

1938 June 6.

Dear Fisher,

As this thing follows rather closely on your work I feel inclined to submit it for the *Annals*. I think it is mostly just a tidying up of loose ends, but there are a few minor practical points in it, e.g. on p.13. On p.4 I think that I am really flogging a dead horse, but people still won't let it be buried. Bartlett and E.S. Pearson wrote to me lately accusing me of claiming knowledge inaccessible to them, and I am rather tired of it.

I think that the kind of argument on p.10 would be useful inverted when direct distributions are wanted. E.g. take a set of measures; we have

$$P(dx_1, \dots, dx_n | \mu, \sigma, k) = (2\pi\sigma^2)^{-\frac{1}{2}n} \exp\left[-\frac{n}{2\sigma^2} \left\{ (\bar{x} - \bar{\mu})^2 + s^2 \right\}\right] dx_1, \dots, dx_n \quad (1)$$

which on integration will lead to a definite distribution for the probability of \bar{x} and s given μ and σ ; and since the total probability of x and s must be 1 it must be of the form

$$\frac{P(dx_1, \dots, dx_n | \mu, \sigma, k)}{P(dx_1, \dots, dx_n | \mu, \sigma, k)} = \frac{1}{\sigma^2} f\left(\frac{\bar{x} - \bar{\mu}}{\sigma}, \frac{s}{\sigma}\right) d\bar{x} ds \quad (2)$$

But with

$$P(dx d\sigma | h) \propto dx d\sigma / \sigma, \quad (3)$$

(1) gives

$$P(dx d\sigma | h) \propto \sigma^{-(n+1)} \exp\left[-\frac{n}{2\sigma^2} \left\{ \dots \right\}\right] dx d\sigma \quad (4)$$

the other factor being independent of x and σ ; hence

$$P(dx d\sigma | h) \propto \phi(n) s^{n-1} \sigma^{-(n+1)} dx d\sigma \quad (5)$$

But (2) gives

$$P(dx d\sigma | \bar{\mu}, s, k) \propto f\left(\frac{\bar{x} - \bar{\mu}}{\sigma}, \frac{s}{\sigma}\right) \frac{dx d\sigma}{\sigma^2} \quad (6)$$

$$= \lambda(n) \frac{1}{s} \int \left[\frac{n-n}{\sigma}, \frac{s}{\sigma} \right] \frac{d\lambda ds}{\sigma^2} \quad (7)$$

Comparing (5) & (7) { since (4) shows that \bar{x} & s are sufficient statistics }

$$s^{n-2} \sigma^{-n+2} \exp \left[-\frac{n}{2\sigma^2} \{ (x-\bar{x})^2 + s^2 \} \right] = \phi(x) \psi \left(\frac{n-\bar{x}}{\sigma}, \frac{s}{\sigma} \right) \quad (8)$$

$$\& P(d\bar{x} ds | n, \sigma, \lambda) = \lambda(n) \frac{s^{n-2}}{\sigma^n} \exp \left[-\frac{n}{2\sigma^2} \{ (n-\bar{x})^2 + s^2 \} \right] d\bar{x} ds. \quad (9)$$

Thus the form is got while the multiple integrations are short-circuited. (3) of course really cancels, but ~~it is the only one~~ ^{a higher index would} ~~that works~~ _{note (4) diverges at $\sigma = \infty$} for $n = 2$, and for $n = 1$ there is no problem.

One W. O. Storer here got the z distribution as a posterior probability last term, as the probability distribution of \bar{x} ^{deviation} the standard ~~error~~ of a new set of observations, a previous set being the data ; it is exactly your form. The same applies to the prediction of a set of means. The kind of argument I used for 'Student' suggested to me that this should be another case where a direct distribution should go over with no alteration at all, and it does.

By the way do you approve of my expression 'standard variation ?' I prefer to restrict 'deviation' to deviations ^a of observed quantities from the mean ; otherwise qualifications are needed to show which we are talking about. I don't like 'standard error' - the word error makes Dingle see red - because in the gravity problem and your plot yields the error of measurement is a very small part of the whole variation that is treated as random. Equally I don't like either 'true value' or 'population parameter' but cannot see anything really satisfactory. How about 'estiland' ?

Yours sincerely,

Harold Jefferys.