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# Visual Question Answering: A Tutorial

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## Abstract

*The task of Visual Question Answering (VQA) receives increasing interest from researchers in both Computer Vision and Natural Language Processing. The field of computer vision has seen tremendous advances with the success of deep learning, in particular on low- and mid-level tasks, such as image segmentation or object recognition. These advances have fueled the confidence of researchers for tackling more complex tasks that combine vision with language and high-level reasoning. VQA is a prime example of this trend. This article presents the ongoing work in the field and the current approaches to VQA based on deep learning. VQA constitutes a test for deep visual understanding and a benchmark for general artificial intelligence. While the field of VQA has seen recent successes, it remains a largely unsolved task. We will discuss the current limitations and the challenges faced by researchers to perform unbiased evaluations. We will also outline promising directions of active and future research.*

## 1. Introduction

The task of Visual Question Answering (VQA) involves an image and a related text question, to which the machine must determine the correct answer. This task spans the fields of computer vision and natural language processing, since it requires both the comprehension of the question, and parsing the visual elements of the image. VQA is a practical setting to evaluate deep visual understanding, itself considered the over-arching goal of the field of computer vision. Deep visual understanding can be defined as the ability of algorithm to extract high-level information from images and to perform reasoning based on that information. In this regard, VQA is an alternative to other tasks proposed to evaluate this capability. Examples include the visual Turing

test [24], the task of image captioning [21, 74], and recent works on visual dialogs [18, 19].

A second parallel motivation for the study of VQA is its utility in its own right. A system capable of answering questions about images has direct practical applications, such as personal assistants, or in robotics as aids for the visually-impaired. Note however that current VQA datasets do not directly address this setting, because questions are typically collected in a non-goal-oriented setting. Realistic, motivated questions would likely require information not present in the image and involve rare words and concepts. In comparison, most questions in current datasets are purely visual (e.g. about counts or colors) and centered on common concepts. For example, in one of the most popular datasets [5], a mere 1,000 different answers can correctly answer more than 90% of questions.

The recent interest towards VQA [5, 46, 82] originates from the recent advances in computer vision on low- and mid-level tasks. This encouraged further research on higher-level tasks, and the combination of vision with other modalities, particularly language. Historically, one of the earliest integrations of computer vision with language was the *SHRDLU* system dating back to 1972 [79]. It allowed users to use language to instruct a computer to move objects in a simulated “blocks world”. Other attempts at creating conversational robotic agents [15, 48, 60] were also grounded in the visual world. However, these early works were often limited to specific domains and/or simple language. Deep learning has now been applied to virtually every problem imaginable in computer vision, and convolutional Neural Networks (CNNs) are approaching human performance at tasks such as image segmentation [40] or object recognition [20, 25]. The success of deep learning on perceptual tasks drove an increasing enthusiasm for high-level tasks. VQA particularly embodies this confidence in achieving high-level image understanding.

This article presents an overview of the field of VQA. We first examine the challenges of the task through examples from datasets, which were specifically devised for training

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Is this pizza vegetarian ?    What is the mustache made of ?    Does this person have 20/20 vision ?

Figure 1. The task of visual question answering (VQA) is a significant step towards general AI, and a departure from low- and mid-level tasks in classical computer vision. It requires relating visual concepts with elements of language, common-sense and general knowledge. Examples from a major dataset [5] are pictured.

and evaluating VQA systems. We then study the common approach to VQA, which uses a deep neural network trained with supervision on a large amount of example questions and answers. The vast majority of papers addressing VQA from the past few years present variations of this approach. We survey some popular variants, in particular attention mechanisms and memory-augmented networks, which are familiar principles to deep learning practitioners. We finally discuss the limitations of current methods, the challenges of unbiased evaluation, and a road-map of directions for current and future research.

## 2. Task definition and datasets

An instance of Visual Question Answering (VQA), consists in an image and a related question given in plain text (see examples in Figure 1). The task for the machine is to determine the correct answer, which is, in current datasets, typically a few words or a short phrase. Two practical variants are usually considered, an *open-ended* and a *multiple choice* setting [5, 93]. In the latter, a set of candidate answers are proposed. This makes the evaluation of a generated answer easier than in the open-ended setting, where the comparison between the machine’s output and a ground truth (*i.e.* human-provided) answer faces issues with synonyms and paraphrasing.

In comparison to classical tasks of computer vision such as object recognition or image segmentation, instances of VQA cover a wide range of complexity. Indeed, the question itself can take an arbitrary form, and so can the set of operations required to answer it. In this sense, VQA more closely reflects the challenges of general image understanding. VQA is also related to the task of *textual* question answering [10, 14, 89], in which the answer is to be found in a textual narrative (*i.e.* reading comprehension) or in large knowledge bases (*i.e.* information retrieval). Textual QA has been studied for a long time in the Natural Language Processing (NLP) community, and VQA is basically its extension to a visual input. The additional challenge of a visual input is significant because images are simply much

higher dimensional than text. Images capture the richness of the real world in a noisy manner, whereas natural language already represents a certain level of abstraction. For example, compare the phrase ‘a red hat’ with the multitude of its representations that one could picture, *e.g.* with many different styles and details that cannot be described in a short phrase.

While the processing of language is possible, to some extent, with discrete and rule-based approaches, such as syntactic parsers and regular expression matching, the complexity of images renders such engineered methods intractable. Modern computer vision is based on statistical learning, and recent works combining vision and language (including image captioning and VQA) similarly evolved from machine learning techniques. Finally, both language and vision are inherently compositional in their structure. This constitutes both a challenge and an opportunity when considering the generalization capabilities of learned models (see Section 5.5).

Let us mention the relation of VQA with the task of automatic image captioning [21, 74, 80], *i.e.* generating a textual description of a given image. It has also attracted significant interest in the past few years, and can be compared to VQA as they both combine vision and language. The two tasks are complementary as they evaluate different capabilities. Captioning requires mostly descriptive capabilities which involve almost purely visual information. VQA, in comparison, often requires reasoning with common sense and with other information not present in the given image. In this respect, VQA constitutes an AI-complete task [5] since it requires multimodal knowledge beyond specific domains. This reinforces the motivation for research on VQA, as it provides a proxy to evaluate progress towards general Artificial Intelligence (AI), with systems capable of advanced reasoning combined with deep image and language understanding.

## 2.1. Datasets for training and evaluating VQA

We now examine datasets that have been specifically compiled for research on VQA. These datasets contain, at a minimum, triples made each of an image, a question, and its correct answer. Some early datasets were generated semi-automatically (*e.g.* from image captions [46]) but modern datasets were created manually through crowd sourcing [5, 36]. The creation of these sets of questions with ground-truth answers is very time-consuming and today’s largest datasets of several 100,000s of instances [36] represent a major effort. Those datasets are designed for both evaluating and training VQA systems in a supervised setting, and the latter demands such large amounts of data. As will be discussed in Section 5, this very need for large amounts of data is a significant limit of current approaches.

For the purpose of standardized comparisons and benchmarking of different algorithms, datasets are split into pre-determined sets of instances for training, validation, and testing. Benchmarks typically do not provide the ground-truth answers of the test set. The evaluation is performed by an automatic online service that compares the provided answers (inferred by the algorithm to be evaluated) and the private ground truth [5]. This method typically restricts the number and frequency of submissions so as to prevent cheating or unintentional overfitting of the test set.

Existing datasets vary mainly along three dimensions: (i) their size, *i.e.* the number and variety concepts represented in the images and questions, (ii) the amount of required reasoning, *e.g.* whether the detection of a single object is sufficient or whether inference is required over multiple facts or concepts, and (iii) how much information beyond what is present in the input image is necessary to infer an answer, *e.g.* common sense or subject-specific information. Most datasets lean towards visual-level questions and require little external knowledge beyond common sense. These characteristics reflect the fact that current state-of-the-art methods still struggle with simple visual questions.

The first VQA dataset designed as benchmark was DAQUAR, for DATaset for QUEStion Answering on Real-world images [46]. The most popular modern datasets [5, 36, 93] use images sourced from MS COCO [41], a dataset initially devised for image recognition, which is itself composed of images from Flickr. Those images constitute a very diverse collection of photographs.

**VQA-real** The most widely used dataset is currently the one proposed by a team of researchers from Virginia Tech, and is commonly referred to simply as VQA [5]. It comprises two parts, one using natural images named VQA-real, and a second one with clipart images named VQA-abstract (discussed at the end of this section). VQA-real comprises 123,287 training and 81,434 test images, respectively, sourced from COCO [41]. Human annotators were encouraged to provide interesting and diverse questions, and

short concise answers (typically 2-3 words). The dataset allows evaluation both in an open-ended and in a multiple-choice setting, the latter providing 17 additional (incorrect) candidate answers for each question. Overall, the dataset contains 614,163 questions. According to an analysis performed by polling annotators, most subjects (at least 6 out of 10) estimated that some common sense was required for 18% of the questions, and adult-level knowledge was necessary for only 5.5% of the questions. These figures show that purely visual information is likely sufficient to answer most questions.

A recent, updated version of this dataset, known as VQA v2.0 includes two images with each question that lead to different answers [26]. This aims at addressing issues of dataset biases (see Section 5.1).

**Visual Genome and Visual7W** The Visual Genome QA dataset [36] is currently the largest one designed for VQA, with 1.7 million question/answer pairs. It is built with images from the Visual Genome project [36], which includes structured annotations of scene contents in the form of scene graphs. Those scene graphs describe the visual elements of each image with their attributes and the relationships between them. Human subjects provided questions that must start with one of the “seven Ws”, *i.e.* who, what, where, when, why, how, and which. The diversity of answers in the Visual Genome is larger than in VQA-real [5]. The 1,000 most frequent answers in the dataset correspond only to the correct answers of 64% of all questions. In VQA-real, the corresponding top 1,000 answers cover more than 90% of questions. The Visual7w [93] dataset is a subset of the Visual Genome that allows evaluation in a multiple-choice setting, as each question is provided with four plausible but incorrect candidate answers.

**Zero-shot VQA** A special version of the Visual7W dataset was proposed in [71]. The authors redefined the training and test splits such that every test instance includes one or several words that were not present in any training example. For example, a test question “*How many zebras are in the image ?*” might arise even though the word *zebra* was never used in the training set. The evaluation of an algorithm with this dataset emphasizes its capabilities for generalization beyond training examples and for using sources of information other than VQA-specific datasets. Another similar study appeared in [55].

**Clipart images** Datasets for VQA have also been proposed with synthetic clipart images (referred to as “abstract scenes” in [5]). These images were created manually with cartoon representations of characters and objects from a predefined set. The motivation is to enable research on VQA in a controlled setting, where the computer vision part of the problem is eased by the restricted set of visual elements. Such data allows focusing on the high-level semantics of the scenes rather than on visual recognition. For



this purpose, the images are provided with structured descriptions, in the form of XML files that list the objects present in the scene with their visual properties (*e.g.* position, scale, *etc.*). VQA methods can use these descriptions to completely bypass the visual parsing of the images.

Using synthetic images gives great control over the elements actually depicted, and this allowed the creation a dataset of balanced binary questions [91]. That dataset contains only binary (yes/no) questions and each question appears twice in the dataset, with two different images that give rise to opposite answers. This removes conditional biases that are common in other datasets, for example a predominance of *yes* answers to questions of the form “*Is there ... in the image ?*”. Those biases otherwise allow to blindly guess correct answers, which hinders a meaningful evaluation of VQA systems.

Despite undeniable advantages, VQA datasets of clipart images have seen little use [5, 70, 91] compared to their counterparts of real images.

**Video-based QA** In addition to the studies on image QA mentioned above, there has been a few works on VQA with videos. Zhu *et al.* [92] assembled a dataset of over 100,000 videos and 400,000 questions, using existing collections of videos from different domains, from cooking scenarios to movies and web videos. Tapaswi *et al.* [68] proposed a setting named MovieQA, where questions have to be answered using multiple sources of information including he full-length movies, but also subtitles, scripts and plot summaries. Zeng *et al.* [90] proposed to generate questions from video descriptions.

**Evaluation** VQA systems are evaluated by inferring the answers on the test split of a given dataset. Recent datasets [93] recommend the multiple-choice setting, since there is only one correct answer among the multiple choices. The evaluation is thus straightforward, as one can simply measure the mean accuracy over test questions. In an open-ended setting, several answers could be equally valid, because of synonyms and paraphrasing. This makes a fair evaluation non-trivial. The usual workaround is to restrict answers, at the time of the creation of the datasets, to short phrases, typically 1 to 3 words. This restriction limits ambiguities by forcing questions and answers to be more specific, and allows evaluation by exact string-matching. Most datasets partition the test questions into subsets depending on the type of answer (*e.g.* yes/no, number, *etc.*) such that performance can be reported on each subset (see Table 1).

### 3. Deep neural networks for VQA

The common approach to VQA is to train a deep neural network with supervision which maps the given image and question to a relative scoring of candidate answers. The

main idea is to learn a *joint embedding* of the visual and textual inputs. First, the image and the question are processed independently to obtain separate vector representations (see Figure 3). Those features are then mapped with learned functions to a joint space, then combined and fed to an output stage. We examine each of those elements below. Section 4 will then look at advanced techniques that build onto this model.

**Image encoding** On the computer vision side, the input image  $x^I$  is processed with a deep convolutional neural network (CNN) to extract image features described as a vector  $y^I$ . This large fixed-size vector encodes the contents of the image. This CNN is typically a standard network architecture that has been pretrained to perform image recognition [37]. The motivation for a pretrained network is to take advantage of the vast amounts of training data available for image recognition, relative to the amounts of data annotated for VQA. The pretrained network is used as a generic feature extractor, by discarding the final classification layers, and using the features produced within the CNN prior to this classification [56]. In comparison to classical hand-crafted image features such as SIFT [42] or HOG [16], CNN features provide higher-level representations of the contents of the image, and are naturally produced as a fixed-size vector. The size of this vector is typically in the order of 1024 or 2048.

**Question encoding** On the language side, the input question is also processed to obtain a fixed-size representation of its contents. Initially, the  $i$ th word of the question is represented by an index  $x_i^Q$  in the input vocabulary. Each word is then turned into a vector. This uses a mapping implemented as a lookup table  $W[\cdot]$  that associates the index of any word of the input vocabulary to a learned vector<sup>1</sup>. The vectors of all words  $W[x_1^Q], W[x_2^Q], \dots, W[x_N^Q]$  is then collapsed into a single vector. A simple option for this purpose is to make a Bag-of-Words (BoW), which correspond to simply averaging the word vectors, *i.e.*  $y^Q = \frac{1}{N} \sum_i^W [x_i^Q]$ . Another popular option is to feed the word vectors into a Recurrent Neural Network (RNN) such as a Long Short-Term Memory (LSTM). An RNN processes words sequentially and can capture the sequential relationships between them. In comparison, a BoW does not account for word order, and, for example, would produce a same representation for “*this man eats a hot dog*” and “*a hot man eats this dog*”.

**Combination of image and question features** The feature vectors  $y^I$  and  $y^Q$  represent respectively the image and the questions. They are each passed through a learned function before being combined. The intuition here is to map the features to a joint space, in which distances between

<sup>1</sup>An alternative implementation initially represents each word with a one-hot vector (a vector of all zeros, except for a one at the location of the word index in the vocabulary) which is then multiplied with a dense weight matrix that contains the embeddings of all words.




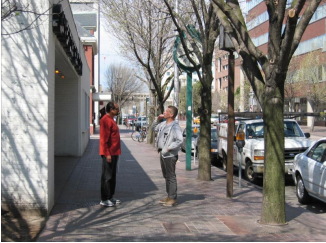












VQA-real [5]				
	<p>Q: What shape is the bench seat ? A: curved</p>	<p>Q: What color is the stripe on the train ? A: white</p>	<p>Q: Where are the magazines in this picture ? A: on stool</p>	
Visual Genome [36]				
	<p>Q: What color is the clock ? A: green</p>	<p>Q: What is the woman doing ? A: sitting</p>	<p>Q: How is the ground ? A: dry</p>	
VQA-abstract [5]				
	<p>Q: Who looks happier ? A: man</p>	<p>Q: Where are the flowers ? A: around tree</p>	<p>Q: How many pillows ? A: 2</p>	
Zero-shot VQA [71]				
	<p>Q: What color are the <i>barricades</i> ? A: Pink</p>	<p>Q: What are they using to <i>draw</i> ? A: <i>markers</i></p>	<p>Q: Who is playing ? A: <i>rafael nadal</i></p>	
VQA v2.0 [26]				
	<p>Q: Who is wearing glasses? A: man</p>	<p>A: woman</p>	<p>A: yes</p>	<p>Q: Is the TV on? A: no</p>

Figure 2. Examples from the test splits of different VQA datasets. For the *Zero-shot VQA* dataset, the highlighted words are unknown words, *i.e.* not present in training examples.

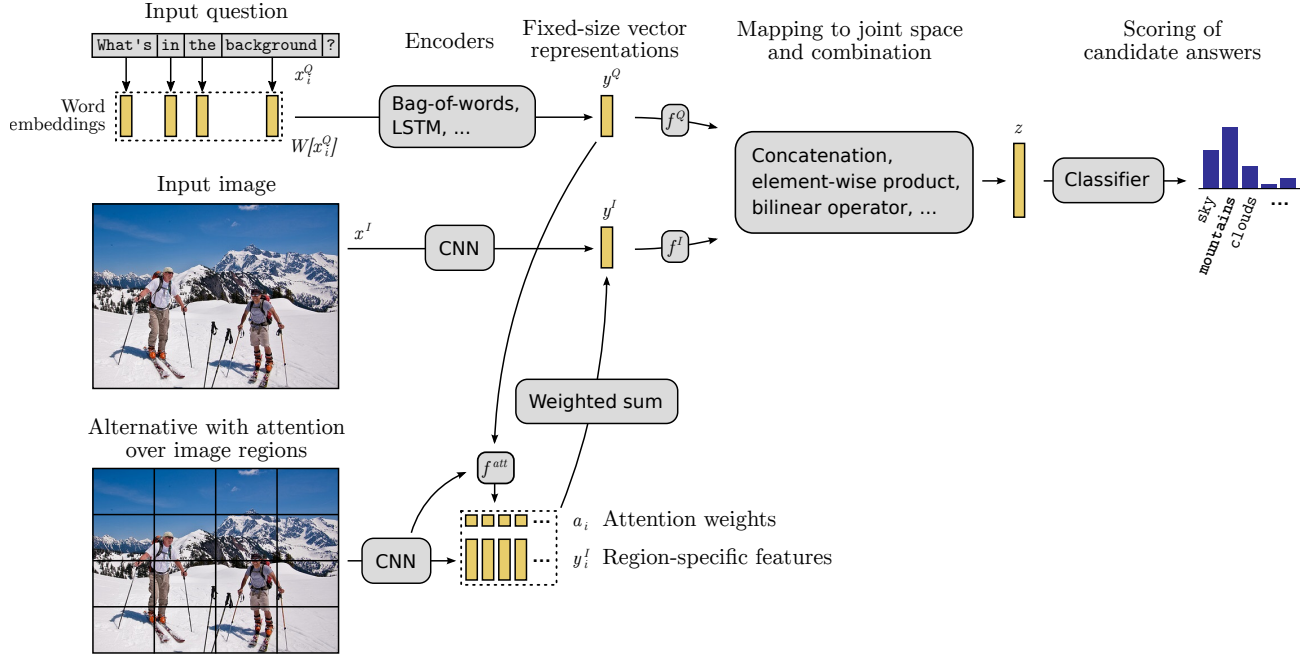


Figure 3. The common approach to VQA is to train a deep neural network for classification over a large set of candidate answers (Section 3). The input question and image are encoded into fixed-size feature vectors (orange bars), using respectively word embeddings and a Convolutional Neural Network (CNN). The resulting representations are mapped into a joint space, then combined and passed on to the classifier. It assigns scores to a large set of candidate answers. The top-ranking candidate is returned as the final answer. An attention mechanism (Section 4.1) can improve this model and allows the model to focus on relevant parts of the image. In that case, the CNN extracts region-specific image features and aggregates them using scalar weights (orange squares).

both modalities become comparable. The learned functions  $f^I(\cdot)$  and  $f^Q(\cdot)$  are typically implemented as additional layers of the neural network, e.g.  $f(y) = \text{ReLU}(Wy + b)$ , where  $W$  and  $b$  are learned weights and biases, and ReLU a rectified linear unit that serves as a non-linearity. The mapped features are then combined before being fed to the output stage. A simple option for this combination is to simply concatenate them as  $z = [f^I(y^I); f^Q(y^Q)]$ . Alternatively, it is popular to include multiplicative interactions within the neural network to increase its capacity and use  $z = f^I(y^I) \cdot f^Q(y^Q)$ , where  $\cdot$  is the Hadamard (element-wise) product.

**Output** The output stage of a VQA system can be seen either as a generation or as a classification task. The generation of a free-form answer has the advantage of being able to compose complex sentences. In practice however, such a model is difficult to learn [23, 47, 81]. Current datasets are limited to short answers, and a practical alternative is to rather learn a classifier over candidate answers [23, 45, 47, 58]. For this purpose, a large set of candidate answers is predetermined from the most common ones in the training set (typically in the order of 2,000). This inevitably leaves out some infrequent words, but such a set is typically sufficient to answer correctly more than 90% of test questions [5]. This is a non-limiting issue since this fig-

ure is well above the accuracy of current systems. The combined features  $z$  are passed to a classifier over those candidate answers (a linear layer followed by a softmax [22] or sigmoid transformation [31]). The classifier assigns score to each candidate answer, and the top-ranked one is returned as the final output. In a multiple-choice setting, only the scores assigned to proposed choices are considered. For training the model, the classifier is followed by a cross-entropy loss, and the whole network is trained end-to-end by backpropagation to minimize this loss over the set of training examples.

**Variations** A vast array of variations on the method presented above have been proposed in the literature. Here are some examples.

- Encoding the question and the image with a single recurrent neural network (an LSTM), by passing the image features together with each word embedding [23] or only once prior to the question words [47, 58].
- Encoding the question with a bidirectional RNN, i.e. two LSTMs that process the words in forward and backward order, respectively. This aims at capturing the language structure with more uniform importance on the beginning and the end of the question [58].
- Adding additional multiplicative interactions within the network and between the features of the image and of



the question. For example in [52], the authors present their “DPPnet” model as a way of dynamically adapting the computations applied on the image features based on the question (one branch of the network computes weights that are then multiplied with the inputs in another branch). Such interpretations are typical of deep learning models, but have little concrete support. Performance benefits usually stem simply from the additional capacity of the network.

- Alternative schemes for combining image and question representations, such as element-wise sums and products [34], bilinear operations [31] such as the Multimodal Compact Bilinear pooling (MCB) [22], *etc.*
- Gradual increases in performance of the state-of-the-art is also explained by increasingly better pretrained CNNs to provide image features, and by the application of general enhancements for neural network architectures, such highway networks and residual networks [34], dropout, batch normalization, *etc.*

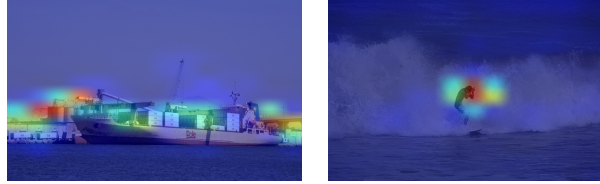
## 4. Advanced techniques

In this section, we review popular improvements to the general approach described so far.

### 4.1. Attention mechanisms

One of the most effective improvements to the joint embedding model is to use visual attention. Humans have the ability to quickly understand visual representations by attending to regions of the image instead of processing the entire scene at once [59]. Mimicking human attention in deep neural networks has been applied with success to machine translation [8], reading comprehension [64], textual question answering [85], object recognition [65] and image captioning [87], and is also used in most modern VQA models (*e.g.* in [44, 88]).

The main idea behind attention mechanisms is to allow the model to focus on certain regions of the image. The technique involves (1) using region-specific image features and (2) including multiplicative interactions within the neural network. The basic VQA model described above uses a CNN to extract a *global* feature vector  $y^I$  that describes the whole image. This can contain irrelevant or noisy information. Instead, we now extract *local* features  $\{y_i^I\}_i$  for different regions  $i = 1 \dots M$  of the image. Those features are obtained from an earlier layer in the pretrained CNN, prior to the last spatial pooling. The network computes a scalar attention weight  $a_i$  for each region using both the region and the question features, *i.e.*  $a_i = f^{\text{att}}(y_i^I, y^Q)$ . The function  $f^{\text{att}}(\cdot)$  is learned and implemented as additional layers of the network. The attention weights can be interpreted as the relevance of a given region, and the image is finally represented by a weighted sum of the region features, *i.e.*  $y^I = \sum_i a_i y_i^I$ .



Q: What is in the water ?

A: boat

Q: Who is surfing ?

A: man

Figure 4. Attention weights are often visualized as spatial maps overlaid on the input image (warmer colors correspond to higher weights). They are interpreted as the importance given by the model to different regions of the image (examples from [75]).

The attention weights computed for a given question/image can be visualized in the form of “attention maps” for purposes of introspection into the VQA model. Each  $a_i$  corresponds to a specific region of the input image, and those values are overlaid onto the image canvas (see Figure 4). They are interpreted as the importance given by the model to each image region.

The use of an attention mechanism has shown to be very beneficial and is now common practice. Variations on this principle have been proposed. For example, [88] and [86] use multiple rounds of visual attention to allow focusing on several regions. In [86], a two-step process performs a word-guided attention, then a question-guided one. In [66], the authors define image regions with object proposals and then select the regions most to the question and to given answer choices. In [44], the authors propose a “hierarchical co-attention” (HieCoAtt) that performs a question-guided attention on the image and an image-guided attention on the question.

The overall idea of attention in neural networks was initially motivated by analogy to the human visual system. Even though the model is capable of modeling a behaviour similar to human attention, that only constitutes an interpretation. In a neural network trained end-to-end, nothing enforces the attention mechanism to actually reflect human-like behaviour. In a recent study [17], Das *et al.* compared the attention used by human subjects presented with VQA problems, and VQA models with attention [44, 88]. Their conclusion was a systematically low correlation.

### 4.2. Pretraining language representations

As described in Section 3, the first step for encoding the question is to map words to vector representations called word embeddings. Each word of the input vocabulary (*i.e.* any word appearing in the training set) is associated with its own embedding, and those embeddings are normally learned alongside the other parameters of the network via backpropagation. Two potential issues can arise however. First, word occurrences in any dataset typically follow a long-tailed distribution, meaning that a majority of words



occur infrequently. It is thus difficult to learn stable and meaningful embeddings for those rare words. Second, the long-tail property, at its extreme, means that words commonly appear in test questions that were not seen in any training example. Embeddings for those words cannot be learned from those examples, and they are typically associated with a special vector (of zeros or of a special “unknown” token), and their meaning is practically discarded from the questions.

A solution to these issues is to pre-train word embeddings on a larger auxiliary dataset. This practice is known in the field of natural language processing and has shown benefit in many tasks besides VQA. Popular methods for pretraining word embeddings include *GloVe* [54] (Global Vectors for Word Representation) and *word2vec* [49], which we outline below. The general principle is to use a large, auxiliary training set of unannotated text, such as news articles and Wikipedia pages. Those methods require no specific annotations. That data can thus be much larger than the training set used for VQA and involve a much larger vocabulary.

The idea in the skip-gram model of *word2vec* is to train a model which, using the representation (*i.e.* embedding) of a given word, is predictive of the context, *i.e.* the neighbouring words in which it frequently appears [50]. As a consequence, words that are interchangeable or appear in similar contexts become associated with similar embeddings. Distances between embeddings thus naturally capture semantic relatedness between the words they represent.

More precisely, the skip-gram model seeks to maximize the ability to predict, from each word embedding, the occurrences of other words in a small surrounding window. The objective function to be maximized is

$$J = \frac{1}{N} \sum_i \frac{1}{|\Omega(i)|} \sum_{j \in \Omega(i)} \log p(x_j | x_i) \quad (1)$$

where  $i$  indexes the  $N$  ordered words in the training corpus,  $x_i$  is the index in the vocabulary of word  $i$ ,  $\Omega(i)$  is a context window of fixed size around word  $i$  in the corpus [50]. The conditional probability  $\log p(x_j | x_i)$  is modeled as a compatibility measure between embeddings such as a dot product followed by a sigmoid, *i.e.*

$$p(x_j | x_i) = 1 / (1 + e^{-W[x_i] W[x_j]}) \quad (2)$$

where  $W[\cdot]$  is a lookup table containing the embeddings of all words in the vocabulary, reusing the notation of Section 3. After the training, the context-prediction part of the model is discarded, and the embeddings associated with the words are retained (*i.e.* the table  $W[\cdot]$ ) and used as word embeddings in the downstream application such as VQA. The embeddings can be used as “frozen weights”, *i.e.* static representations associated with the words, or they can serve as

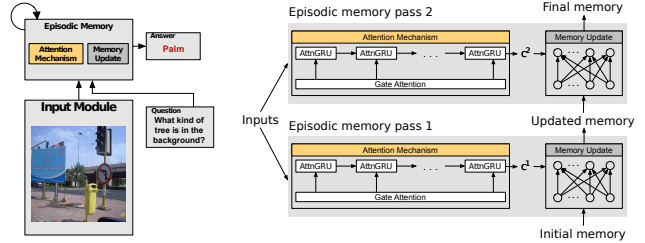


Figure 5. Dynamic Memory Networks for VQA (figure adapted from [84]). Overview (left) and details of the episodic memory module with two passes (right).

initial values to be subsequently fine-tuned, *i.e.* optimized with a lower learning rate relative to the other network parameters.

Using pretrained embeddings helps the generalization capabilities of a VQA model. Since semantically similar words are mapped to close points in the word embedding space, the processing by the subsequent layers of the network can more easily (1) interpolate across concepts and (2) generalize to words absent from training questions but for which embeddings were pretrained.

### 4.3. Memory-augmented neural networks

The design of deep neural networks including an internal memory is an active research area [13, 53, 67, 78]. Memory-augmented networks have shown success on tasks such as textual question answering [29], reading comprehension [38], and VQA [84]. The general idea of memory-augmented networks is to maintain an internal representation of the input data, on which multiple read and write operations can be applied. The composition of multiple operations can potentially execute complex chains of inference on the data. A “controller” part of the network is responsible for controlling those operations. The mechanism is comparable to multiple rounds of an attention mechanism, in that it also enables the modeling of interactions between specific sections of the input data.

The variant proposed in [38, 84], named Dynamic Memory Networks (DMNs), was successfully applied to VQA. It is built around four modules (see Figure 5). The *input module* transforms the input data into a set of discrete vectors called “facts”. A *question module* computes a vector representation of the question, using a gated recurrent unit (GRU, a variant of LSTM). An *episodic memory module* retrieves the facts required to answer the question. A key element is to allow the episodic memory module to perform multiple passes over the facts to allow transitive reasoning. An attention mechanism selects the relevant facts and an update mechanism iteratively generates new memory representations from the current state and the retrieved facts. The initial state is set as the representation produced by the question module. Finally, the *answer module* uses the fi-

nal state of the memory and the question to predict the final output, using a classic classifier over candidate answers.

#### 4.4. Runtime retrieval of additional information

Interfacing a VQA method with external sources of information allows one to separate the reasoning from the representation of prior knowledge in a scalable manner. A limitation of the basic joint embedding approach is to attempt capturing all the information of training examples within the parameters of a neural network. This cannot scale arbitrarily however. On the one hand, any network has a finite capacity, and on the other hand, training examples also provide finite information. Several works explored the idea of connecting a VQA system with external sources of information that can be virtually infinite (*e.g.* web searches) or extensible without needing to retrain the VQA model (*e.g.* structured knowledge bases).

In [76, 83], the authors train a model to interface with a knowledge base (KB). Such KBs like DBpedia [7] and Freebase [12] are databases compiled with facts ranging from common sense to encyclopedic knowledge. Such non-visual information can be helpful for VQA. For example, the question “*How many mammals appear in this image ?*” requires understanding the word *mammal* and which animals belong to this category. The VQA system of [76, 83] is trained to map the input question/image to queries to be executed on KBs. The queries retrieve information relevant to the concepts involved in the question and/or image, which is fed as an additional input to the output stage of the system. The overall principle has shown limited benefits on existing VQA datasets, since most questions do not require such specific, non-visual information. The idea remains a promising direction for developing scalable VQA systems.

In [71], the authors propose to retrieve visual information from web searches in the form of exemplar images of question words. Rare and novel words, for example the name of a uncommon animal or of an up-and-coming celebrity, are not likely to appear or be even known during training. The retrieval of images from the web allows the method to expand its domain of applicability as needed. The implementation of [71] simply retrieves the top five images from Google for every word of the question, from which CNN features are extracted, and fed alongside the input question/image to the VQA system. This mechanism, however crude, showed advantage with questions involving unknown words (*i.e.* “zero-shot VQA”, see Section 5.2) while leaving substantial room for future developments.

### 5. Directions of current and future research

Most modern methods for VQA have been evaluated on the dataset of Antol. *et al.* [5], which has served as the *de facto* standard benchmark. State-of-the-art methods have consistently improved performance on this dataset over the

past few years, from an accuracy of about 58% to over 70% today (see Tables 1 and 2 for a selection of results). These improvements have been incremental and have now seemed to plateau. In the following, we examine how current evaluations can mask some inherent issues of today’s approaches, and examine promising directions to bring future breakthroughs.

#### 5.1. Issues of dataset biases

Several studies have recently pointed out a fundamental issue with VQA datasets [26, 31, 91]. The text questions alone often provide strong cues that can be sufficient to answer them correctly, with no regards to the contents of the input image. These cues can be obvious. For example, questions starting with “*Do you see a ...*” can be correctly answered with *yes* almost nine times out of ten [26]. These cues can also stem from an imbalance among possible answers. For example, questions starting with “*How many ...*” often have a correct answer of 1 or 2 but rarely 17. This issue can also be more subtle and manifest in the form of conditional biases. For example, we could imagine that questions starting with “*What is the color ...*” can often be answered correctly with *gray* if it also contains the word *car* and *red* if it contains the word *flower*. Biases conditioned on image contents are also likely and yet more subtle. Biases are inherent to the real world, and it is desirable for a VQA model to capture and exploit them to some extent. However, today’s methods have shown to overly rely on dataset biases and essentially reduce to rote-learning of training questions. This is counter-productive to the objective of evaluating visual understanding. It has been indeed shown that a blinded VQA model (*i.e.* not being shown the input image, and only guessing from the question) still achieves an accuracy of 56% versus 65% in the non-blinded case [31].

The issue of dataset biases has been recognized. Attempts at addressing it include balanced datasets. Zhang *et al.* [91] first proposed a dataset of clipart images where each binary question is accompanied by two different images that elicit *yes* and *no* answers, respectively. Goyal *et al.* applied the idea to real images, associating two images with each question that lead to different answers (see example in Figure 2). An appropriate performance metric in this case is to measure accuracy on pairs of scenes. Blind models in this case would obtain an accuracy of 0%<sup>2</sup>. The use of balanced datasets encourages VQA models, to a larger extent, to utilize visual information instead of relying on language cues and dataset biases. It is expected that future evaluations of algorithms on those datasets will be more representative of actual progress on visual understanding.

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<sup>2</sup>Random guessing on balanced binary questions can still achieve 25% of accuracy.

Method	Yes/no	VQA-real Open-ended			Multiple choice
		Numbers	Other	All	All
Baseline: deeper LSTM Q norm. I [43]	80.6	36.5	43.7	58.2	63.1
Neural modules network (NMN) [4]	81.2	37.7	44.0	58.7	-
Stacked attention networks (SAN) [88]	-	-	-	58.9	-
Dynamic memory networks (DMN+) [84]	-	-	-	60.4	-
DualNet [61]	81.9	37.8	49.7	61.7	66.7
Hierarchical co-attention (HieCoAtt) [44]	-	-	-	62.1	66.1
VQA-Machine [75]	81.4	38.2	53.2	63.3	67.8
MLB [35]	84.0	37.9	54.8	65.1	68.9
MCB ensemble 7 models [22]	83.2	39.5	58.0	<b>66.5</b>	<b>70.1</b>

Table 1. Selection of results on the *VQA-real* dataset (*test-std* split) in both the open-ended and multiple-choice settings. Performance has incrementally improved over the past few years.

Method	Yes/no	VQA v2 Open-ended		
		Numbers	Other	All
Baseline: deeper LSTM Q norm. I [43]	73.46	35.18	41.83	54.22
MCB [22]	78.82	38.28	53.36	62.27
UPMC-LIP6 [9]	82.07	41.06	57.12	65.71
Athena [1]	82.50	44.19	59.97	67.59
LV-NUS[1]	81.89	46.29	58.30	66.77
HDU-USYD-UNCC [1]	68.09	84.50	45.39	59.01
Tips and Tricks VQA [69, 2]	86.60	48.64	61.15	<b>70.34</b>

Table 2. Selection of results on the newer *VQA v2* dataset (*test-std* split; open-ended questions). Baseline methods score lower on this harder dataset, but the state-of-art now reaches more than 70% of accuracy on open-ended questions.

## 5.2. Issues with unknown and novel words

A VQA method to be used in a real-world setting, *e.g.* in robotics or as personal AI assistants, must be applicable to open, unrestricted domains. The current paradigm of training VQA systems with supervision, *i.e.* with datasets of questions and their ground truth answers, can only cover a limited set of objects and concepts. Although VQA datasets have grown in size, no finite set of exemplars will ever cover the diversity of the world that an ideal VQA system should be prepared for. A secondary issue with the current approach is the incentive for published methods to perform well on benchmark datasets. These benchmarks do not encourage addressing rare words and concepts, but rather focus on the concepts most frequent in the dataset. Current methods are therefore designed to best learn – and often overfit – dataset biases.

Recent works have argued for addressing a setting named “zero-shot VQA” [55, 71], where questions (or the proposed multiple-choice answers) specifically involve words that have not been seen in any training question. For example, a question “*How many zebras are in the image ?*” may arise, even though no zebra was involved in the training set. This setting requires strong generalization capabilities. For example, a related training question “*How many giraffes are in the image ?*” should be taken as an opportunity to learn to count, although not giraffes specifically. In parallel of works on VQA, the learning of high-level reasoning is addressed in the more abstract setting of program induction (see *e.g.* [57]). We expect that VQA will ultimately require similar principled approaches, such as differentiable com-

puting [27, 51], rather than brute-force learning from limited sets of examples.

## 5.3. External knowledge

The setting of “zero-shot VQA” mentioned above exposes the need for VQA systems to apply to concepts not present in training question/answers. This motivates the use of other kinds of data for training, and for retrieving additional information as needed at test time. This requires the system not only to capture actual information from training examples, but to learn to retrieve and use novel information, *i.e.* learn to learn. That capability of meta-learning receives increased attention [11, 62, 73]. In the context of VQA, [71] showed the benefit of retrieving, on-the-fly, exemplar images of unknown words from an online search engine. In [76, 77], the authors showed benefit from retrieving additional information from a structured knowledge base. The extension of these ideas is a promising research direction.

## 5.4. Modular approaches

Most current VQA models use a monolithic neural network and end-to-end supervision to learn the representations of data, the reasoning process, and to capture background knowledge from training examples. Alternatively, modular approaches have been explored [75, 81] with the goal of explicitly factoring the overall process of VQA into distinct subtasks. The principle of modularity allows one to decouple subtasks to some extent, and to use intermediate supervision and leverage several types of training data, as opposed to only “end-to-end” question/answer pairs. The

use of pretrained word embeddings (Section 4.2) is a very successful example of this general principle. Word embeddings are pretrained to capture language-based semantic similarities, and, in a similar spirit, other representations could be pretrained from auxiliary data to capture visual similarities [39] and other kinds of background information [72].

Modular systems for VQA also allow decoupling, to some extent the visual perception from the high-level reasoning. For example, Wang *et al.* [75] proposed a VQA model on top of a collection of computer vision algorithms that detect visual elements such as objects, persons, and relations between them. Thereby, the VQA model only has to reason over this explicit high-level representation of the contents of the image.

### 5.5. Compositional models

The compositional nature of images and language lends itself to learning similarly-compositional models [6]. The approach aims at addressing the challenge of generalization, *i.e.* applying the learned model to novel compositions of words and visual elements. Compositional models were proposed by Hendricks *et al.* on the task of image captioning [28]. Andreas *et al.* [4, 3, 30] were the first to propose a compositional architecture for VQA, named Neural Module Networks (NMNs). In their approach, the input question is processed to determine the set of operations required to answer the question. A deep neural network is assembled with trained modules, each corresponding one of those operations. A custom network is thus tailored specifically to each question, and finally applied on the image to infer the answer.

A dataset of synthetic images named CLEVR [32] was specifically designed to evaluate generalization to novel combinations in VQA. It contains photorealistic images of shapes of various colors and materials. The dataset also contains annotations describing the kind of reasoning that each question requires (*i.e.* as functional “programs”). The dataset spurred a series of works on compositional models [30, 33]. The extra annotations facilitate the training of compositional models by serving as an intermediate supervision signal. This supervision correspond to an arrangement of modules or operations to be executed for each question. All of the above works demonstrated unique capabilities on synthetic datasets. However, it is yet unclear how to best apply them to real images, and how to train them only using end-to-end supervision, *i.e.* only knowing the final answer.

An alternative approach that addresses compositionality is the Relational Networks [63]. The idea is to consider the input as a set of objects, such as the locations in a CNN feature map, and to learn a common predictor that is applied to pairwise combinations of those objects. The predictor ba-

sically learns the relations between parts of the input. This proved effective on the CLEVR dataset without the need for the intermediate supervision mentioned above.

## 6. Conclusions

This article presented a review of the state-of-the-art on visual question answering. We reviewed popular approaches based on deep learning, which treat the task as a classification problem over a set of candidate answers. We described the common joint embedding model, and additional improvements that build up on this concept, such as attention mechanisms. Despite shortcomings of current practices for both training and evaluating VQA systems, we identified a number of promising research that could potentially bring future breakthroughs for both VQA and for the general objective of visual scene understanding.



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