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Dear Haldane,

Your problem is a very good example of the general use of maximum likelihood as explained in Section 57.1 of my book.

If you are satisfied in respect of visibility etc., that the data ought to be combined, you proceed to write down the expectation and observed frequencies in each set of experiments:

(α) Backcrossed females

Expectation	$\frac{1}{2}n_1 \{ 1 - \rho, \rho, \rho, 1 - \rho \}$
Observed	a_1, b_1, c_1, d_1

(β) Backcrossed males

Expectation	$\frac{1}{2}n_2 \{ 1 - q, q, q, 1 - q \}$
Observed	a_2, b_2, c_2, d_2

(γ) F_2 Coupling

Expectation	$\frac{1}{4}n_3 \{ 2 + (1 - \rho)(1 - q), 1 - (1 - \rho)(1 - q), 1 - (1 - \rho)(1 - q), (1 - \rho)(1 - q) \}$
Observed	a_3, b_3, c_3, d_3

(δ) F_2 Repulsion

Expectation	$\frac{1}{4}n_4 \{ 2 + \rho q, 1 - \rho q, 1 - \rho q, \rho q \}$
Observed	a_4, b_4, c_4, d_4

Thence the logarithm of the likelihood is

$$\begin{aligned} & (a_1 + d_1) \log(1-\phi) + (b_1 + c_1) \log \phi + (a_2 + d_2) \log(1-q) + (b_2 + c_2) \log q \\ & + a_3 \log \{2 + (1-\phi)(1-q)\} + (b_3 + c_3) \log \{1 - (1-\phi)(1-q)\} + d_3 \log(1-\phi)(1-q) \\ & + a_4 \log(2 + \phi q) + (b_4 + c_4) \log(1+\phi q) + d_4 \log \phi q \end{aligned}$$

and the two equations for ϕ and q are found by differentiation,

$$\frac{\partial L}{\partial \phi} = -\frac{a_1 + d_1 + d_3}{1-\phi} + \frac{b_1 + c_1 + d_4}{\phi} - \frac{a_3(1-q)}{2 + (1-\phi)(1-q)} + \frac{(b_3 + c_3)(1-q)}{1 - (1-\phi)(1-q)} + \frac{a_4 q}{2 + \phi q} - \frac{(b_4 + c_4)q}{1 - \phi q} = 0$$

and

$$\frac{\partial L}{\partial q} = -\frac{a_2 + d_2 + d_3}{1-q} + \frac{b_2 + c_2 + d_4}{q} - \frac{a_3(1-\phi)}{2 + (1-\phi)(1-q)} + \frac{(b_3 + c_3)(1-\phi)}{1 - (1-\phi)(1-q)} + \frac{a_4 \phi}{2 + \phi q} - \frac{(b_4 + c_4)\phi}{1 - \phi q} = 0$$

in which you ^{will} notice that all weighting is taken care of automatically by means of the observed frequencies.

Solution proceeds numerically, using probably the values from (α) and (β) as first approximations.

To systematise the process, and also to estimate the precision of the solution, it will be useful to calculate

$$-\frac{\partial^2 L}{\partial \phi^2}, -\frac{\partial^2 L}{\partial \phi \partial q}, -\frac{\partial^2 L}{\partial q^2}$$

for the trial values of ϕ and q . There is no need to trouble about algebraic simplification.

If ϕ_o , q_o are the trial values, then the corrections $\delta\phi_o$, δq_o are given by

$$\delta\phi_o \left(-\frac{\partial^2 L}{\partial \phi_o^2} \right) + \delta q_o \left(-\frac{\partial^2 L}{\partial \phi_o \partial q_o} \right) = \frac{\partial L}{\partial \phi_o}$$

$$\delta_{\beta_0} \left(-\frac{\partial^2 L}{\partial \beta_0 \partial q_0} \right) + \delta_{q_0} \left(-\frac{\partial^2 L}{\partial q_0^2} \right) = \frac{\partial L}{\partial q_0}$$

giving a new solution

$$\beta_0 = \beta_0 + \delta_{\beta_0}, \quad q_0 = q_0 + \delta_{q_0}$$

which will I think be efficient, though capable of further improvement in the same way. If a, b, c stand for the second differential coefficients of L , with changed sign, then $\frac{c}{a}$ gives the sampling variance of β for given observed q , while the total sampling variance of β is $\frac{c}{ac - b^2}$, and the sampling covariance of β and q is $b/(ac - b^2)$. Consequently, the sampling variance of $\beta - q$ is

$$\frac{a+c-2b}{ac-b^2}$$

and you will probably want this. A point which might be worth while following through in the algebra is the amount of information respecting $\beta - q$, i.e. $(ac - b^2)/(a+c-2b)$ to be expected from samples of n_1, n_2, n_3 , and n_4 , for this would show how much each type of experiment contributed to the total amount of information available.

Do you believe the Berlin file? The fallacies of Edin's work on Stockholm are fairly easy to see, but I have not looked at the Berlin stuff.

Yours sincerely,

R. A. Fisher