

Application of a Helmholtz resonator excited by grazing flow for manipulation of a turbulent boundary layer

Farzin Ghanadi

School of Mechanical Engineering The University of Adelaide South Australia, 5005 Australia

A thesis submitted in fulfilment of the requirements for the degree of Ph.D. in Mechanical Engineering on the 22nd September 2014

Abstract

In most industrial applications involving flow the Reynolds number is typically sufficiently high such that the boundary layer is turbulent. Flow instabilities within the turbulent boundary layer can result in an excessive drag penalty which is considered to be the main parameter affecting the aerodynamic efficiency in numerous applications including aircraft and pipelines. The aim of this research is manipulation of the turbulent boundary layer through the oscillatory flow created by a flow-excited Helmholtz resonator for the purpose of minimising the flow instabilities. Attention has been given here to a cylindrical Helmholtz resonator as a possible alternative flow control device. The energy required to activate the Helmholtz resonator comes from the grazing flow and it can be fitted to existing airframes with minimal manufacturing requirements. Hence it can potentially be an ideal solution for a wall-based flow control device. This research provides an insight into the behaviour of the flow in the vicinity of the resonator and assesses the capability of a flow-excited Helmholtz resonator for reduction of disturbances within the boundary layer.

The excitation of flow in the vicinity of the Helmholtz resonator is associated with both the external pressure fluctuations within the turbulent boundary layer and the acoustic response of the resonator cavity. A model of the relationship between the pressure inside the cavity and the boundary layer was developed based on a momentum balance equation and combination of the vortex sheet with discrete vortex models. A parametric study of the resonator showed that when the orifice length is increased the pressure fluctuations within the resonator are reduced, potentially due to the larger skin friction inside the orifice. To understand the boundary layer features over a flow-excited Helmholtz resonator a Large Eddy Simulation (LES) of the three dimensional flow over a wide range of flow velocities was also conducted. It was demonstrated that when the boundary layer thickness equals the orifice length and is twice the orifice diameter, the flow suction within the orifice is greater than the flow injection area which results in a reduction in the turbulence intensity of up to 10%. Detailed investigation of the characteristics of the turbulent boundary layer downstream of the resonator has also been accomplished through an extensive experimental study in a subsonic wind tunnel with a low turbulence intensity level of 0.5%, for free stream velocities between 15 and 30m/s. Similar to the results of the numerical modelling, the experimental results showed that a resonator with an orifice length equal to the boundary layer thickness modifies near-wall structures such that the intensity of sweep is reduced by up to 5% and its duration by up to 8%. It was also demonstrated that when the orifice diameter approximately equals the thickness of the inner layer, $y^+ \approx 400$, the velocity fluctuations normal to the grazing flow can penetrate the boundary layer, which in turn causes the large eddies to transfer their energy to the smaller eddies within the logarithmic region, resulting in attenuation of turbulence production.

The results of this study provide an improved understanding for the further development of flow-excited Helmholtz resonators as a flow control device, an area that warrants further investigation in the future.

Contents

Abstract		i
Declaration	n	vi
Acknowled	lgments	vii
Nomenclat	ture	viii
Chapter 1.	Introduction	1
1.1 Bac	ckground	1
1.2 Air	ms and objectives	5
1.3 The	esis outline	6
1.4 Put	blications arising from this thesis	9
1.5 For	rmat	
Referen	nces	10
Chapter 2.	Literature Review	13
2.1 Flo	ow-excited Helmholtz resonator	13
2.1	1.1 Behaviour of the grazing flow over a Helmholtz resonator	17
2.1	1.2 Frequency and amplitude of the instabilities within the shear layer	25
2.1	1.3 Pressure fluctuation within the cavity of a flow-excited resonator	27
2.1	1.4 Effects of characteristics of the Helmholtz resonator on flow behavio	ur 32
2.2 Tu	rbulent boundary layer	
2.3 Tu	rbulent boundary layer control	40
2.3	3.1 Riblets	

2.3.2 Blowing and suction of the turbulent boundary layer	43
2.3.3 Travelling waves	46
2.3.4 Wall oscillation	
2.3.4 Other techniques	
2.4 Conclusion of literature & research objectives	51
References	53
Chapter 3. Pressure Field within the Flow-excited Helmholtz Resonator	63
Paper 1: Analysis of the pressure fluctuations induced by grazing flow over a H resonator	Ielmholtz 65
Chapter 4. Flow Behaviour on a Helmholtz Resonator Excited by Grazing Flow	88
Paper 2: Understanding of the flow behaviour on a Helmholtz resonator ex grazing flow	xcited by 90
Paper 3: Numerical simulation of grazing flow over a self-excited H resonator	Helmholtz
Chapter 5. Interaction of a Flow-excited Helmholtz Resonator with a	Grazing
Chapter 5. Interaction of a Flow-excited Helmholtz Resonator with a Turbulent Boundary Layer	Grazing 109
Chapter 5. Interaction of a Flow-excited Helmholtz Resonator with a Turbulent Boundary Layer Paper 4: Interaction of a flow-excited Helmholtz resonator with a grazing boundary layer.	Grazing 109 turbulent 111
 Chapter 5. Interaction of a Flow-excited Helmholtz Resonator with a Turbulent Boundary Layer Paper 4: Interaction of a flow-excited Helmholtz resonator with a grazing boundary layer. Paper 5: Analysis of the turbulent boundary layer in the vicinity of a set cylindrical Helmholtz resonator	Grazing 109 turbulent 111 lf-excited 124
 Chapter 5. Interaction of a Flow-excited Helmholtz Resonator with a Turbulent Boundary Layer Paper 4: Interaction of a flow-excited Helmholtz resonator with a grazing boundary layer. Paper 5: Analysis of the turbulent boundary layer in the vicinity of a ser cylindrical Helmholtz resonator . Chapter 6. Control of the Turbulent Boundary Layer by a Self-excited Helmholtz 	Grazing 109 turbulent 111 lf-excited 124 [elmholtz
Chapter 5. Interaction of a Flow-excited Helmholtz Resonator with a Turbulent Boundary Layer Paper 4: Interaction of a flow-excited Helmholtz resonator with a grazing boundary layer. Paper 5: Analysis of the turbulent boundary layer in the vicinity of a set cylindrical Helmholtz resonator Chapter 6. Control of the Turbulent Boundary Layer by a Self-excited Helmholtz Resonator	Grazing 109 turbulent 111 lf-excited 124 [elmholtz 156
 Chapter 5. Interaction of a Flow-excited Helmholtz Resonator with a Turbulent Boundary Layer Paper 4: Interaction of a flow-excited Helmholtz resonator with a grazing boundary layer. Paper 5: Analysis of the turbulent boundary layer in the vicinity of a set cylindrical Helmholtz resonator	Grazing 109 turbulent 111 lf-excited 124 lelmholtz 156 onator.158
 Chapter 5. Interaction of a Flow-excited Helmholtz Resonator with a Turbulent Boundary Layer Paper 4: Interaction of a flow-excited Helmholtz resonator with a grazing boundary layer. Paper 5: Analysis of the turbulent boundary layer in the vicinity of a ser cylindrical Helmholtz resonator Chapter 6. Control of the Turbulent Boundary Layer by a Self-excited Helmholtz resonator Paper 6: Control of the turbulent boundary layer by a self-exited Helmholtz resonator Chapter 7. Conclusions and Future Work 	Grazing 109 turbulent 111 lf-excited 124 (elmholtz 156 mator.158 188
 Chapter 5. Interaction of a Flow-excited Helmholtz Resonator with a Turbulent Boundary Layer Paper 4: Interaction of a flow-excited Helmholtz resonator with a grazing boundary layer. Paper 5: Analysis of the turbulent boundary layer in the vicinity of a set cylindrical Helmholtz resonator Chapter 6. Control of the Turbulent Boundary Layer by a Self-excited Helmholtz resonator Paper 6: Control of the turbulent boundary layer by a self-excited Helmholtz reso Chapter 7. Conclusions and Future Work 7.1 Instantaneous pressure field inside the resonator. 	Grazing 109 turbulent 111 lf-excited 124 lelmholtz 156 onator.158 188 188
 Chapter 5. Interaction of a Flow-excited Helmholtz Resonator with a Turbulent Boundary Layer Paper 4: Interaction of a flow-excited Helmholtz resonator with a grazing boundary layer. Paper 5: Analysis of the turbulent boundary layer in the vicinity of a set cylindrical Helmholtz resonator Chapter 6. Control of the Turbulent Boundary Layer by a Self-excited Helmholtz resonator Paper 6: Control of the turbulent boundary layer by a self-excited Helmholtz reso Chapter 7. Conclusions and Future Work 7.1 Instantaneous pressure field inside the resonator. 7.2 Velocity fluctuations within the shear layer. 	Grazing 109 turbulent 111 lf-excited 124 (elmholtz 156 onator.158 188 188
 Chapter 5. Interaction of a Flow-excited Helmholtz Resonator with a Turbulent Boundary Layer Paper 4: Interaction of a flow-excited Helmholtz resonator with a grazing boundary layer. Paper 5: Analysis of the turbulent boundary layer in the vicinity of a se cylindrical Helmholtz resonator Chapter 6. Control of the Turbulent Boundary Layer by a Self-excited Helmholtz resonator Paper 6: Control of the turbulent boundary layer by a self-excited Helmholtz reso Chapter 7. Conclusions and Future Work 7.1 Instantaneous pressure field inside the resonator. 7.2 Velocity fluctuations within the shear layer. 7.3 Manipulation of the turbulent boundary layer. 	Grazing 109 turbulent 111 lf-excited 124 lelmholtz 156 onator.158 188 188 189 190

7.4.1 Effects of the flow conditions on the resonator performance	192
7.4.2 Shape and arrangement effects of the resonator on the grazing flow	193
7.4.3 Detailed flow measurements	194
References	195

Declaration

I certify that this work contains no material which has been accepted for the award of any other degree or diploma in my name, in any university or other tertiary institution and, to the best of my knowledge and belief, contains no material previously published or written by another person, except where due reference has been made in the text. In addition, I certify that no part of this work will, in the future, be used in a submission in my name, for any other degree or diploma in any university or other tertiary institution without the prior approval of the University of Adelaide and where applicable, any partner institution responsible for the joint-award of this degree.

I give consent to this copy of my thesis when deposited in the University Library, being made available for loan and photocopying, subject to the provisions of the Copyright Act 1968.

The author acknowledges that copyright of published works contained within this thesis resides with the copyright holder(s) of those works.

I also give permission for the digital version of my thesis to be made available on the web, via the University's digital research repository, the Library Search and also through web search engines, unless permission has been granted by the University to restrict access for a period of time.

Acknowledgment

I would firstly like to acknowledge the support of my principal supervisor Dr Arjomandi for his endless support and guidance during the course of this study; I continue to learn a lot from him. I would also like to thank the co-supervisors of the project, A/Prof Ben Cazzolato and A/Prof Anthony Zander who have shared their knowledge and expertise. I thank you all sincerely.

I would also like to thank all of my friends, (of which there are many), who have supported me throughout my research endeavours.

I would like to extend my thanks to the technicians of the Mechanical and Electrical workshops in the School of Mechanical Engineering at the University of Adelaide who have assisted in the fabrication of the designed models as well as the provision of the required equipment. You have all been a source of knowledge, fun and friendliness, and to you all I express my thanks.

Finally I save the biggest thanks to my parents Nayereh Beheshti and Mohammadreza Ghanadi and to my brother Mehdi Ghanadi whose love and support led me to this point. This journey has been as much hard work for you as it has been for me and through your support we have made it. Words cannot express my thanks and appreciation.

Nomenclature

A	cross-section area of the riblets groove (m ²)
С	speed of sound (m/s)
C_q	suction coefficient: $\frac{V_w}{U_{rec}}$
d	orifice diameter (m)
D	cavity diameter (m)
f	frequency (Hz)
f_b	bursting frequency (Hz)
F_c	Coriolis force (N)
F _{ext}	force exerted on the fluid inside the orifice (N)
f_n	natural frequency of the resonator (Hz)
f_r	resonance frequency of the resonator (Hz)
h	groove depth (m)
i	resonator mode number, imaginary number $\sqrt{-1}$
K	spring constant (N/m)
k	wavenumber (rad/m)
l	length of the orifice (mm)
L	cavity depth (mm)
l_e	effective length of the orifice (mm)
m	mass of fluid (kg)
Ма	Mach number

n	compliance of the resonator
P _{ext}	excitation pressure (Pa)
Pres	resonator pressure fluctuations (Pa)
P_t	acoustic power (W)
q_o	spatially averaged flow rate induced by flow over the resonator orifice (m^3/s)
q_r	spatially averaged acoustic volume flux through the resonator orifice (m^3/s)
R	damping constant
S	cross-section area of the orifice (m ²)
S	groove spacing (m)
St	Strouhal number
t	time (s)
T _{osc}	period of wall oscillation (s)
U, U_{∞}	mean free stream velocity (m/s)
и	streamwise flow velocity (m/s)
<i>u</i> _a	acoustic particle velocity (m/s)
u _c	convection velocity of the vortices (m/s)
u_{cs}	propagation speed of streaks (m/s)
$u_{ au}$	friction velocity (m/s)
Т	time period (s)
v_t	local velocity (m/s)
ν	cross-stream component of velocity (m/s)
V _c	cavity volume (m ³)
V_{w}	suction velocity (m/s)
x	indicates the x-direction (streamwise) (m)
у	indicates the y-direction (wall-normal direction) (m)
Ζ	indicates the z-direction (spanwise direction) (m)

Ζ	spanwise spacing of streaks (m)
Z _c	total input impedance of the resonator $(N.s/m^3)$
Z_M	acoustic impedance (N.s/m ³)

Symbols

σ	standard deviation
Г	circulation (m^2/s)
ζ	damping ratio
ω	angular frequency (rad/s)
ω _r	angular resonance frequency (rad/s)
Ω	vorticity (1/s)
ρ	density of air (kg/m ³)
arphi	phase lag between the vortical flow and acoustic volume flow (rad)
λ	acoustic wavelength (m)
υ	kinematic viscosity (m ² /s)
δ	boundary layer thickness (mm)
θ	momentum thickness (mm)

Superscripts

- \overrightarrow{O} denotes a vector
- $\widehat{()}$ denotes Fourier transform of ()
- + denotes time scale $(\frac{v}{u_{\tau}^2})$ or length scale $(\frac{v}{u_{\tau}})$