, n$ and hence

$$
\begin{equation*}
\theta_{\bullet}=\left\{\theta_{n}\right\}_{n \geq 0} \in A^{1}\left(N \bar{G}_{\bullet}\right) \otimes \mathfrak{g} \tag{4.27}
\end{equation*}
$$

is a well defined simplicial connection on $N \overline{G_{\bullet}}$. Similarly, we can define the simplicial curvature 2 -form by

$$
\begin{equation*}
\Omega_{\bullet}=\left\{d \theta_{n}-\frac{1}{2}\left[\theta_{n}, \theta_{n}\right]\right\}_{n \geq 0} \in A^{2}\left(N \bar{G}_{\bullet}\right) \otimes \mathfrak{g} \tag{4.28}
\end{equation*}
$$

which we will use shortly.

### 4.2.3 The Simplicial Chern-Weil Homomorphism

Let $G$ be a Lie group with Lie algebra $\mathfrak{g}$ and $\theta_{\bullet}$ be a connection form on a principal $G$-bundle $P_{\bullet} \rightarrow B_{\bullet}$. Since $\theta_{n}$ is a connection on $\Delta^{n} \times P_{n} \rightarrow \Delta^{n} \times B_{n}$ it is clear that for any $\xi \in \mathfrak{g}$ and $p \in P_{n}$,

$$
\theta_{n}\left(p ; X_{\xi}\right)=\xi .
$$

Let $\left\{\xi_{1}, \ldots, \xi_{n}\right\}$ be a basis for $\mathfrak{g}$ and $\left\{\xi_{1}^{*}, \ldots, \xi_{n}^{*}\right\}$ the corresponding dual basis for $\mathfrak{g}^{*}$. Similarly to the discussion in Section 2.2.2, we define a series of 1 -forms

$$
\theta_{\bullet}^{i}:=\left\{\xi_{i}^{*} \theta_{n}\right\}_{n \geq 0} \in A^{1}\left(P_{\bullet}\right) .
$$

Likewise, if $\Omega_{\bullet}$ is the curvature 2 -form associated to $\theta_{\bullet}$ we define a corresponding series of 2 -forms

$$
\mu_{\bullet}^{i}:=\left\{\xi_{i}^{*} \Omega_{n}\right\}_{n \geq 0} \in A^{2}\left(P_{\bullet}\right) .
$$

Associated to the choice of connection $\theta_{\bullet}$ is a unique homomorphism

$$
w\left(\theta_{\bullet}\right): W(\mathfrak{g}) \rightarrow A^{*}\left(P_{\bullet}\right)
$$

given by the natural identifications

$$
w\left(\theta_{\bullet}\right)\left(\theta^{i}\right)=\theta_{\bullet}^{i}, \quad w\left(\theta_{\bullet}\right)\left(\mu^{i}\right)=\mu_{\bullet}^{i} .
$$

As previously calculated in Section 2.3.3, for each $n \geq 0$ this homomorphism can be thought of as the ordinary Weil homomorphism

$$
w\left(\theta_{n}\right): W(\mathfrak{g}) \rightarrow \Omega^{*}\left(P_{n}\right)
$$

and hence the identities

1. $d w\left(\theta_{\bullet}\right)-w\left(\theta_{\bullet}\right) d=0$
2. $\iota_{\xi} w\left(\theta_{\bullet}\right)-w\left(\theta_{\bullet}\right) \iota_{\xi}=0$
are satisfied accordingly. First, a useful lemma will be proved.
Lemma 4.29: Let $M, N$ be manifolds and $F$ be a compact manifold of dimension $k$. If $g$ : $M \rightarrow N$ is a smooth function then the diagram

commutes.
Proof. If $\omega$ is a differential $n$-form on $N \times F$ it can locally be written as

$$
\omega=\sum f_{i_{1} \cdots i_{q}} d x_{i_{1}} \cdots d x_{i_{n}} d \varphi_{j_{1}} \cdots d \varphi_{j_{q-n}}
$$

where $f_{i_{1} \cdots i_{q}}: N \times F \rightarrow \mathbb{R}$ and $\left\{x_{i}\right\},\left\{\varphi_{i}\right\}$ are local coordinates on $F$ and $N$ respectively. Then one notes that for any $y \in N$, we may consider the smooth map

$$
f_{i_{1} \cdots i_{q}}(y,-): F \rightarrow \mathbb{R} .
$$

If $n=k$ we can thus consider

$$
\int_{F} f_{i_{1} \cdots i_{q}} d x_{i_{1}} \cdots d x_{i_{k}}: N \rightarrow \mathbb{R}
$$

as a smooth map which, at a point $y \in N$, takes the value

$$
\left(\int_{F} f_{i_{1} \cdots i_{q}} d x_{i_{1}} \cdots d x_{i_{k}}\right)(y)=\int_{F} f_{i_{1} \cdots i_{q}}(y,-) d x_{i_{1}} \cdots d x_{i_{k}} .
$$

It follows that if $g: M \rightarrow N$ is a smooth map,

$$
\begin{aligned}
\left(g^{*} \int_{F} f_{i_{1} \cdots i_{q}} d x_{i_{1}} \cdots d x_{i_{k}}\right)(y) & =\left(\int_{F} f_{i_{1} \cdots i_{q}} d x_{i_{1}} \cdots d x_{i_{k}}\right)(g(y)) \\
& =\int_{F} f_{i_{1} \cdots i_{q}}(g(y),-) d x_{i_{1}} \cdots d x_{i_{k}} \\
& =\int_{F}\left(f_{i_{1} \cdots i_{q}} \circ(g \times \mathrm{id})\right) d x_{i_{1}} \cdots d x_{i_{n}}
\end{aligned}
$$

and hence

$$
\begin{aligned}
g^{*} \int_{F} \omega & =\sum \int_{F}\left(f_{i_{1} \cdots i_{q}} \circ\left(g \times \mathrm{id}^{*}\right)\right) d x_{i_{1}} \cdots d x_{i_{n}} d\left(\varphi_{j_{1}} \circ g\right) \cdots d\left(\varphi_{j_{q-n}} \circ g\right) \\
& =\int_{F}\left(g \times \mathrm{id}^{*}\right) \omega
\end{aligned}
$$

proving the lemma.
Lemma 4.30: Let $M_{\bullet}$ be a simplicial manifold and $F$ be a compact manifold of dimension $m$. Define $M_{\bullet} \times F$ to be the sequence of simplicial manifolds

$$
M_{n} \times F
$$

where the face and degeneracy maps are simply

$$
\bar{d}_{i}:=d_{i} \times \operatorname{id}_{F}: M_{n} \times F \rightarrow M_{n-1} \times F \quad \& \quad \bar{s}_{i}:=s_{i} \times \operatorname{id}_{F}: M_{n} \times F \rightarrow M_{n+1} \times F
$$

where $0 \leq i \leq n$ and $n \geq 0$. Then the integration map over the fibre $F$,

$$
\int_{F}: A^{q}\left(M_{\bullet} \times F\right) \rightarrow A^{q-k}\left(M_{\bullet}\right),
$$

is well defined.

Proof. Let $\omega_{\bullet}=\left\{\omega_{p}\right\}$ be a simplicial differential form on $A^{*}\left(M_{\bullet} \times F\right)$. By Equation 4.16, we have that

$$
\left(d^{i} \times \operatorname{id}_{M_{p+1}} \times \operatorname{id}_{F}\right)^{*} \omega_{p+1}=\left(\mathrm{id}_{\Delta^{p}} \times \bar{d}_{i}\right)^{*} \omega_{p}
$$

for every $p \geq 0$. By two applications of Lemma 4.29, we see that

$$
\begin{align*}
\left(d^{i} \times \operatorname{id}_{M_{p+1}}\right)^{*} \int_{F} \omega_{p+1} & =\int_{F}\left(d^{i} \times \operatorname{id}_{M_{p+1}} \times \operatorname{id}_{F}\right)^{*} \omega_{p+1}  \tag{4.31}\\
& =\int_{F}\left(\operatorname{id}_{\Delta^{p}} \times \bar{d}_{i}\right)^{*} \omega_{p}  \tag{4.32}\\
& =\left(\operatorname{id}_{\Delta^{p}} \times d_{i}\right)^{*} \int_{F} \omega_{p} \tag{4.33}
\end{align*}
$$

and hence $\int_{F} \omega_{\bullet}$ is well defined.
Theorem 4.34: Let $P_{\bullet} \rightarrow B_{\bullet}$ be a simplicial principal bundle and $\theta_{\bullet}, \theta_{\bullet}^{\prime}$ be two connections on $P_{\bullet}$. Then there is a chain homotopy

$$
w\left(\theta_{\bullet}\right) \simeq w\left(\theta_{\bullet}^{\prime}\right)
$$

Moreover, since the Weil homomorphism descends to a map on basic differential forms, the induced maps on cohomology

$$
w\left(\theta_{\bullet}\right), w\left(\theta_{\bullet}^{\prime}\right): S\left(\mathfrak{g}^{*}\right) \rightarrow H^{*}\left(A^{*}\left(P_{\bullet}\right)\right)
$$

are equal.
Proof. Let $P_{\bullet} \rightarrow B_{\bullet}$ be a simplicial principal $G$-bundle with simplicial connections $\theta_{\bullet}, \theta_{\bullet}^{\prime}$. Associated to each connection are the respective simplicial curvature 2 -forms $\Omega_{\bullet}, \Omega_{\bullet}^{\prime}$. We restrict our attention to individually considering connections $\theta_{n}, \theta_{n}^{\prime}$ on the principal bundle

$$
\Delta^{n} \times P_{n} \rightarrow \Delta^{n} \times B_{n}
$$

Associated to this bundle is the bundle $\Delta^{n} \times P_{n} \times I \rightarrow \Delta^{n} \times B_{n} \times I$ and projection bundle maps

$$
p_{n}: \Delta^{n} \times P_{n} \times I \rightarrow \Delta^{n} \times P_{n}
$$

given by $p_{n}(t, p, s)=(t, p)$ and inclusion bundle maps

$$
i_{n}^{s}: \Delta^{n} \times P_{n} \rightarrow \Delta^{n} \times P_{n} \times I
$$

given by $i_{n}^{s}(t, p)=(t, p, s)$ for every $s \in I$. Note that these maps commute with the maps defined in (4.16) and hence for any simplicial differential form $\omega_{\bullet} \in A^{*}\left(P_{\bullet}\right)$ the simplicial differential form

$$
p_{\bullet}^{*} \omega_{\bullet}=\left\{p_{n}^{*} \omega_{n}\right\}_{n \geq 0} \in A^{*}\left(P_{\bullet} \times I\right)
$$

is well defined as well as the simplicial differential form

$$
i_{\bullet}^{s *} \nu_{\bullet}=\left\{i_{n}^{s *} \nu_{n}\right\}_{n \geq 0} \in A^{*}\left(P_{\bullet}\right)
$$

for $\nu_{\bullet} \in A^{*}\left(P_{\bullet} \times I\right)$ and any $s \in I$. Then define a connection $\tilde{\theta}_{\bullet} \in A^{1}\left(P_{\bullet} \times I\right) \otimes \mathfrak{g}$ by

$$
\tilde{\theta}_{\bullet}:=(1-s) p_{\bullet}^{*} \theta_{\bullet}+s p_{\bullet}^{*} \theta_{\bullet}^{\prime}
$$

and note that $i_{\bullet} \boldsymbol{0}^{*} \tilde{\theta}_{\bullet}=\theta_{\bullet}$ and $i_{\bullet}^{1^{*}} \tilde{\theta}_{\bullet}=\theta_{\bullet}^{\prime}$. The connection $\tilde{\theta}_{\bullet}$ has curvature $\tilde{\Omega}_{\bullet}$ which also satisfies that $i_{\bullet}{ }^{*} \tilde{\Omega}_{\bullet}=\Omega_{\bullet}$ and $i_{\bullet}^{1^{*}} \tilde{\Omega}_{\bullet}=\Omega_{\bullet}^{\prime}$ since curvature commutes with pullbacks.

The connection $\tilde{\theta}_{\bullet}$ also induces a simplicial Weil homomorphism

$$
w\left(\tilde{\theta}_{\bullet}\right): W(\mathfrak{g}) \rightarrow A^{*}\left(P_{\bullet}\right) .
$$

Note that from the identities above,

$$
\begin{equation*}
i_{\bullet}^{0^{*}} w\left(\tilde{\theta}_{\bullet}\right)=w\left(\theta_{\bullet}\right) \text { and } i_{\bullet}^{1^{*}} w\left(\tilde{\theta}_{\bullet}\right)=w\left(\theta_{\bullet}^{\prime}\right) . \tag{4.35}
\end{equation*}
$$

By Lemma 4.30, we can define an operator $h_{\bullet}: A^{q}\left(P_{\bullet} \times I\right) \rightarrow A^{q-1}\left(P_{\mathbf{\bullet}}\right)$ for every $q$ by

$$
h_{\bullet} \omega_{\boldsymbol{\bullet}}=\int_{I} \omega_{\boldsymbol{\bullet}}
$$

The map $h_{\bullet}$ is a homotopy operator in the sense that for every $n \geq 0$

$$
\left(d h_{n}+h_{n} d\right) \tilde{\omega}_{n}=i_{n}^{1 *} \tilde{\omega}_{n}-i_{n}^{0 *} \tilde{\omega}_{n}
$$

and hence $d h_{\bullet}+h_{\bullet} d=i_{\bullet}^{1^{*}}-i_{\bullet}^{0^{*}}$. It follows that

$$
\begin{align*}
\left(d h_{\bullet}+h_{\bullet} d\right) w\left(\tilde{\theta}_{\bullet}\right) & =\left(i_{\bullet}^{1^{*}}-i_{\bullet}^{0^{*}}\right) w\left(\tilde{\theta}_{\bullet}\right) \\
& =w\left(\theta_{\bullet}\right)(\alpha)-w\left(\theta_{\bullet}^{\prime}\right)(\alpha) \tag{4.36}
\end{align*}
$$

for every $n \geq 0$. Since $w\left(\tilde{\theta}_{\bullet}\right)$ is a chain map it follows by Equation 4.36 that for any $\alpha \in W(\mathfrak{g})$

$$
\left(d\left(h \bullet w\left(\tilde{\theta}_{\bullet}\right)\right)+\left(h \bullet w\left(\tilde{\theta}_{\bullet}\right)\right) d\right) \alpha=w\left(\theta_{\bullet}\right)(\alpha)-w\left(\theta_{\bullet}^{\prime}\right)(\alpha) .
$$

The homomorphisms $w\left(\theta_{\bullet}\right), w\left(\theta_{\bullet}^{\prime}\right)$ are thus chain homotopic. The map $w\left(\tilde{\theta}_{\bullet}\right)$ descends to a map on basic differential forms and hence if $\alpha$ is a closed and basic

$$
d\left(h \bullet w\left(\tilde{\theta}_{\bullet}\right)(\alpha)\right)=w\left(\theta_{\bullet}\right)(\alpha)-w\left(\theta_{\bullet}^{\prime}\right)(\alpha)
$$

and hence the simplicial Chern-Weil homomorphism is independent of the choice of connection.

### 4.3 An Analogue of the Weil Model

### 4.3.1 $\quad G^{*}$ Algebras

The term $G^{*}$ algebra is due to [GS99] but the idea can be traced back to Cartan's paper [Car50b]. Let $G$ be a Lie group and $A$ be a chain complex that has a right $G$-action. The general idea of a $G^{*}$ algebra is to isolate the conditions on a chain complex $A$ such that it can be thought of as an algebraic model for equivariant cohomology and is motivated by the graded derivations $d, \iota_{\xi}$ and $\mathcal{L}_{\xi}$ on $\Omega^{*}(M)$ that were encountered in Section 2.2.1. We first recall the definition of a graded commutative algebra and some facts about these graded derivations.

Definition 4.37: $A(\mathbb{Z}-)$ graded commutative algebra $A$ is an algebra

$$
A=\bigoplus_{i \in \mathbb{Z}} A_{i}
$$

equipped with a multiplication satisfying

$$
a \cdot b=(-1)^{i j} b \cdot a
$$

for $a \in A_{i}$ and $b \in A_{j}$ such that

$$
A_{i} \cdot A_{j} \subset A_{i+j} .
$$

Definition 4.38: Let A be a graded commutative algebra. A graded derivation D of degree $k$ is an endomorphism $D: A \rightarrow A$ satisfying the graded Leibniz identity

$$
D(a \cdot b)=(D a) \cdot b+(-1)^{k i} a \cdot(D b) \in A_{i+j+k}
$$

for $a \in A_{i}$ and $b \in A_{j}$.
The vector space of graded derivations of degree $k$ is denoted $\operatorname{Der}_{k}(A)$. The collection of all derivations of $A$ is defined as

$$
\operatorname{Der}(A)=\bigoplus_{k \in \mathbb{Z}} \operatorname{Der}_{k}(A)
$$

Because of this natural grading on the derivations of $A$, there is a bracket

$$
[-,-]: \operatorname{Der}_{k}(A) \otimes \operatorname{Der}_{l}(A) \rightarrow \operatorname{Der}_{k+l}(A)
$$

called the graded commutator which is defined by

$$
[C, D]=C D-(-1)^{k l} D C
$$

where $C$ is a graded derivation of degree $k$ and $D$ is a graded derivation of degree $l$. With this bracket, it follows that $\operatorname{Der}_{0}(A)$ has a natural Lie algebra structure.

Example 4.39: Note that if $M$ is a manifold and $M_{\bullet}$ is a simplicial manifold, the wedge product on the graded algebras $\Omega^{*}(M)$ and $A^{*}\left(M_{\bullet}\right)$ satisfy the condition in Definition 4.37. Moreover, the de Rham differential $d$ is a graded derivation of degree 1 satisfying Definition 4.38. The fact that $d^{2}=0$ means this is a differential operator and the notion of a differential graded commutative algebra follows.

Definition 4.40: $A$ differential graded commutative algebra $(A, d)$ is a graded commutative algebra with a graded derivation d of degree 1 which is also a differential operator (i.e. $d^{2}=0$ ).

From this definition it is clear that $\left(\Omega^{*}(M), d\right)$ and $\left(A^{*}\left(M_{\bullet}\right), d\right)$ are differential graded commutative algebras. We now recall some properties about the graded derivations $d, \iota_{\xi}$ and $\mathcal{L}_{\xi}$ on $\Omega^{*}(M)$ which we will carry over to the definition of a $G^{*}$ algebra.

## The graded derivation $\iota_{\xi}$ of degree -1

The derivation $\iota_{\xi}$ can be thought of more abstractly as a map from $\mathfrak{g}$ to the derivations of $\Omega^{*}(M)$

$$
\iota: \mathfrak{g} \rightarrow \operatorname{Der}_{-1}\left(\Omega^{*}(M)\right)
$$

and hence can be acted upon by $G$. Firstly note that $\iota_{\xi}^{2}=0$ for every $\xi \in \mathfrak{g}$. The natural action of $G$ on $\mathfrak{g}$ is the adjoint action and so one would expect that the identity

$$
\begin{equation*}
\phi_{g}^{*} \iota_{\xi} \phi_{g^{-1}}^{*}=\iota_{\operatorname{Ad}(g) \xi} \tag{4.41}
\end{equation*}
$$

is held.
Proof. Let $\xi \in \mathfrak{g}, g \in G$ and consider an $n$-form $\omega \in \Omega^{n}(M)$. First recall

$$
\left(\phi_{g}\right)_{*} X_{\xi}(p)=X_{\operatorname{Ad}\left(g^{-1}\right) \xi}(p)
$$

from Equation 2.34. Then consider

$$
\left(\phi_{g}^{*} \iota_{\xi} \phi_{g^{-1}}^{*} \omega\right)\left(x ; X_{1}, \ldots, X_{n-1}\right)
$$

where $X_{1}, \ldots, X_{n-1}$ are any $n-1$ vector fields on $M$. The calculation is straightforward and yields

$$
\begin{aligned}
\phi_{g}^{*}\left(\iota_{\xi} \phi_{g^{-1}}^{*} \omega\right)\left(x ; X_{1}, \ldots, X_{n-1}\right) & =\left(\iota_{\xi} \phi_{g^{-1}}^{*} \omega\right)\left(x \cdot g ;\left(\phi_{g}\right)_{*} X_{1}, \ldots,\left(\phi_{g}\right)_{*} X_{n-1}\right) \\
& =\left(\phi_{g^{-1}}^{*} \omega\right)\left(x \cdot g ; X_{\xi},\left(\phi_{g}\right)_{*} X_{1}, \ldots,\left(\phi_{g}\right)_{*} X_{n-1}\right) \\
& =\omega\left(x ;\left(\phi_{g}^{-1}\right)_{*} X_{\xi}, X_{1}, \ldots, X_{n-1}\right) \\
& =\iota_{\operatorname{Ad}(g) \xi} \omega\left(x ; X_{1}, \ldots, X_{n-1}\right)
\end{aligned}
$$

which verifies that the identity in Equation 4.41 holds.

## The graded derivation $\mathcal{L}_{\xi}$ of degree 0

Because the derivations of degree 0 are naturally a Lie algebra, the derivation $\mathcal{L}_{\xi}$ can be thought of more abstractly as a Lie algebra homomorphism

$$
\mathcal{L}: \mathfrak{g} \rightarrow \operatorname{Der}_{0}\left(\Omega^{*}(M)\right)
$$

and hence can be acted upon by $G$. We defined $\mathcal{L}_{\xi}$ in 2.31 to be the Lie derivative

$$
\begin{equation*}
\mathcal{L}_{\xi} \omega=\left.\frac{d}{d t} \phi_{\exp t \xi}^{*} \omega\right|_{t=0} \tag{4.42}
\end{equation*}
$$

Since this is thought of as 'differentiation in the direction $\xi$ ', one would expect this derivation to agree with the group action in this way. Similarly to the case of $\iota_{\xi}$, one would expect that the identity

$$
\begin{equation*}
\phi_{g}^{*} \mathcal{L}_{\xi} \phi_{g^{-1}}^{*}=\mathcal{L}_{\operatorname{Ad}(g) \xi} \tag{4.43}
\end{equation*}
$$

is held.
Proof. Cartan's magic formula may be invoked to show that

$$
\begin{aligned}
\phi_{g}^{*} \mathcal{L}_{\xi} \phi_{g^{-1}}^{*} & =\phi_{g}^{*}\left(d \iota_{\xi}+\iota_{\xi} d\right) \phi_{g^{-1}}^{*} \\
& =d \phi_{g}^{*} \iota_{\xi} \phi_{g^{-1}}^{*}+\phi_{g}^{*} \iota_{\xi} \phi_{g^{-1}}^{*} d \\
& =d \iota_{\operatorname{Ad}(g) \xi}+\iota_{\operatorname{Ad}(g) \xi} d \\
& =\mathcal{L}_{\operatorname{Ad}(g) \xi}
\end{aligned}
$$

which verifies that the identity in Equation 4.43 holds.

## The graded derivation $d$ of degree 1

The commutativity identity

$$
\begin{equation*}
\phi_{g}^{*} d \phi_{g^{-1}}^{*}=d \tag{4.44}
\end{equation*}
$$

holds since pullbacks commute with $d$.

We combine these identities associated to the differential graded commutative algebra $\Omega^{*}(M)$ as a blueprint to form the definition of a $G^{*}$ algebra.

Definition 4.45: $A G^{*}$-algebra is a differential graded commutative algebra $(A, d)$ with a right G-action

$$
\phi: A \times G \rightarrow A
$$

together with maps

$$
\begin{aligned}
& \iota: \mathfrak{g} \rightarrow \operatorname{Der}_{-1}(A) \\
& \mathcal{L}: \mathfrak{g} \rightarrow \operatorname{Der}_{0}(A)
\end{aligned}
$$

such that $\left(\iota_{\xi}\right)^{2}=0$ for all $\xi \in \mathfrak{g}, \mathcal{L}$ is a Lie algebra homomorphism, and the following identities are satisfied:

$$
\mathcal{L}_{\xi}=d \iota_{\xi}+\iota_{\xi} d,\left[\mathcal{L}_{\xi}, \iota_{\eta}\right]=\iota_{[\xi, \eta]}
$$

for all $\xi, \eta \in \mathfrak{g}$. Additionally the following identities involving the map $\phi$ are satisfied:

1. $\left.\frac{d}{d t} \phi_{\exp t \xi}\right|_{t=0}=\mathcal{L}_{\xi}$,
2. $\phi_{g} \mathcal{L}_{\xi} \phi_{g^{-1}}=\mathcal{L}_{\operatorname{Ad}(g) \xi}$,
3. $\phi_{g} \iota_{\xi} \phi_{g^{-1}}=\iota_{\operatorname{Ad}(g) \xi}$ and
4. $\phi_{g} d \phi_{g^{-1}}=d$.

Corollary 4.46: Let $G$ be a Lie group and $M$ a manifold with right $G$-action. Then $\Omega^{*}(M)$ is a $G^{*}$ algebra.

The natural notion of a homomorphism of $G^{*}$ algebra arises as an algebra homomorphism that commutes with the action of $G$ and the graded derivations $d, \iota_{\xi}, \mathcal{L}_{\xi}$.

Definition 4.47: Let $A, B$ be $G^{*}$ algebras. $A G^{*}$ homomorphism

$$
f: A \rightarrow B
$$

is an algebra homomorphism such that

1. $\phi_{g} \circ f=f \circ \phi_{g}$,
2. $d \circ f=f \circ d$,
3. $\iota_{\xi} \circ f=f \circ \iota_{\xi}$ and $\mathcal{L}_{\xi} \circ f=f \circ \mathcal{L}_{\xi}$
for every $g \in G$ and $\xi \in \mathfrak{g}$.
Remark 4.48: Note that a $G^{*}$ homomorphism $f: A \rightarrow B$ induces a natural chain map $f$ : $A_{b a s} \rightarrow B_{b a s}$ since it commutes with $d, \iota_{\xi}$ (for every $\xi \in \mathfrak{g}$ ) and is equivariant.

Let $G$ be a Lie group and $M_{\bullet}$ be a simplicial manifold with right $G$-action. The complex $A^{*}\left(M_{\bullet}\right)$ is built out of the complexes $\Omega^{*}\left(\Delta^{p} \times M_{p}\right)$ which are $G^{*}$ algebras from Corollary 4.46. Because of this we only need to show is that the graded derivations $\mathcal{L}_{\xi}, \iota_{\xi}$ and $d$ are well defined on $A^{*}\left(M_{\bullet}\right)$ by showing that they commute with the face maps defined in 4.16 . Recall that the
pullbacks of equivariant maps commute with $\iota_{\xi}$ for all $\xi \in \mathfrak{g}$ by Proposition 4.22. It is clear that they also commute with $\mathcal{L}_{\xi}$ from the identity

$$
\mathcal{L}_{\xi}=d \iota \xi+\iota_{\xi} d .
$$

Hence, we have the following corollary.
Corollary 4.49: Let $f: M \rightarrow N$ be an equivariant map. Then

$$
f^{*} \mathcal{L}_{\xi}=\mathcal{L}_{\xi} f^{*}
$$

for every $\xi \in \mathfrak{g}$.
From these last two corollaries, it is evident that since the face maps $d^{i} \times \mathrm{id}$ and $\mathrm{id} \times d_{i}$ are equivariant the derivations $\mathcal{L}_{\xi}, \iota_{\xi}, d$ commute with them and hence $A^{*}\left(M_{\bullet}\right)$ is a $G^{*}$ algebra for any simplicial manifold with right $G$-action.

Proposition 4.50: Let $M_{\bullet}$ be a simplicial manifold with right $G$-action. Then $A^{*}\left(M_{\bullet}\right)$ is a $G^{*}$ algebra.

### 4.3.2 The Cohomology of a $G^{*}$ Algebra

Since a $G^{*}$ algebra $A$ has a differential operator $d$ there is a well defined notion of cohomology for $A$. Namely, the $n^{\text {th }}$ cohomology group of $A$ is defined to be

$$
H^{n}(A)=\frac{\operatorname{ker} d \cap A}{\operatorname{im} d \cap A}
$$

for every $n \geq 0$. We can also define the basic subalgebra of a $G^{*}$ algebra.
Definition 4.51: Let $A$ be a $G^{*}$ algebra. The element $a \in A$ is said to be basic if it is horizontal and $G$-invariant. That is, $\iota_{\xi} a=0$ and $a \cdot g=a$ for every $\xi \in \mathfrak{g}$ and $g \in G$. The basic subcomplex is the complex that contains all the basic elements of $A$ and is denoted $A_{b a s}$.

Note that an implication of Cartan's magic formula is that for any $a \in A_{b a s}, d a \in A_{b a s}$. This is because the action of $G$ commutes with $d$,

$$
\iota_{\xi}(d a)=\mathcal{L}_{\xi} a-d\left(\iota_{\xi} a\right),
$$

$\mathcal{L}_{\xi} a=0$ when $a$ is $G$-invariant and $\iota_{\xi} a=0$ by the definition of a basic element of $A$. Thinking of $(A, d)$ as a complex, this means that $\left(A_{b a s}, d\right)$ is a well defined subcomplex. One defines the basic cohomology of a $A$ to be the cohomology of the basic subcomplex

$$
H^{*}\left(A_{b a s}\right) .
$$

### 4.3.3 The Cartan Model for $G^{*}$ Algebras

Recall from Section 2.3.4 that there was an operator

$$
\zeta=\theta^{i} \otimes \iota_{\xi_{i}}
$$

such that $\exp (\zeta):\left(W(\mathfrak{g}) \otimes \Omega^{*}(M)\right)_{\text {bas }} \rightarrow\left(S\left(\mathfrak{g}^{*}\right) \otimes \Omega^{*}(M)\right)^{G}$ was an isomorphism. If $A$ is a $G^{*}$ algebra, then Definition 4.45 gives a sensible notion of $\zeta$ on the complex $W(\mathfrak{g}) \otimes A$. Namely, we define the operator

$$
\begin{equation*}
\zeta=\theta^{i} \otimes \iota_{\xi_{i}}: W(\mathfrak{g}) \otimes A \rightarrow W(\mathfrak{g}) \otimes A . \tag{4.52}
\end{equation*}
$$

Since the results of Secion 2.3.4 and 2.3.5 only rely on the $G^{*}$ structure of $\Omega(M)$, the fact that the map

$$
\exp (\zeta):(W(\mathfrak{g}) \otimes A)_{b a s} \rightarrow\left(S\left(\mathfrak{g}^{*}\right) \otimes A\right)^{G}
$$

is an isomorphism can also be proven in a similar fashion. We will refer to the complex

$$
\left(S\left(\mathfrak{g}^{*}\right) \otimes A^{*}\left(M_{\bullet}\right)\right)^{G}
$$

as the Cartan Model of $A$. We state the results and direct the reader to [GS99, Ch. 4] for further reading on the matter.

Proposition 4.53: Let $G$ be a Lie group with Lie algebra $\mathfrak{g}$ and $A$ be a $G^{*}$ algebra. Then the Mathai-Quillen Isomorphism

$$
\exp (\zeta):(W(\mathfrak{g}) \otimes A)_{\text {bas }} \rightarrow\left(S\left(\mathfrak{g}^{*}\right) \otimes A\right)^{G}
$$

satisfies the following identities.

1. $d_{G}:=\exp (\zeta) d \exp (-\zeta)=d-\mu^{k} \otimes \iota_{\xi_{k}}$.
2. $\exp (\zeta)\left(1 \otimes \iota_{\xi}+\iota_{\xi} \otimes 1\right) \exp (-\zeta)=\iota_{\xi} \otimes 1$.

Example 4.54: Let $\alpha \otimes b \in\left(S\left(\mathfrak{g}^{*}\right) \otimes A\right)^{G}$. Then

$$
d_{G}(\alpha \otimes b)=\alpha \otimes d b-\mu^{k} \alpha \otimes \iota_{\xi_{k}} b
$$

where Einstein summation convention is observed.
We exploit the technology of Guillemin and Sternberg to further prove a result about homomorphisms between $G^{*}$ algebras and the induced homomorphisms between their Cartan models.

Theorem 4.55: Let $G$ be a compact group. Let $A, B$ be $G^{*}$ algebras and $f: A \rightarrow B$ a $G^{*}$ homomorphism that induces an isomorphism in cohomology. Then the map

$$
1 \otimes f:\left\{S\left(\mathfrak{g}^{*}\right) \otimes A\right\}^{G} \rightarrow\left\{S\left(\mathfrak{g}^{*}\right) \otimes B\right\}^{G}
$$

is an isomorphism on cohomology with respect to the differential operator $d_{G}$.
Proof. The reader is directed to [GS99, Ch. 6] for a proof of this statement.

### 4.4 Simplicial Equivariant Cohomology and Cartan's Theorem

### 4.4.1 Constructing a $G^{*}$ Homomorphism

At the end of the last section, we stated a result of Guillemin and Sternberg regarding induced maps on the Cartan models of $G^{*}$ Algebras. In this section we will construct a $G^{*}$ homomorphism

$$
\Omega^{*}(M) \rightarrow A^{*}(N \bar{G} \bullet \times M)
$$

such that there is a chain map

$$
\left\{S\left(\mathfrak{g}^{*}\right) \otimes \Omega^{*}(M)\right\}^{G} \rightarrow\left\{S\left(\mathfrak{g}^{*}\right) \otimes A^{*}\left(N \bar{G}_{\bullet} \times M\right)\right\}^{G}
$$

that induces an isomorphism in cohomology via Theorem 4.55.
Recall that any manifold $M$ can be turned into a simplicial manifold $\left\{M_{n}\right\}_{n \geq 0}$ by letting $M_{n}=M$ and setting each face and degeneracy map to the identity

$$
d_{i}=\operatorname{id}_{M}: M_{n} \rightarrow M_{n-1}, s_{i}=\operatorname{id}_{M}: M_{n} \rightarrow M_{n+1}
$$

for every $0 \leq i \leq n$. As a slight abuse of notation, for the rest of the section we will consider $\Omega^{*, *}(M)$ and $A^{*}(M)$ to refer to the chain complexes associated to the trivial simplicial manifold constructed from the manifold $M$.

Lemma 4.56: The canonical inclusion

$$
\Omega^{*}(M) \hookrightarrow \Omega^{0, *}(M)
$$

of $\Omega^{*}(M)$ into the first column of $\Omega^{*, *}(M)$ induces an isomorphism in cohomology

$$
H^{*}\left(\Omega^{*}(M)\right) \cong H_{\mathrm{Tot}}^{*}\left(\Omega^{*, *}(M)\right) .
$$

Proof. An element $\nu \in \operatorname{Tot}^{q}\left(\Omega^{*, *}(M)\right)$ is of the form

$$
\nu=\left(\nu_{0}, \nu_{1}, \ldots, \nu_{q}\right)
$$

where $\nu_{i} \in \Omega^{q-i}(M)=\Omega^{i, q-i}(M)$. From the definition of $\delta$ in Equation 4.2 we see that

$$
\delta \nu_{i}= \begin{cases}\nu_{i} & \text { if } i \text { is odd }  \tag{4.57}\\ 0 & \text { if } i \text { is even }\end{cases}
$$

for each $\nu_{i}$. It is perhaps easiest to see this as a diagram.


Looking again at Equations 4.3 and 4.57,

$$
D \nu=\left\{\begin{array}{l}
\left(d \nu_{0},-d \nu_{1}, \nu_{1}+d \nu_{2},-d \nu_{3}, \ldots,-d \nu_{q}, \nu_{q}\right) \text { if } q \text { is odd }  \tag{4.58}\\
\left(d \nu_{0},-d \nu_{1}, \nu_{1}+d \nu_{2},-d \nu_{3}, \ldots, \nu_{q-1}+d \nu_{q}, 0\right) \text { if } q \text { is even }
\end{array}\right.
$$

for a general element $\nu$. If $\nu$ is a cocycle then the condition that $d \nu_{i}=0$ and $\nu_{i}=-d \nu_{i+1}$ for each even odd $i<q$. If $q$ is odd, we also have that $\nu_{q}=0$. This means we can write any cocycle $\nu$ as

$$
\nu=\left(\nu_{0}, 0, \ldots, 0\right)+D\left(0, \nu_{2}, 0, \nu_{4}, \ldots\right)
$$

and thus any cocycle can be represented by it's first entry $\nu_{0}$. Ultimately, this means the inclusion

$$
\omega \mapsto(\omega, 0, \ldots, 0)
$$

is a surjection on cohomology. Clearly this map is an injection on cohomology as well and thus the map

$$
\Omega^{*}(M) \hookrightarrow \Omega^{0, *}(M)
$$

defines an isomorphism on cohomology.
Proposition 4.59: The map $p_{M}: N \bar{G} \bullet M \rightarrow M$ induces a map

$$
\Omega^{*}(M) \rightarrow A^{*}(N \bar{G} \bullet \times M)
$$

which is an isomorphism in cohomology.
Proof. From Lemma 4.56 we have a natural inclusion

$$
\Omega^{*}(M) \stackrel{i}{\longleftrightarrow} \Omega^{0, *}(M) .
$$

The map $p_{M}$ induces a map

$$
\Omega^{*, *}(M) \xrightarrow{p_{M}^{*}} \Omega^{*, *}\left(N \bar{G}_{\bullet} \times M\right)
$$

which is an isomorphism in cohomology by Theorem 4.14 and Corollary 3.62. From Theorem 4.20 , the chain map

$$
E_{\Delta}: \Omega^{*, *}\left(N \bar{G}_{\bullet} \times M\right) \rightarrow A^{*}\left(N \bar{G}_{\bullet} \times M\right)
$$

induces an isomorphism in cohomology. Hence the map $E_{\Delta} \circ p_{M}^{*} \circ i$, which may be explicitly written as

$$
\omega \mapsto\left\{p!\sum_{s=0}^{p}(-1)^{s} t_{i_{s}} d t_{i_{0}} \cdots d \hat{t}_{i_{s}} \cdots d t_{i_{p}} \wedge p_{M}^{*} \omega\right\}_{p \geq 0},
$$

induces an isomorphism in cohomology.
Proposition 4.60: The map $E_{\Delta} \circ p_{M}^{*} \circ i: \Omega^{*}(M) \rightarrow A^{*}(N \bar{G} \bullet \times M)$ is a $G^{*}$ morphism.
Proof. Firstly we note that each map $E_{\Delta}, p_{M}^{*}, i$ is a chain map and hence

$$
d\left(E_{\Delta} \circ p_{M}^{*} \circ i\right)=\left(E_{\Delta} \circ p_{M}^{*} \circ i\right) d .
$$

The maps $p_{M}^{*}, i$ are equivariant so it remains to verify that $E_{\Delta}$ is equivariant. This is trivially true since

$$
\begin{aligned}
E_{\Delta}(\omega)_{p} \cdot g & =p!\left(\sum_{s=0}^{p}(-1)^{s} t_{i_{s}} d t_{i_{0}} \cdots d \hat{t}_{i_{s}} \cdots d t_{i_{p}} \wedge \omega\right) \cdot g \\
& =p!\sum_{s=0}^{p}(-1)^{s} t_{i_{s}} d t_{i_{0}} \cdots d \hat{t}_{i_{s}} \cdots d t_{i_{p}} \wedge(\omega \cdot g) \\
& =E_{\Delta}(\omega \cdot g)_{p}
\end{aligned}
$$

for every $g \in G$ since $G$ acts trivially on $\Delta^{p}$. Since $E_{\Delta} \circ p_{M}^{*} \circ i$ is equivariant, by Definition 4.45 (1) it is also true that

$$
\mathcal{L}_{\xi}\left(E_{\Delta} \circ p_{M}^{*} \circ i\right)=\left(E_{\Delta} \circ p_{M}^{*} \circ i\right) \mathcal{L}_{\xi} .
$$

for every $\xi \in \mathfrak{g}$. Finally, the fact that $E_{\Delta} \circ p_{M}^{*} \circ i$ commutes with $\iota_{\xi}$ follows from the calculation

$$
\begin{aligned}
\left(\iota_{\xi}\left(E_{\Delta} \circ p_{M}^{*} \circ i\right) \omega\right)_{p} & =\iota_{\xi} p!\sum_{s=0}^{p}(-1)^{s} t_{i_{s}} d t_{i_{0}} \cdots d \hat{t}_{i_{s}} \cdots d t_{i_{p}} \wedge p_{M}^{*} \omega \\
& =p!\sum_{s=0}^{p}(-1)^{s} t_{i_{s}} d t_{i_{0}} \cdots d \hat{t}_{i_{s}} \cdots d t_{i_{p}} \wedge \iota_{\xi} p_{M}^{*} \omega \\
& =p!\sum_{s=0}^{p}(-1)^{s} t_{i_{s}} d t_{i_{0}} \cdots d \hat{t}_{i_{s}} \cdots d t_{i_{p}} \wedge p_{M}^{*} \iota_{\xi} \omega \\
& =\left(\left(E_{\Delta} \circ p_{M}^{*} \circ i\right) \iota_{\xi} \omega\right)_{p}
\end{aligned}
$$

for every $\xi \in \mathfrak{g}$ and every $p \geq 0$ since $\iota_{\xi}$ vanishes on $\Delta^{p}$ and commutes with pullbacks by Proposition 4.22.

### 4.4.2 Cartan's Theorem via Simplicial Differential Forms

Lemma 4.61: Let $P \rightarrow B$ be a principal $G$-bundle and $\mathfrak{g}$ be the Lie algebra of $G$ with basis $\left\{\xi_{1}, \ldots, \xi_{n}\right\}$. Let $P$ have connection $\theta$ and elements $\left\{\theta^{1}, \ldots, \theta^{n}\right\}$ respectively to the basis of $\mathfrak{g}$. Then a differential form $\omega$ can be written uniquely as a sum

$$
\omega=\sum \theta^{i_{1}} \ldots \theta^{i_{k}} \nu_{i_{1}, \ldots, i_{k}}
$$

where $\nu_{i_{1}, \ldots, i_{k}}$ is a horizontal differential form on $P$.
Proof. Let $\omega$ be a differential form on $P$. Define the components $\alpha_{i}=\iota_{\xi_{i}} \omega$ and $\beta_{i}=\omega-\theta^{i} \alpha_{i}$ such that $\omega=\theta^{i} \alpha_{i}+\beta_{i}$. Clearly $\alpha$ satisfies $\iota_{\xi_{i}} \alpha_{i}=0$. Moreover, $\beta_{i}$ satisfies

$$
\begin{aligned}
\iota_{\xi_{i}} \beta_{i} & =\iota_{\xi_{i}} \omega-\iota_{\xi_{i}}\left(\theta^{i} \iota_{\xi_{i}} \omega\right) \\
& =\iota_{\xi_{i}} \omega-\left(\iota \iota_{\xi_{i}} \theta^{i}\right) \iota_{\xi_{i}} \omega+\theta^{i} \iota_{\xi_{i}}\left(\iota_{\xi_{i}} \omega\right) \\
& =0 .
\end{aligned}
$$

Since any differential form $\omega$ can be written as

$$
\omega=\theta^{i} \alpha_{i}+\beta_{i}
$$

the process can be repeated on $\alpha_{i}$ and $\beta_{i}$ for a different index $j \neq i$ to yield the decomposition

$$
\alpha_{i}=\theta^{j} \alpha_{i j}+\beta_{i j}, \quad \beta_{i}=\theta^{j} \alpha_{i j}^{\prime}+\beta_{i j}^{\prime}
$$

and thus $\omega=\theta^{i} \theta^{j} \alpha_{i j}+\theta^{i} \beta_{i j}+\theta^{j} \alpha_{i j}^{\prime}+\beta_{i j}^{\prime}$ and each of the differential forms $\alpha_{i j}, \beta_{i j}, \alpha_{i j}^{\prime}, \beta_{i j}^{\prime}$ vanish on $\iota \xi_{i}$ and $\iota \xi_{j}$. Repeating this for each index $i=1, \ldots, n$ we obtain the unique decomposition

$$
\omega=\sum \theta^{i_{1}} \ldots \theta^{i_{k}} \nu_{i_{1}, \ldots, i_{k}}
$$

as required.
Since the lemma above relies only on the existence of the operator $\iota_{\xi}$ and connection elements, the above calculation can be repeated in the simplicial case to yield the following corollary.

Corollary 4.62: Let $P_{\bullet}$ have simplicial connection $\theta_{\bullet}$ and respectively elements $\left\{\theta_{\bullet}^{1}, \ldots, \theta_{\bullet}^{n}\right\}$. Then a simplicial differential form $\omega_{\bullet}$ can be written uniquely as a sum

$$
\omega_{\bullet}=\sum \theta_{\bullet}^{i_{1}} \ldots \theta_{\bullet}^{i_{k}} \nu_{i_{1}, \ldots, i_{k} \bullet}
$$

where $\nu_{i_{1}, \ldots, i_{k} \bullet}$ is a horizontal simplicial differential form on $P_{\bullet}$.
Let $A^{*}\left(N \bar{G}_{\bullet} \times M\right)_{v e r t}$ be the set of elements generated by $\left\{\theta_{\bullet}^{1}, \ldots, \theta_{\bullet}^{n}\right\}$. Clearly from the corollary we have the decomposition

$$
A^{*}\left(N \bar{G}_{\bullet} \times M\right)=A^{*}\left(N \bar{G}_{\bullet} \times M\right)_{v e r t} \otimes A^{*}\left(N \bar{G}_{\bullet} \times M\right)_{h o r}
$$

There is a natural projection onto the horizontal component of $\omega_{\bullet}$,

$$
\operatorname{Hor}\left(\omega_{\bullet}\right)=\operatorname{Hor}\left(\sum \theta_{\bullet}^{i_{1}} \ldots \theta_{\bullet}^{i_{k}} \nu_{i_{1}, \ldots, i_{k} \bullet}\right)=\nu_{0}
$$

where $\nu_{0}$ is the single summand in $A^{*}\left(N \bar{G}_{\bullet} \times M\right)_{h o r}$. We are interested in the complex $\left(S\left(\mathfrak{g}^{*}\right) \otimes\right.$ $\left.A^{*}(N \bar{G} \bullet \times M)\right)^{G}$ which can thus be decomposed

$$
\begin{equation*}
\left(S\left(\mathfrak{g}^{*}\right) \otimes A^{*}\left(N \bar{G}_{\bullet} \times M\right)\right)^{G}=\bigoplus C^{p, q} \tag{4.63}
\end{equation*}
$$

where $C^{p, q}=\left(S^{p}\left(\mathfrak{g}^{*}\right) \otimes A^{q}\left(N \bar{G}_{\bullet} \times M\right)_{v e r t} \otimes A^{*}\left(N \bar{G}_{\bullet} \times M\right)_{h o r}\right)^{G}$. That is, an element of $c \in C^{p, q}$ can be written as

$$
c=\sum \alpha \otimes \theta_{\bullet}^{i_{1}} \cdots \theta_{\bullet}^{i_{q}} \nu_{i_{1}, \ldots, i_{q}}
$$

where $\alpha \in S^{p}\left(\mathfrak{g}^{*}\right)$ and $\nu_{i_{1}, \ldots, i_{q} \bullet} \in A^{*}(N \bar{G} \bullet \times M)_{h o r}$ by Corollary 4.62. Note that $C^{0,0}$ can naturally be identified with $A^{*}(N \bar{G} \bullet \times M)_{b a s}$ which we will occasionally refer to as a subcomplex

$$
A^{*}\left(N \bar{G}_{\bullet} \times M\right)_{b a s} \subset\left(S\left(\mathfrak{g}^{*}\right) \otimes A^{*}\left(N \bar{G}_{\bullet} \times M\right)\right)^{G}
$$

The following two results establish the existence of an explicit chain map that induces an isomorphism in cohomology

$$
H^{*}\left(\left(S\left(\mathfrak{g}^{*}\right) \otimes A^{*}\left(N \bar{G}_{\bullet} \times M\right)\right)^{G}\right) \cong H^{*}\left(A^{*}\left(N \bar{G}_{\bullet} \times M\right)_{b a s}\right)
$$

and then an explicit description of the chain map. The results follow the proof of Theorem 5.9 of [GS99] closely.

Proposition 4.64: There is a chain map

$$
\chi:\left(S\left(\mathfrak{g}^{*}\right) \otimes A^{*}\left(N \bar{G}_{\bullet} \times M\right)\right)^{G} \rightarrow\left(S\left(\mathfrak{g}^{*}\right) \otimes A^{*}(N \bar{G} \bullet \times M)\right)^{G}
$$

such that

$$
\operatorname{im}(\chi)=A^{*}\left(N \bar{G}_{\bullet} \times M\right)_{b a s} \subset\left(S\left(\mathfrak{g}^{*}\right) \otimes A^{*}\left(N \bar{G}_{\bullet} \times M\right)\right)^{G}
$$

and it is an isomorphism on cohomology.
Proof. Firstly let $\mathfrak{g}$ have basis $\left\{\xi_{1}, \ldots, \xi_{n}\right\}$ and correspondingly $S\left(\mathfrak{g}^{*}\right)$ has generators $\left\{\mu_{1}, \ldots, \mu_{n}\right\}$. Define an operator $\partial_{i}: S^{1}\left(\mathfrak{g}^{*}\right) \rightarrow S^{0}\left(\mathfrak{g}^{*}\right)$ by

$$
\partial_{i} \mu^{j}= \begin{cases}1 & \text { if } i=j \\ 0 & \text { if } i \neq j\end{cases}
$$

for every $i=1, \ldots, n$. Since $\partial_{i}$ is defined on the generators of $S\left(\mathfrak{g}^{*}\right)$, this operator can be extended as a map $\partial_{i}: S^{p}\left(\mathfrak{g}^{*}\right) \rightarrow S^{p-1}\left(\mathfrak{g}^{*}\right)$ for every $p \geq 0$. Moreover, it is clear that for $\alpha \in S^{p}\left(\mathfrak{g}^{*}\right)$,

$$
\left(\mu^{i} \partial_{i}\right) \alpha= \begin{cases}p \cdot \alpha & \text { if } p>0 \\ 0 & \text { if } p=0\end{cases}
$$

where Einstein summation convention is observed. Also, from Corollary 4.62, we know that any simplicial differential form $\omega \in A^{*}\left(N \bar{G}_{\bullet} \times M\right)$ can be written as a sum

$$
\omega_{\bullet}=\sum \theta_{\bullet}^{i_{1}} \ldots \theta_{\bullet}^{i_{q}} \nu_{i_{1}, \ldots, i_{q} \bullet} .
$$

One observes that for each summand $\beta=\theta_{\bullet}^{i_{1}} \ldots \theta_{\bullet}^{i_{q}} \nu_{i_{1}, \ldots, i_{q} \bullet}$ we have a similar relation

$$
\left(\theta_{\bullet}^{i}{ }_{\xi_{i}}\right) \beta= \begin{cases}q \cdot \beta & \text { if } q>0 \\ 0 & \text { if } q=0\end{cases}
$$

as before. The two operators $\left(\mu^{i} \partial_{i}\right)$ and $\left(\theta_{\bullet}^{i}{ }_{\bullet} \xi_{i}\right)$ can naturally be thought of as operators on the tensor product $\left(S\left(\mathfrak{g}^{*}\right) \otimes A^{*}\left(N \overline{G_{\bullet}} \times M\right)\right)^{G}$ and thus on $C^{p, q}$ (as described in Equation 4.63) one observes that

$$
\left(\mu^{i} \partial_{i}\right)+\left(\theta_{\bullet}^{i} \iota \xi_{i}\right)=(p+q) \cdot \mathrm{id}
$$

and is hence invertible for every $p, q$ such that $p+q>0$. We construct an operator $z$ : $\left(S\left(\mathfrak{g}^{*}\right) \otimes A^{*}\left(N \overline{G_{\bullet}} \times M\right)\right)^{G} \rightarrow\left(S\left(\mathfrak{g}^{*}\right) \otimes A^{*}\left(N \overline{G_{\bullet}} \times M\right)\right)^{G}$ by

$$
z \alpha:= \begin{cases}\alpha & \text { if } \alpha \in A^{*}\left(N \overline{G_{\bullet}} \times M\right)_{\text {bas }}  \tag{4.65}\\ 0 & \text { otherwise }\end{cases}
$$

for every $\alpha \in\left(S\left(\mathfrak{g}^{*}\right) \otimes A^{*}(N \bar{G} \bullet \times M)\right)^{G}$. One can restate this identity in the language of the decomposition $C^{p, q}$ by saying that the restriction of $z$ to $C^{p, q}$ is defined by

$$
z= \begin{cases}\text { id } & \text { if } p+q=0  \tag{4.66}\\ 0 & \text { otherwise }\end{cases}
$$

for every $p, q \geq 0$. We define $z$ so that we can define an operator $E: C^{p, q} \rightarrow C^{p, q}$

$$
E:=\left(\mu^{i} \partial_{i}\right)+\left(\theta_{\bullet}^{i} \iota_{\xi_{i}}\right)+z= \begin{cases}(p+q) \cdot \text { id } & \text { if } p+q>0  \tag{4.67}\\ \text { id } & \text { if } p+q=0\end{cases}
$$

that is clearly invertible on all of $\left(S\left(\mathfrak{g}^{*}\right) \otimes A^{*}(N \bar{G} \bullet \times M)\right)^{G}$. Alternatively, define an operator $R:=\left(d \theta_{\bullet}^{i}\right) \partial_{i}$. By direct calculation, we can show $E-R$ is invertible. That is, since

$$
E-R=\left(\mathrm{id}-R E^{-1}\right) E
$$

we can write

$$
\begin{equation*}
(E-R)^{-1}=E^{-1}\left(\mathrm{id}+R E^{-1}+\left(R E^{-1}\right)^{2}+\cdots\right) \tag{4.68}
\end{equation*}
$$

as long as the sum

$$
i d+R E^{-1}+\left(R E^{-1}\right)^{2}+\cdots
$$

terminates. This sum must terminate however, since $R E^{-1}$ lowers the degree of $S\left(\mathfrak{g}^{*}\right)$ by 1 and thus for $\alpha \in C^{p, q}$

$$
\left(R E^{-1}\right)^{p+1} \alpha=0 .
$$

Let $\chi=z(E-R)^{-1}$ and $Q=\left(-\theta_{\bullet}^{i} \partial_{i}\right)(E-R)^{-1}$. We will show, following the proof in [GS99, Theorem 5.9], that

$$
d_{G} Q+Q d_{G}=\mathrm{id}-\chi
$$

holds. I.e. that $Q$ is a chain homotopy from id to $\chi$ and hence $\chi$ is an isomorphism on cohomology. Thinking of $A^{*}\left(N \bar{G}_{\bullet} \times M\right)_{\text {bas }}$ as a subspace of $\left(S\left(\mathfrak{g}^{*}\right) \otimes A^{*}(N \bar{G} \bullet \times M)\right)^{G}$, clearly $\operatorname{im}(\chi)=A^{*}(N \bar{G} \bullet \times M)_{b a s}$ by the definition of $z$ in Equation 4.66. One checks by direct calculation that

$$
\begin{align*}
\left(d_{G}\left(-\theta_{\bullet}^{i} \partial_{i}\right)+\left(-\theta_{\bullet}^{i} \partial_{i}\right) d_{G}\right) \alpha & =\left(\mu^{i} \partial_{i}\right) \alpha+\left(\theta_{\bullet}^{i} \iota_{\xi_{i}}\right) \alpha-\left(d \theta_{\bullet}^{i} \partial_{i}\right) \alpha \\
& =(E-R-z) \alpha \tag{4.69}
\end{align*}
$$

for any $\alpha \in\left(S\left(\mathfrak{g}^{*}\right) \otimes A^{*}\left(N \bar{G}_{\bullet} \times M\right)\right)^{G}$. In particular, this means that

$$
\begin{equation*}
d_{G}(E-R)-(E-R) d_{G}=d_{G} z-z d_{G} . \tag{4.70}
\end{equation*}
$$

From above, the operator $(E-R)$ is invertible so conjugating both sides of Equation 4.70 by its inverse yields

$$
\begin{equation*}
d_{G}(E-R)^{-1}-(E-R)^{-1} d_{G}=(E-R)^{-1}\left(d_{G} z-z d_{G}\right)(E-R)^{-1} . \tag{4.71}
\end{equation*}
$$

Note that $\left.d_{G}\right|_{C^{0,0}}$ is the regular de Rham differential $d$ since $\mu^{i}{ }_{\xi_{i}}$ vanishes on $A^{*}(N \bar{G} \bullet \times M)_{\text {bas }}$ and hence we can consider the operator $d_{G} z-z d_{G}$ as a map onto the basic forms of $A^{*}(N \bar{G} \bullet \times M)$

$$
d_{G} z-z d_{G}: C^{p, q} \rightarrow C^{0,0} .
$$

Also, since $R$ vanishes on $A^{*}\left(N \bar{G}_{\bullet} \times M\right)_{b a s},\left.(E-R)\right|_{C^{0,0}}=\mathrm{id}$ and thus

$$
(E-R)^{-1}\left(d_{G} z-z d_{G}\right)=\operatorname{id}\left(d_{G} z-z d_{G}\right) .
$$

Thus one simplification we can make to Equation 4.71 is that

$$
\begin{equation*}
d_{G}(E-R)^{-1}-(E-R)^{-1} d_{G}=\left(d_{G} z-z d_{G}\right)(E-R)^{-1} . \tag{4.72}
\end{equation*}
$$

With these facts, we now expand the expression

$$
\begin{aligned}
d_{G} Q+Q d_{G}= & d_{G}\left(-\theta_{\bullet}^{i} \partial_{i}\right)(E-R)^{-1}+\left(-\theta_{\bullet}^{i} \partial_{i}\right)(E-R)^{-1} d_{G} \\
= & d_{G}\left(-\theta_{\bullet}^{i} \partial_{i}\right)(E-R)^{-1} \\
& +\left(-\theta_{\bullet}^{i} \partial_{i}\right)\left(\left(d_{G} z-z d_{G}\right)(E-R)^{-1}+d_{G}(E-R)^{-1}\right)
\end{aligned}
$$

from Equation 4.72. Since $\left(-\theta_{\bullet}^{i} \partial_{i}\right)$ lowers the degree of $S\left(\mathfrak{g}^{*}\right)$,

$$
\left(-\theta_{\bullet}^{i} \partial_{i}\right)\left(d_{G} z-z d_{G}\right)=0
$$

which yields the equation

$$
\begin{align*}
d_{G} Q+Q d_{G} & =d_{G}\left(-\theta_{\bullet}^{i} \partial_{i}\right)(E-R)^{-1}+\left(-\theta_{\bullet}^{i} \partial_{i}\right) d_{G}(E-R)^{-1} \\
& =\left(d_{G}\left(-\theta_{\bullet}^{i} \partial_{i}\right)+\left(-\theta_{\bullet}^{i} \partial_{i}\right) d_{G}\right)(E-R)^{-1} \\
& =(E-R-z)(E-R)^{-1} \\
& =\operatorname{id}-\chi \tag{4.73}
\end{align*}
$$

proving the assertion that $\chi$ is an isomorphism on cohomology.
The chain map $\chi$ is studied further and we adapt the proof of [GS99, Theorem 5.2.1] to our case.

Theorem 4.74: The map $\chi:\left(S\left(\mathfrak{g}^{*}\right) \otimes A^{*}\left(N \bar{G}_{\bullet} \times M\right)\right)^{G} \rightarrow\left(S\left(\mathfrak{g}^{*}\right) \otimes A^{*}\left(N \bar{G}_{\bullet} \times M\right)\right)^{G}$ is the map

$$
\chi\left(\alpha \otimes \omega_{\mathbf{\bullet}}\right)=1 \otimes w\left(\theta_{\bullet}\right)(\alpha) \wedge \operatorname{Hor}\left(\omega_{\bullet}\right) .
$$

Proof. Firstly, consider the series

$$
\chi=z E^{-1}\left(\mathrm{id}+R E^{-1}+\left(R E^{-1}\right)^{2}+\cdots\right)
$$

given by the definition of $\chi$ and Equation 4.68. The map $E$ does not change the degree of an element in $\left(S\left(\mathfrak{g}^{*}\right) \otimes A^{*}\left(N \bar{G}_{\bullet} \times M\right)\right)^{G}$ and $z$ projects onto $A^{*}\left(N \bar{G}_{\bullet} \times M\right)_{b a s}$ so it follows that

$$
z E^{-1}=z
$$

since $E$ is the identity on $A^{*}(N \bar{G} \bullet \times M)_{b a s}$. Moreover, by the definition of $R$,

$$
\begin{align*}
z R & =z\left(d \theta_{\bullet}^{i} \partial_{i}\right) \\
& =z\left(\mu_{\bullet}^{i}-\frac{1}{2} c_{j k}^{i} \theta_{\bullet}^{j} \theta_{\bullet}^{k}\right) \partial_{i} \\
& =z \mu_{\bullet}^{i} \partial_{i} \tag{4.75}
\end{align*}
$$

since $z=0$ on elements of $C^{p, q}$ with $q>0$. Define the operator $K=\mu_{\bullet}^{i} \partial_{i}$. From Equation 4.75 we have that $z R=z K$ and hence

$$
z R E^{-1}=z K E^{-1}
$$

Since $E$ does not decrease the index of $q$ on $C^{p, q}$, the operator $z\left(R E^{-1}\right)^{n}$ vanishes on $C^{p, q}$ with $q>0$ for any $n \geq 1$ and it follows that we can write

$$
z\left(R E^{-1}\right)^{n}=z\left(K E^{-1}\right)^{n}
$$

From the definition of $E$ in Equation 4.67, one can directly calculate that

$$
\begin{align*}
\left(K E^{-1}\right)^{n} \beta & =\frac{1}{p+q}\left(K E^{-1}\right)^{n-1} K(\beta) \\
& =\frac{1}{p+q} \cdot \frac{1}{p+q-1}\left(K E^{-1}\right)^{n-2} K^{2}(\beta) \\
& \vdots \\
& =\frac{(p+q-n)!}{(p+q)!} K^{n}(\beta) \tag{4.76}
\end{align*}
$$

where $\beta \in C^{p, q}$. But $K^{n}(\beta) \in C^{p-n, q}$ and so $z K^{n}(\beta)$ is only non-zero when $q=0$ and $p=n$. This fact combined with Equations 4.75 and 4.76 yield

$$
\chi=z\left(\mathrm{id}+K+\frac{1}{2!} K^{2}+\cdots\right)=z \exp (K)
$$

If $\beta \in C^{p, 0}$ then we may write $\beta=\alpha \otimes \omega_{\bullet}$ for some $\alpha \in S^{p}\left(\mathfrak{g}^{*}\right)$. So the problem reduces to evaluating $K^{p}\left(\alpha \otimes \omega_{\bullet}\right)$ for which we assert that

$$
K^{p}\left(\alpha \otimes \omega_{\bullet}\right)=p!\cdot 1 \otimes w\left(\theta_{\bullet}\right)(\alpha) \omega_{\bullet}
$$

Since $S^{p}\left(\mathfrak{g}^{*}\right)$ is generated by $\left\{\mu^{1}, \cdots, \mu^{n}\right\}$, we can write

$$
\alpha \otimes \omega_{\bullet}=\sum \mu^{i_{1}} \cdots \mu^{i_{p}} \otimes \omega_{\bullet}
$$

If $p=1$ then it is easy to see that

$$
K\left(\mu^{i_{1}} \otimes \omega\right)=1 \otimes w\left(\theta_{\bullet}\right)\left(\mu^{i}\right) \wedge \omega_{\bullet}
$$

and thus by the linearity of $K, K\left(\alpha \otimes \omega_{\bullet}\right)=1 \otimes w\left(\theta_{\bullet}\right)(\alpha) \wedge \omega_{\bullet}$. Assume that

$$
K^{p-1}\left(\alpha \otimes \omega_{\bullet}\right)=(p-1)!\cdot 1 \otimes w\left(\theta_{\bullet}\right)(\alpha) \wedge \omega_{\bullet}
$$

for every $\alpha \in S^{p-1}\left(\mathfrak{g}^{*}\right)$. Then clearly in the case where $\alpha=\sum \mu^{i_{1}} \cdots \mu^{i_{p}}$

$$
\begin{aligned}
K^{p}\left(\mu^{i_{1}} \cdots \mu^{i_{p}} \otimes \omega_{\bullet}\right) & =K^{p-1}\left(\sum_{k=1}^{p} \mu^{i_{1}} \cdots \mu^{\hat{i}_{k}} \cdots \mu^{i_{p}} \otimes w\left(\theta_{\bullet}\right)\left(\mu^{i_{k}}\right) \wedge \omega_{\bullet}\right) \\
& =\sum_{k=1}^{p}(p-1)!\cdot 1 \otimes w\left(\theta_{\bullet}\right)\left(\mu^{i_{1}} \cdots \hat{\mu}^{i_{k}} \cdots \mu^{i_{p}}\right) w\left(\theta_{\bullet}\right)\left(\mu^{i_{k}}\right) \wedge \omega_{\bullet} \\
& =p!\cdot 1 \otimes w\left(\theta_{\bullet}\right)\left(\mu^{i_{1}} \cdots \mu^{i_{p}}\right) \wedge \omega_{\bullet}
\end{aligned}
$$

and thus we have shown

$$
\frac{1}{p!} K^{p}\left(\alpha \otimes \omega_{\bullet}\right)= \begin{cases}1 \otimes w\left(\theta_{\bullet}\right)(\alpha) \wedge \omega_{\bullet} & \text { if } \alpha \in S^{p}\left(\mathfrak{g}^{*}\right) \\ 0 & \text { otherwise }\end{cases}
$$

via induction. Since $z$ vanishes on forms with any vertical component, only the horizontal component of $\omega_{\bullet}$ is preserved. As a result

$$
\chi\left(\alpha \otimes \omega_{\bullet}\right)=1 \otimes w\left(\theta_{\bullet}\right)(\alpha) \wedge \operatorname{Hor}\left(\omega_{\bullet}\right) .
$$

Corollary 4.77: The map $\bar{\chi}:\left(S\left(\mathfrak{g}^{*}\right) \otimes A^{*}\left(N \bar{G}_{\bullet} \times M\right)\right)^{G} \rightarrow A^{*}\left(N \bar{G}_{\bullet} \times M\right)_{\text {bas }}$ given by

$$
\bar{\chi}\left(\alpha \otimes \omega_{\bullet}\right)=w\left(\theta_{\bullet}\right)(\alpha) \wedge \operatorname{Hor}\left(\omega_{\bullet}\right)
$$

induces an isomorphism in cohomology. Moreover, the inclusion map

$$
i: A^{*}\left(N \overline{G_{\bullet}} \times M\right)_{b a s} \rightarrow\left(S\left(\mathfrak{g}^{*}\right) \otimes A^{*}\left(N \bar{G}_{\bullet} \times M\right)\right)^{G}
$$

also induces an isomorphism in cohomology and is the chain homotopy inverse to $\bar{\chi}$.
Proof. The fact that $\bar{\chi}:\left(S\left(\mathfrak{g}^{*}\right) \otimes A^{*}\left(N \bar{G}_{\bullet} \times M\right)\right)^{G} \rightarrow A^{*}\left(N \bar{G}_{\bullet} \times M\right)_{\text {bas }}$ is an isomorphism in cohomology is an immediate corollary of Theorem 4.74.

One notices that $i \circ \bar{\chi}=\bar{\chi}$ and so, looking back at Equation 4.73,

$$
d_{G} Q+Q d_{G}=\mathrm{id}-i \circ \chi
$$

One can consider $\bar{\chi} \circ i=\mathrm{id}$ on $A^{*}\left(N \bar{G}_{\bullet} \times M\right)_{b a s}$ and so clearly there is a respective chain homotopy between these two maps. Thus we have established that $i$ and $\bar{\chi}$ are chain homotopy inverses.

Theorem 4.78: Let $G$ be a compact Lie group and $M$ be a manifold with right $G$-action and let $\alpha \otimes \omega \in\left(S\left(\mathfrak{g}^{*}\right) \otimes \Omega^{*}(M)\right)^{G}$. There is a chain map

$$
\Phi:\left(S\left(\mathfrak{g}^{*}\right) \otimes \Omega^{*}(M)\right)^{G} \rightarrow A^{*}\left(N \bar{G}_{\bullet} \times M\right)_{b a s}
$$

given by

$$
\Phi(\alpha \otimes \omega)=w\left(\theta_{\bullet}\right)(\alpha) \wedge \operatorname{Hor}\left(\omega_{\bullet}\right)
$$

that induces an isomorphism on cohomology.
Proof. From Theorem 4.55 and Proposition 4.59 and Proposition 4.60 the map

$$
1 \otimes\left(E_{\Delta} \circ p_{M}^{*} \circ i\right):\left(S\left(\mathfrak{g}^{*}\right) \otimes \Omega^{*}(M)\right)^{G} \rightarrow\left(S\left(\mathfrak{g}^{*}\right) \otimes A^{*}(N \bar{G} \bullet \times M)\right)^{G}
$$

induces an isomorphism in cohomology. If we let

$$
\omega_{\bullet}=\left(E_{\Delta} \circ p_{M}^{*} \circ i\right)(\omega)
$$

then from Theorem 4.74 the map $\Phi:=\bar{\chi} \circ 1 \otimes\left(E_{\Delta} \circ p_{M}^{*} \circ i\right)$ which can be explicitly written as

$$
\Phi(\alpha \otimes \omega)=w\left(\theta_{\bullet}\right)(\alpha) \wedge \operatorname{Hor}\left(\omega_{\bullet}\right)
$$

is an isomorphism on cohomology.

This theorem derives the classical result of Cartan - that the Cartan model calculates the equivariant cohomology of a manifold $M$ acted upon by a compact Lie group $G$.

Corollary 4.79 (Cartan's Theorem): Let $G$ be a compact Lie group and $M$ be a manifold with right G-action. The Cartan model

$$
\left(S\left(\mathfrak{g}^{*}\right) \otimes \Omega^{*}(M)\right)^{G}
$$

computes the equivariant cohomology of $M$.
Proof. This follows as a result from Theorem 4.78, Theorem 4.14 and Corollary 3.62.

### 4.4.3 The Weil Model via Simplicial Differential Forms

One may also derive results about the relation between the ordinary Weil model and Dupont's simplicial model for equivariant cohomology.

Proposition 4.80: Let $G$ be a compact Lie group and $M$ be a manifold with right $G$-action. The chain map

$$
\psi:\left(W(\mathfrak{g}) \otimes A^{*}\left(N \bar{G}_{\bullet} \times M\right)\right)_{b a s} \rightarrow A^{*}\left(N \bar{G}_{\bullet} \times M\right)_{b a s}
$$

given by

$$
\psi\left(\alpha \otimes \omega_{\bullet}\right)=w\left(\theta_{\bullet}\right)(\alpha) \wedge \omega_{\bullet}
$$

induces an isomorphism on cohomology.
Proof. Consider the sequence of chain maps below.

$$
\left(W(\mathfrak{g}) \otimes A^{*}\left(N \bar{G}_{\bullet} \times M\right)\right)_{b a s} \xrightarrow{\exp (\zeta)}\left(S\left(\mathfrak{g}^{*}\right) \otimes A^{*}\left(N \bar{G}_{\bullet} \times M\right)\right)^{G} \underset{i}{\stackrel{\bar{\chi}}{\rightleftarrows}} A^{*}\left(N \bar{G}_{\bullet} \times M\right)_{b a s}
$$

The map $\exp (\zeta)$ is an isomorphism and hence induces an isomorphism in cohomology. That is

$$
\bar{\chi} \circ \exp (\zeta):\left(W(\mathfrak{g}) \otimes A^{*}\left(N \bar{G}_{\bullet} \times M\right)\right)_{b a s} \rightarrow A^{*}\left(N \bar{G}_{\bullet} \times M\right)_{b a s}
$$

is an isomorphism in cohomology. As well, we have the map

$$
\psi\left(\alpha \otimes \omega_{\bullet}\right)=w\left(\theta_{\bullet}\right)(\alpha) \wedge \omega_{\bullet}
$$

which satisfies $\bar{\chi} \circ \exp (\zeta) \circ \psi=\psi$. Recall from Corollary 4.77 that the inclusion

$$
i: A^{*}\left(N \bar{G}_{\bullet} \times M\right)_{b a s} \rightarrow\left(S\left(\mathfrak{g}^{*}\right) \otimes A^{*}\left(N \bar{G}_{\bullet} \times M\right)\right)^{G}
$$

is an isomorphism in cohomology and hence

$$
\exp (-\zeta) \circ i: A^{*}\left(N \bar{G}_{\bullet} \times M\right)_{b a s} \rightarrow\left(W(\mathfrak{g}) \otimes A^{*}(N \bar{G} \bullet \times M)\right)_{b a s}
$$

is an isomorphism in cohomology. But for any $\omega_{\bullet} \in A^{*}(N \bar{G} \bullet \times M)_{\text {bas }}$

$$
(\zeta \circ i) \omega_{\bullet}=\left(\theta^{i} \otimes \iota \xi_{i}\right)\left(1 \otimes \omega_{\bullet}\right)=0
$$

since $\omega_{\boldsymbol{0}}$ is basic. So the map

$$
\exp (-\zeta) \circ i: A^{*}(N \bar{G} \bullet \times M)_{b a s} \rightarrow\left(W(\mathfrak{g}) \otimes A^{*}\left(N \bar{G}_{\bullet} \times M\right)\right)_{b a s}
$$

is a similar inclusion

$$
(\exp (-\zeta) \circ i) \omega_{\bullet}=1 \otimes \omega_{\bullet}
$$

and also an isomorphism on cohomology. One notes that

$$
\psi \circ(\exp (-\zeta) \circ i)=\mathrm{id}
$$

and so $\psi$ induces an isomorphism on cohomology.
Lemma 4.81: Consider the map

$$
1 \otimes\left(E_{\Delta} \circ p_{M}^{*} \circ i\right):\left(S\left(\mathfrak{g}^{*}\right) \otimes \Omega^{*}(M)\right)^{G} \rightarrow\left(S\left(\mathfrak{g}^{*}\right) \otimes A^{*}(N \bar{G} \times M)\right)^{G}
$$

from Theorem 4.78. This map commutes with the Mathai-Quillen operator $\zeta$ from Equation 4.52.

Proof. This result naturally follows from Proposition 4.59 which establishes that the map $E_{\Delta} \circ$ $p_{M}^{*} \circ i$ is a $G^{*}$ morphism.

Theorem 4.82: Let $G$ be a compact Lie group and $M$ be a manifold with right $G$-action and let $\alpha \otimes \omega \in\left(W(\mathfrak{g}) \otimes \Omega^{*}(M)\right)_{\text {bas }}$. There is a chain map

$$
\Psi:\left(W(\mathfrak{g}) \otimes \Omega^{*}(M)\right)_{b a s} \rightarrow A^{*}(N \bar{G} \bullet \times M)_{b a s}
$$

given by

$$
\Psi(\alpha \otimes \omega)=w\left(\theta_{\bullet}\right)(\alpha) \wedge \omega_{\bullet}
$$

that induces an isomorphism on cohomology.
Proof. Firstly we note that since $1 \otimes\left(E_{\Delta} \circ p_{M}^{*} \circ i\right)$ commutes with $\zeta$, the diagram

$$
\begin{aligned}
& \left(W(\mathfrak{g}) \otimes \Omega^{*}(M)\right)_{b a s} \xrightarrow{\exp (\zeta)}\left(S\left(\mathfrak{g}^{*}\right) \otimes \Omega^{*}(M)\right)^{G} \\
& \begin{array}{c}
1 \otimes\left(E_{\Delta} \circ p_{M}^{*} \circ i\right) \mid \\
\left(W(\mathfrak{g}) \otimes A^{*}(N \bar{G} \times M)\right)_{b a s} \xrightarrow{\exp (\zeta)}\left(S\left(\mathfrak{g}^{*}\right) \otimes A^{*}(N \bar{G} \times M)\right)^{G}
\end{array}
\end{aligned}
$$

is commutative. Accordingly,

$$
1 \otimes\left(E_{\Delta} \circ p_{M}^{*} \circ i\right):\left(W(\mathfrak{g}) \otimes \Omega^{*}(M)\right)_{\text {bas }} \rightarrow W(\mathfrak{g}) \otimes A^{*}(N \bar{G} \times M)_{\text {bas }}
$$

is an isomorphism on cohomology from Proposition 4.59. Thus the composition

$$
\Psi:=\psi \circ 1 \otimes\left(E_{\Delta} \circ p_{M}^{*} \circ i\right):\left(W(\mathfrak{g}) \otimes \Omega^{*}(M)\right)_{b a s} \rightarrow A^{*}(N \bar{G} \times M)_{b a s}
$$

is an isomorphism in cohomology from Proposition 4.80.
Corollary 4.83: Let $G$ be a compact Lie group and $M$ be a manifold with right $G$-action. The Weil model

$$
\left(W(\mathfrak{g}) \otimes \Omega^{*}(M)\right)_{b a s}
$$

computes the equivariant cohomology of $M$.
Proof. This follows as a result from Theorem 4.82, Theorem 4.14 and Corollary 3.62.

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